

Machine Learning for Integer Programming

Elias B. Khalil

ekhalil.com

Postdoc

**POLYTECHNIQUE
MONTREAL**

UNIVERSITÉ
D'INGÉNIERIE



UNIVERSITY OF
TORONTO

Assistant Professor of
Industrial Engineering

starting July 2020

In Memoriam: Shabbir Ahmed

- Anderson-Interface Chair and professor in Georgia Tech's H. Milton Stewart School of Industrial and Systems Engineering (ISyE)
- Giant of Stochastic Optimization and Integer Optimization



Learning to Run Heuristics in Tree Search

Elias B. Khalil¹, Bistra Dilkina^{*1}, George L. Nemhauser², Shabbir Ahmed², Yufen Shao³

Learning to Solve Large-Scale Security-Constrained Unit Commitment Problems

Álison S. Xavier¹, Feng Qiu¹, and Shabbir Ahmed²

Humans learn to **design algorithms**.

Humans learn to **design algorithms**.

Can **algorithms** “learn” to
design algorithms?

Humans learn to **design algorithms**.

Machine Learning

Can **algorithms** “learn” to
design algorithms?

Humans learn to **design algorithms**.

Can **algorithms** “learn” to
design algorithms?

The diagram features a central question: "Can algorithms 'learn' to design algorithms?". The word "algorithms" is repeated twice, with the second instance highlighted in yellow. A white arrow points from the first "algorithms" to the text "Machine Learning" above it. A yellow arrow points from the second "algorithms" to the text "Discrete Optimization" below it.

Machine Learning

Discrete Optimization

Data Center Resource Management

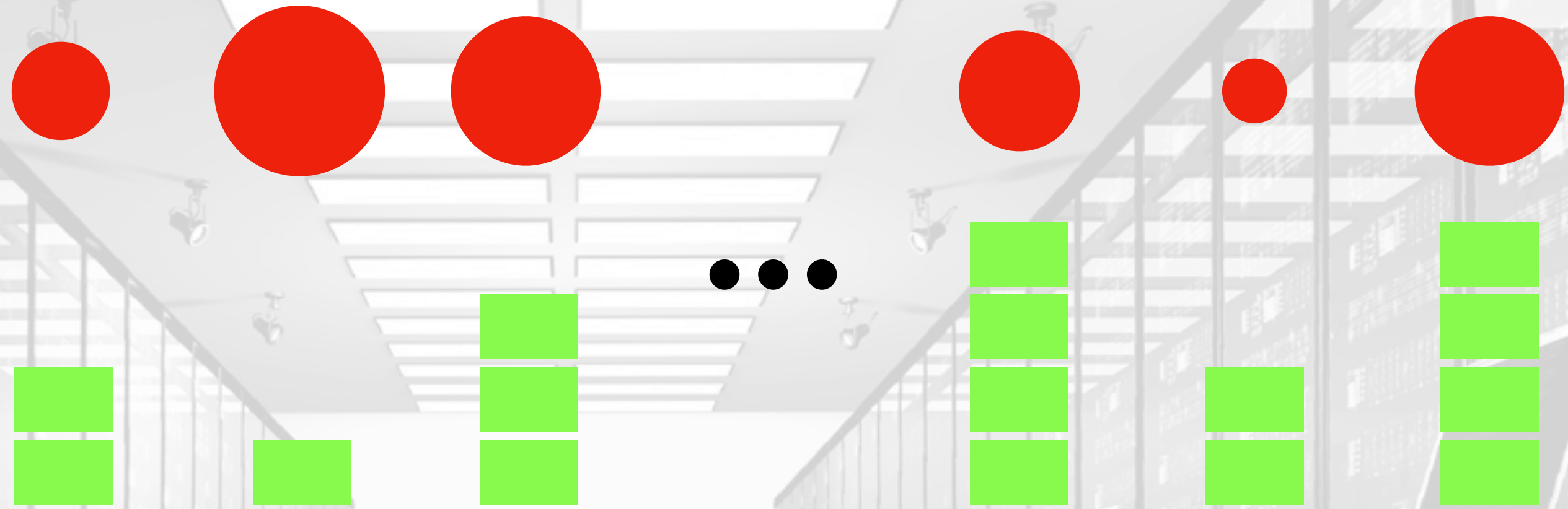
A grayscale photograph of a data center aisle. On both sides are rows of server racks. In the foreground, there are desks with laptops. A person is walking in the distance down the aisle. The ceiling has a grid of lights. The overall scene is a perspective view of a long, clean data center hallway.

Data Center Resource Management

Services

CPU

Memory



Data Center Resource Management

Services

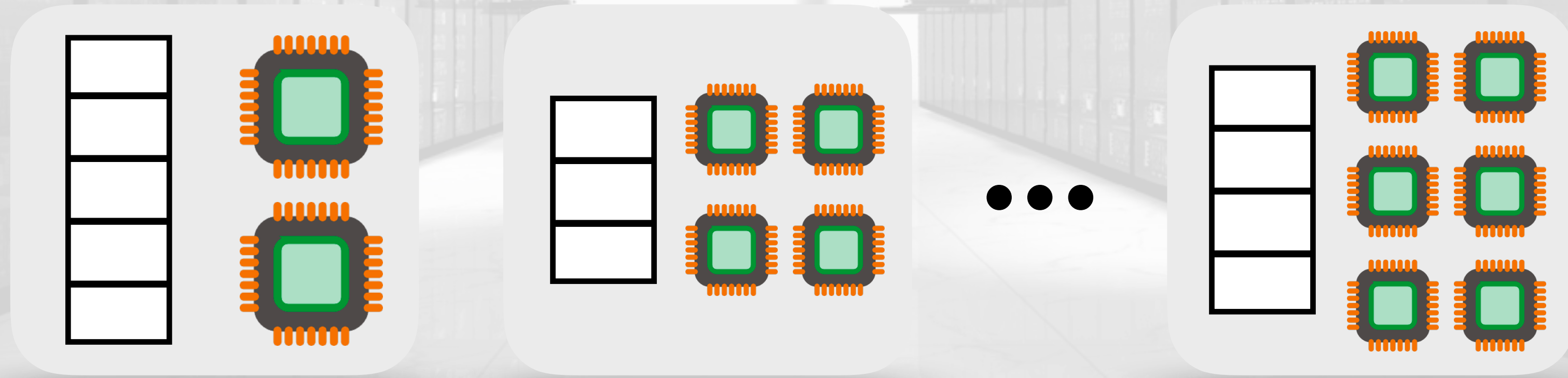
CPU



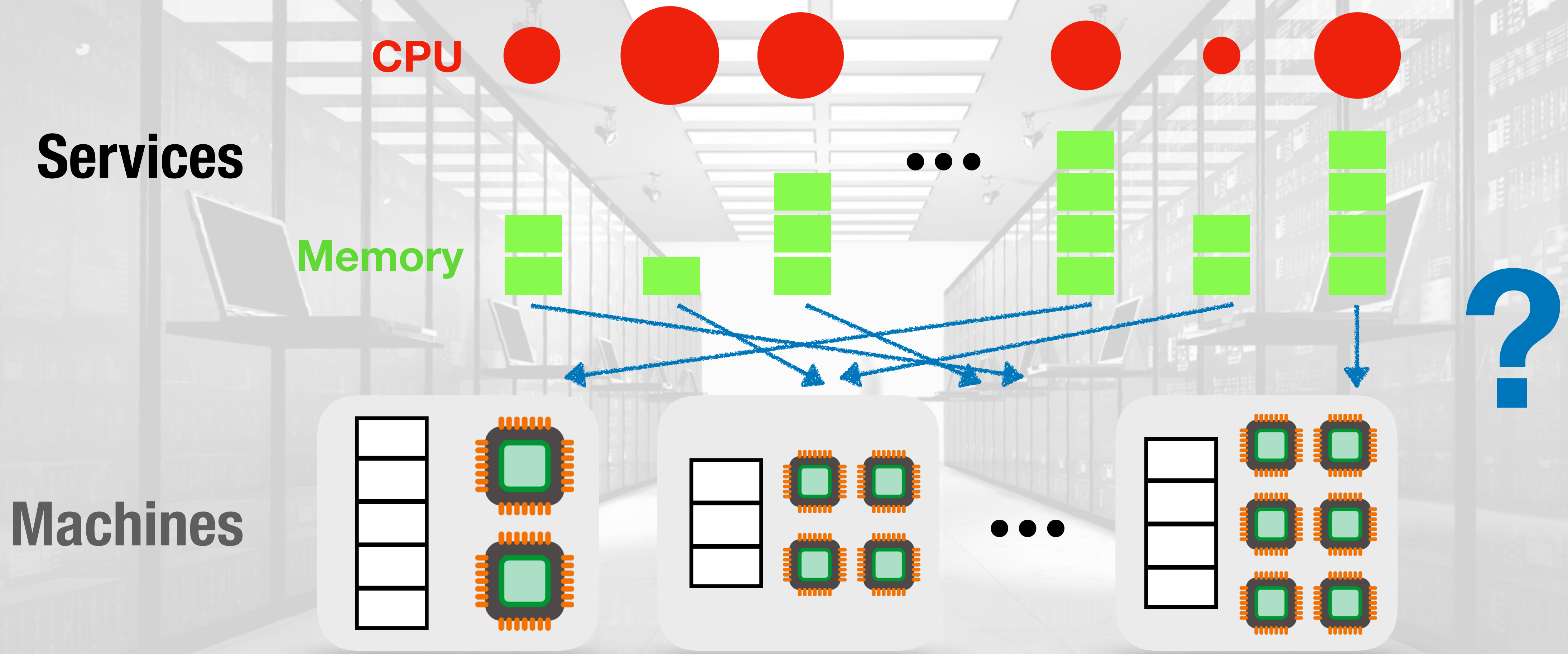
Memory



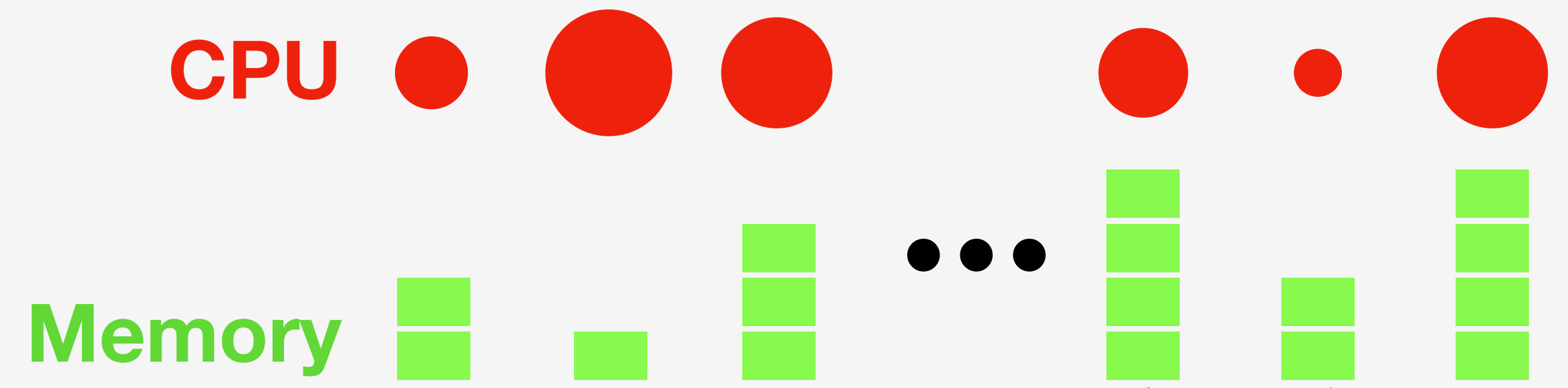
Machines



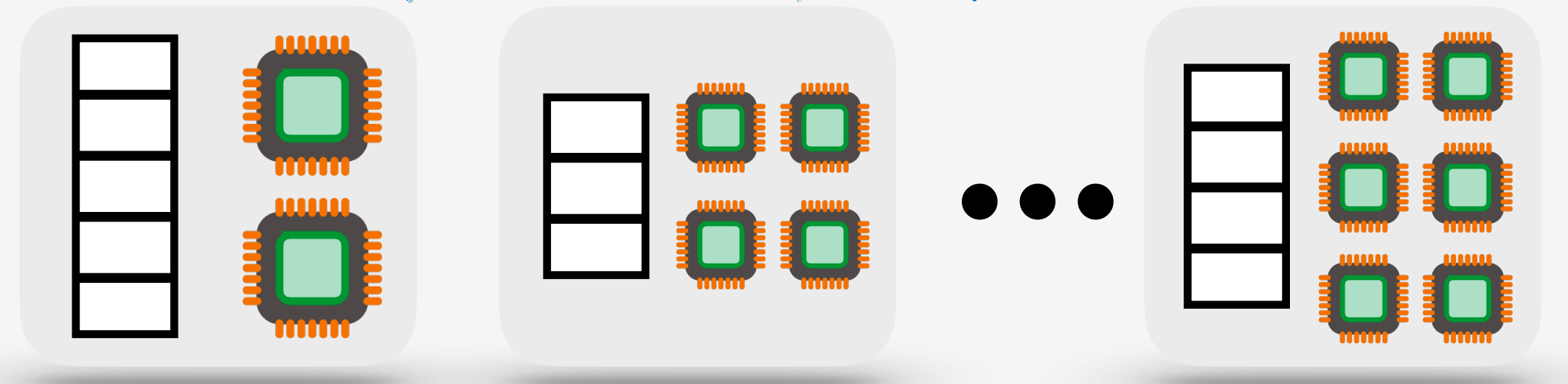
Data Center Resource Management



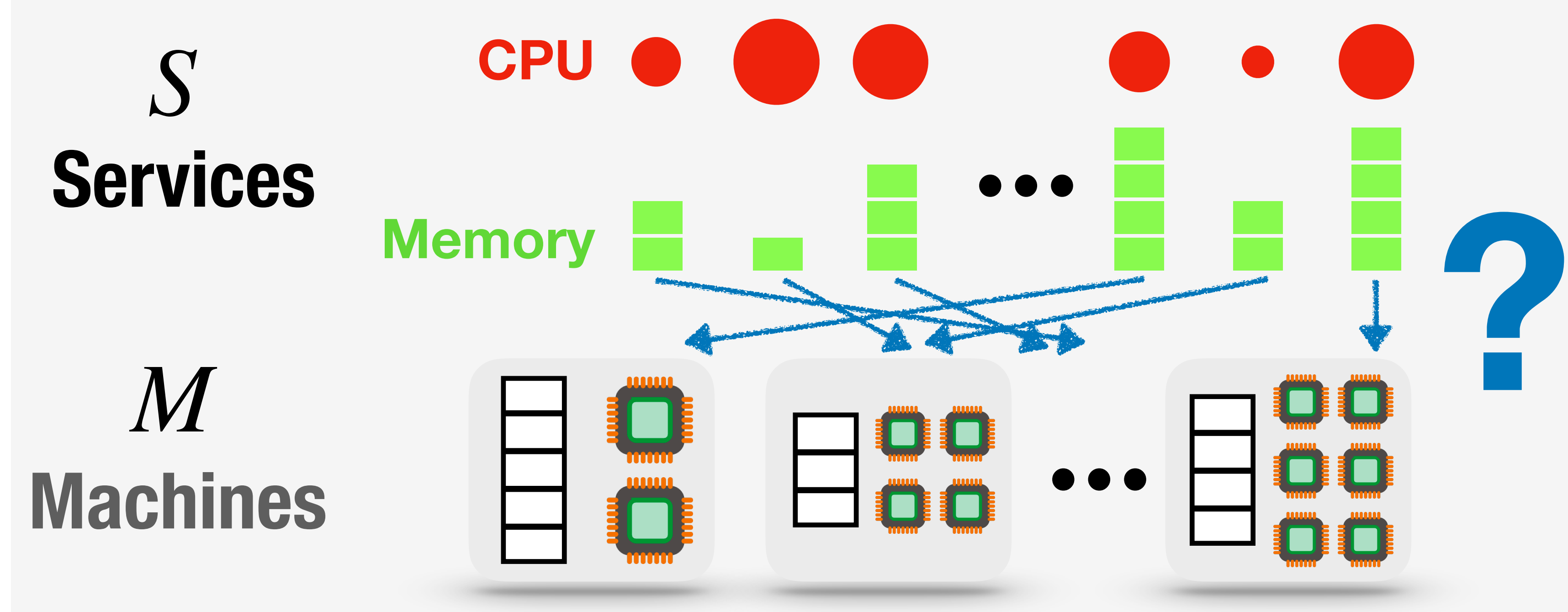
S
Services



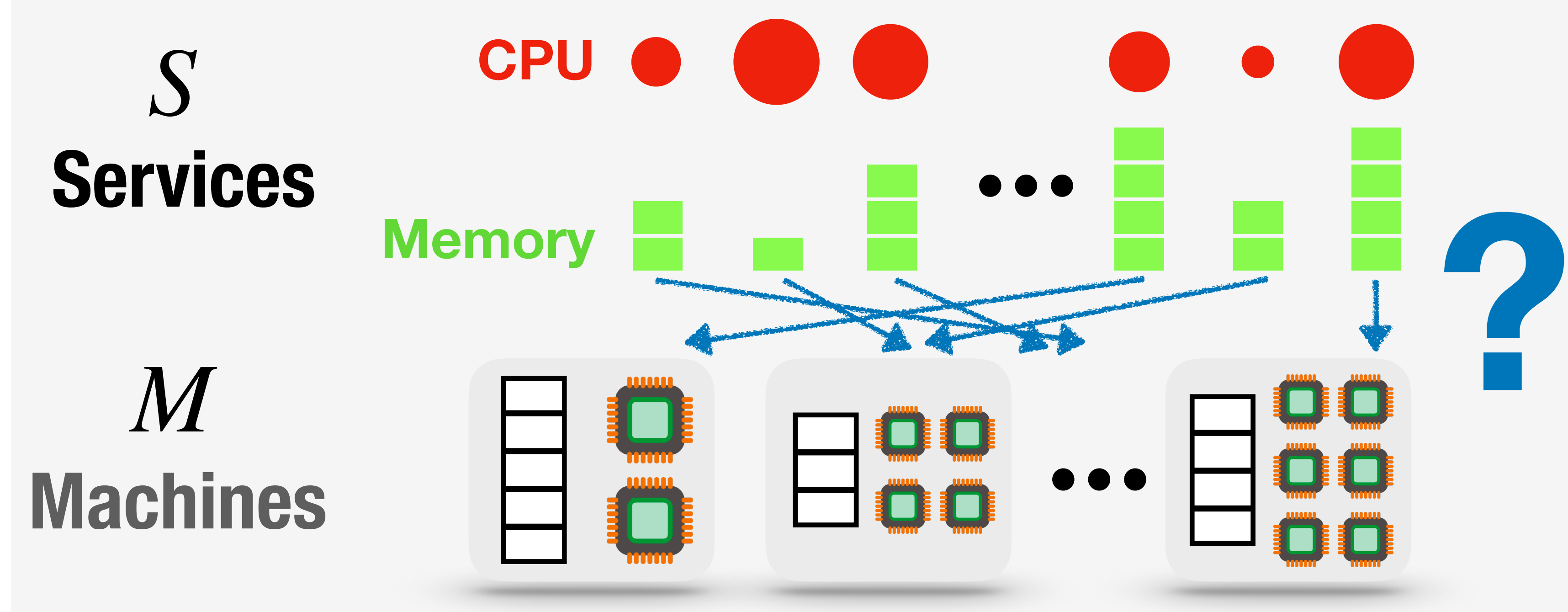
M
Machines



$y_m = 1$ if machine m is used
 $x_{s,m} = 1$ if service s runs on m



$y_m = 1$ if machine m is used
 $x_{s,m} = 1$ if service s runs on m
 $x \in \{0,1\}^{S \times M}, y \in \{0,1\}^M$

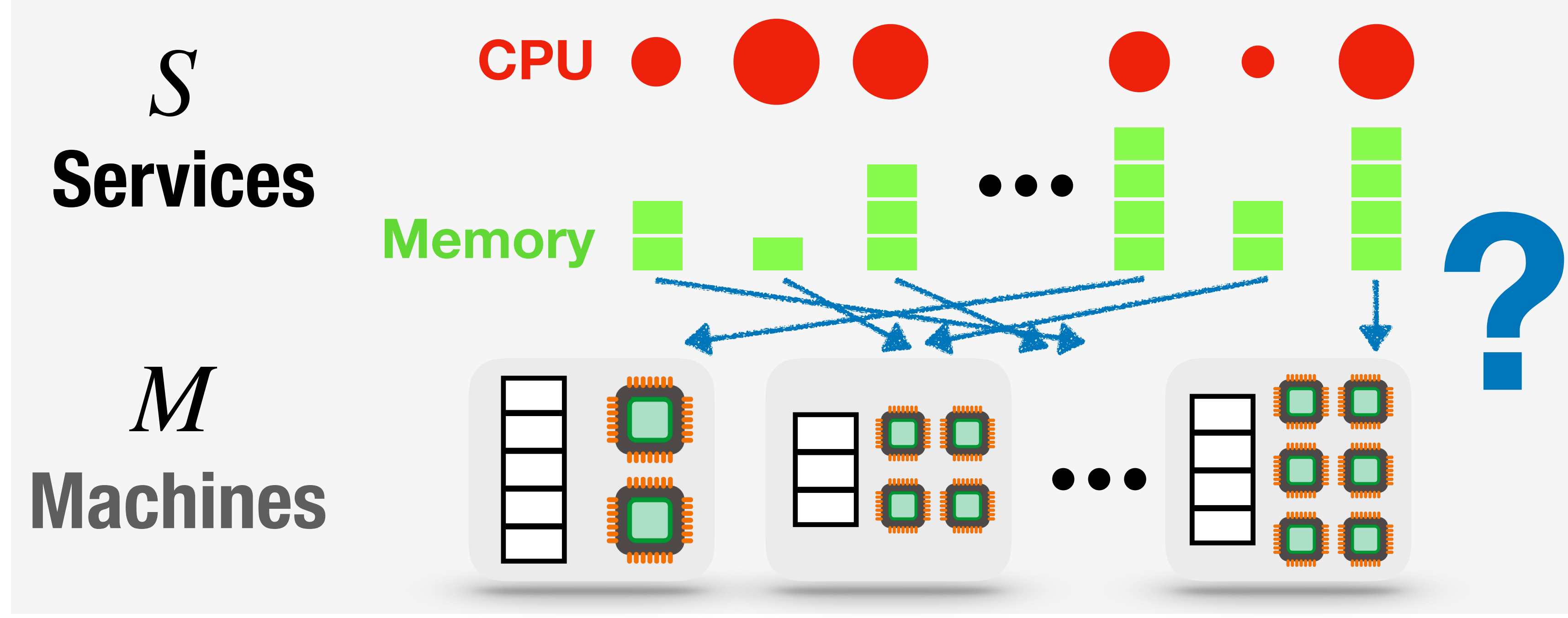


$y_m = 1$ if machine m is used

$x_{s,m} = 1$ if service s runs on m

$x \in \{0,1\}^{S \times M}, y \in \{0,1\}^M$

minimize $\sum_{m=1}^M y_m$

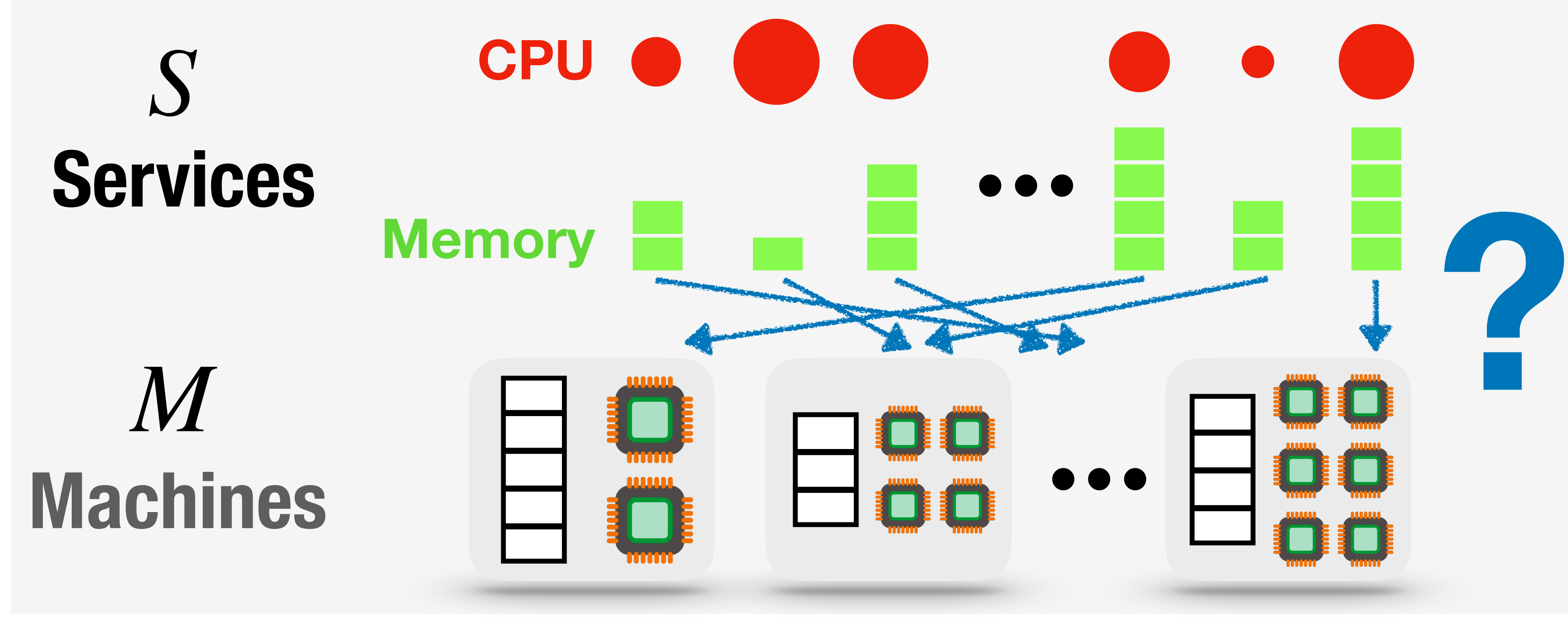


$y_m = 1$ if machine m is used
 $x_{s,m} = 1$ if service s runs on m

$x \in \{0,1\}^{S \times M}, y \in \{0,1\}^M$

minimize $\sum_{m=1}^M y_m$

Constraints:



$y_m = 1$ if machine m is used

$x_{s,m} = 1$ if service s runs on m

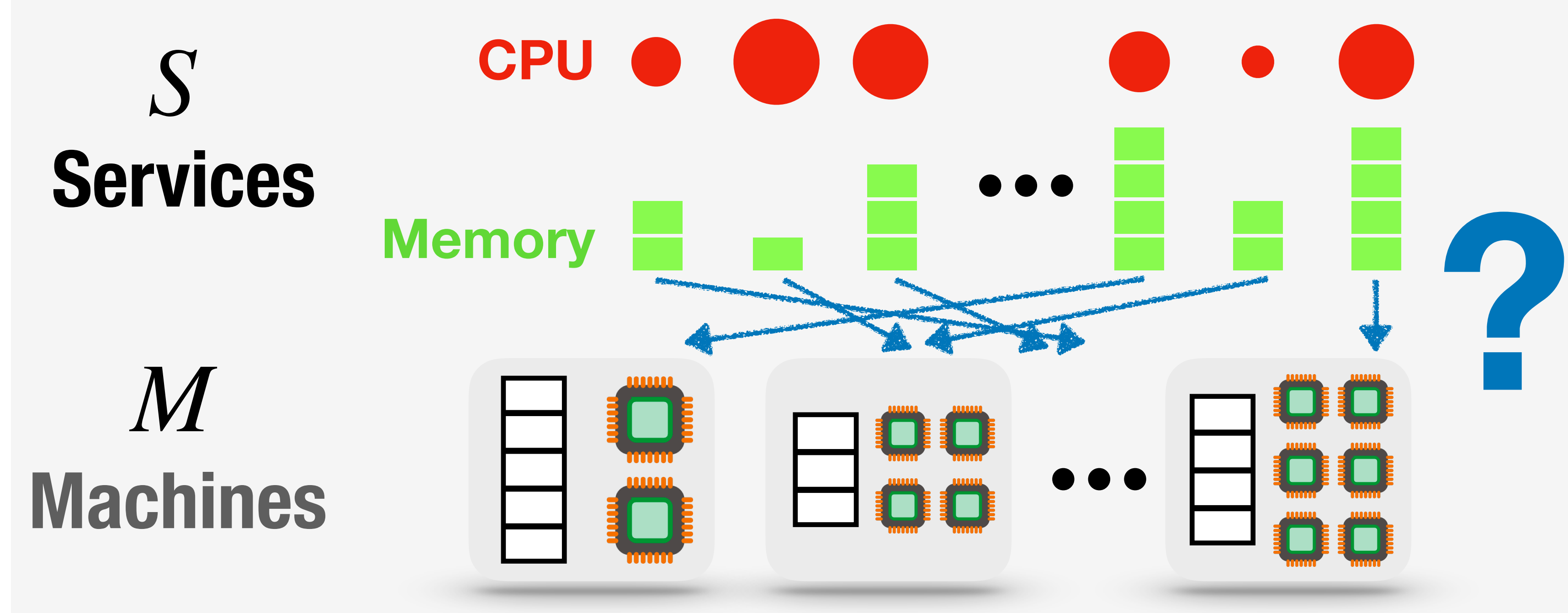
$x \in \{0,1\}^{S \times M}, y \in \{0,1\}^M$

minimize $\sum_{m=1}^M y_m$

Constraints:

Each service on one machine only

$$\sum_{m=1}^M x_{s,m} = 1 \quad \forall s$$



$y_m = 1$ if machine m is used

$x_{s,m} = 1$ if service s runs on m

$x \in \{0,1\}^{S \times M}, y \in \{0,1\}^M$

minimize $\sum_{m=1}^M y_m$

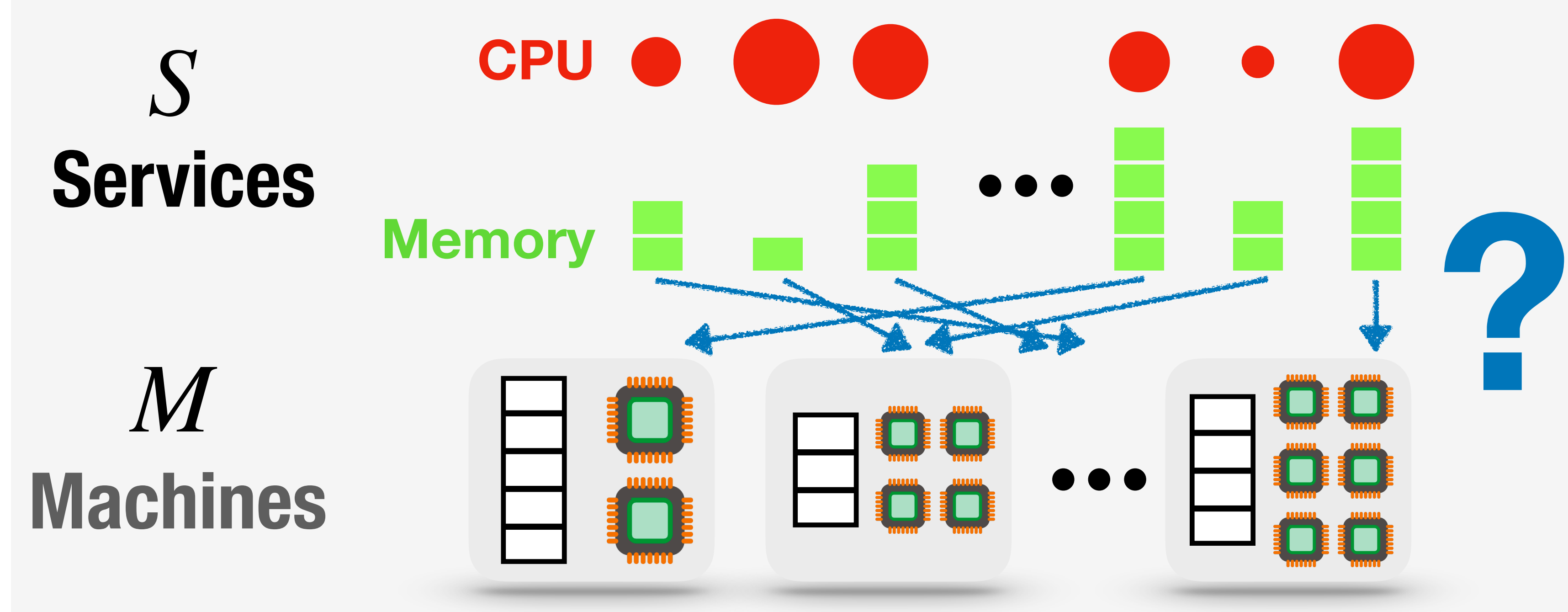
Constraints:

Each service on one machine only

$$\sum_{m=1}^M x_{s,m} = 1 \quad \forall s$$

$$y_m \geq x_{s,m} \quad \forall s, m$$

Machine is "ON" if a job is assigned to it



$y_m = 1$ if machine m is used
 $x_{s,m} = 1$ if service s runs on m

$x \in \{0,1\}^{S \times M}, y \in \{0,1\}^M$

minimize $\sum_{m=1}^M y_m$

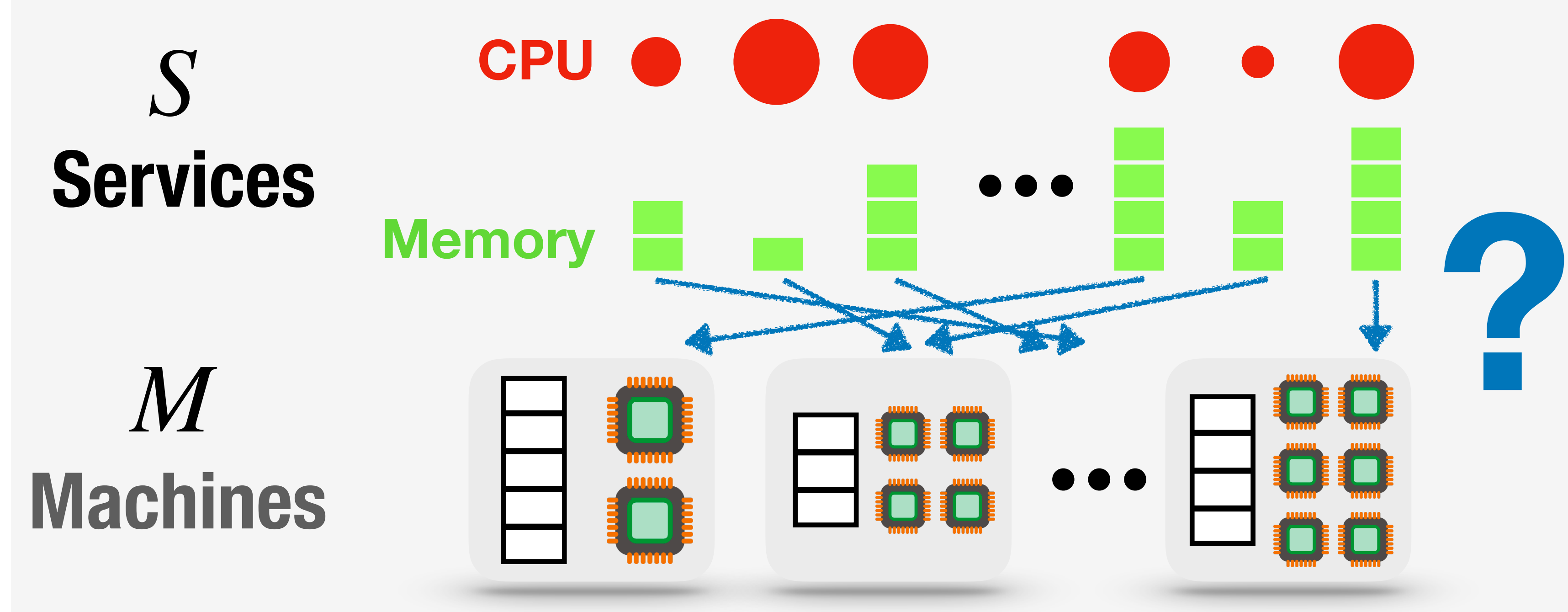
Constraints:

Each service on one machine only

$$\sum_{m=1}^M x_{s,m} = 1 \quad \forall s$$

$$y_m \geq x_{s,m} \quad \forall s, m$$

Machine is "ON" if a job is assigned to it



Memory capacity

$$\sum_{s=1}^S \text{mem}(s) \cdot x_{s,m} \leq \text{cap-mem}(m) \quad \forall m$$

$y_m = 1$ if machine m is used
 $x_{s,m} = 1$ if service s runs on m

$x \in \{0,1\}^{S \times M}, y \in \{0,1\}^M$

minimize $\sum_{m=1}^M y_m$

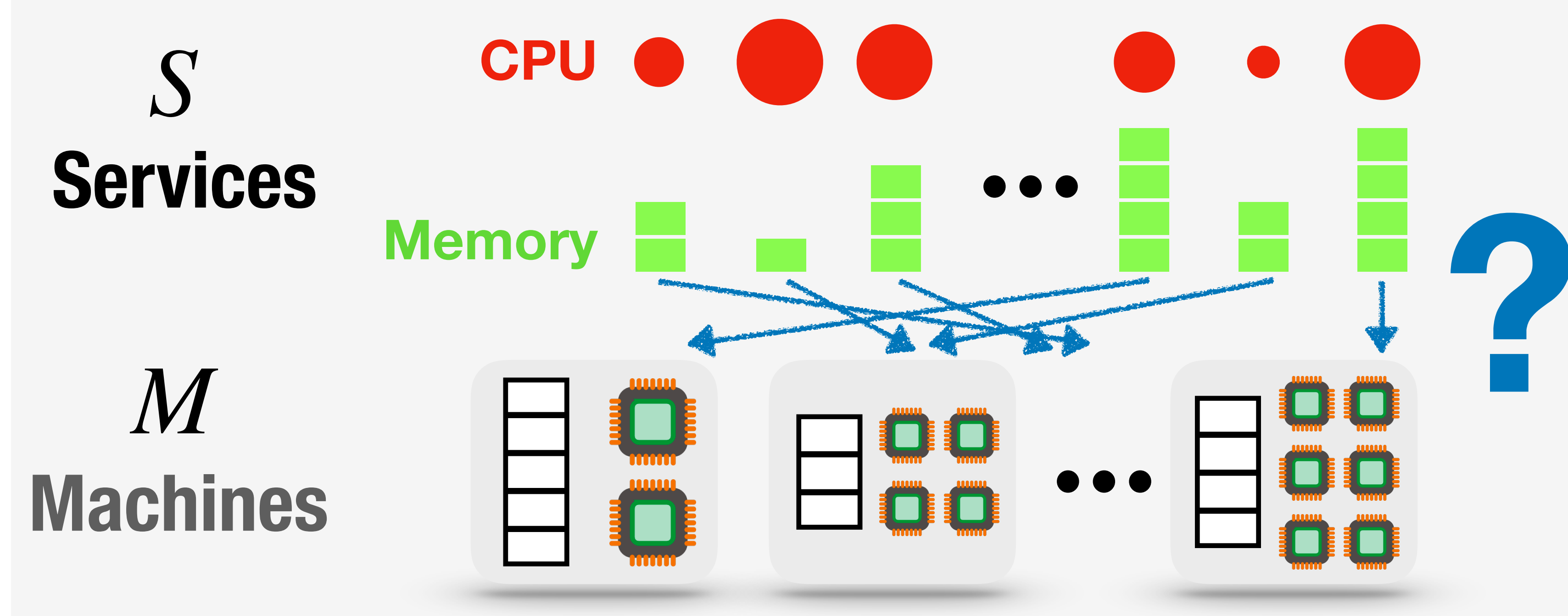
Constraints:

Each service on one machine only

$$\sum_{m=1}^M x_{s,m} = 1 \quad \forall s$$

$$y_m \geq x_{s,m} \quad \forall s, m$$

Machine is "ON" if a job is assigned to it



Memory capacity

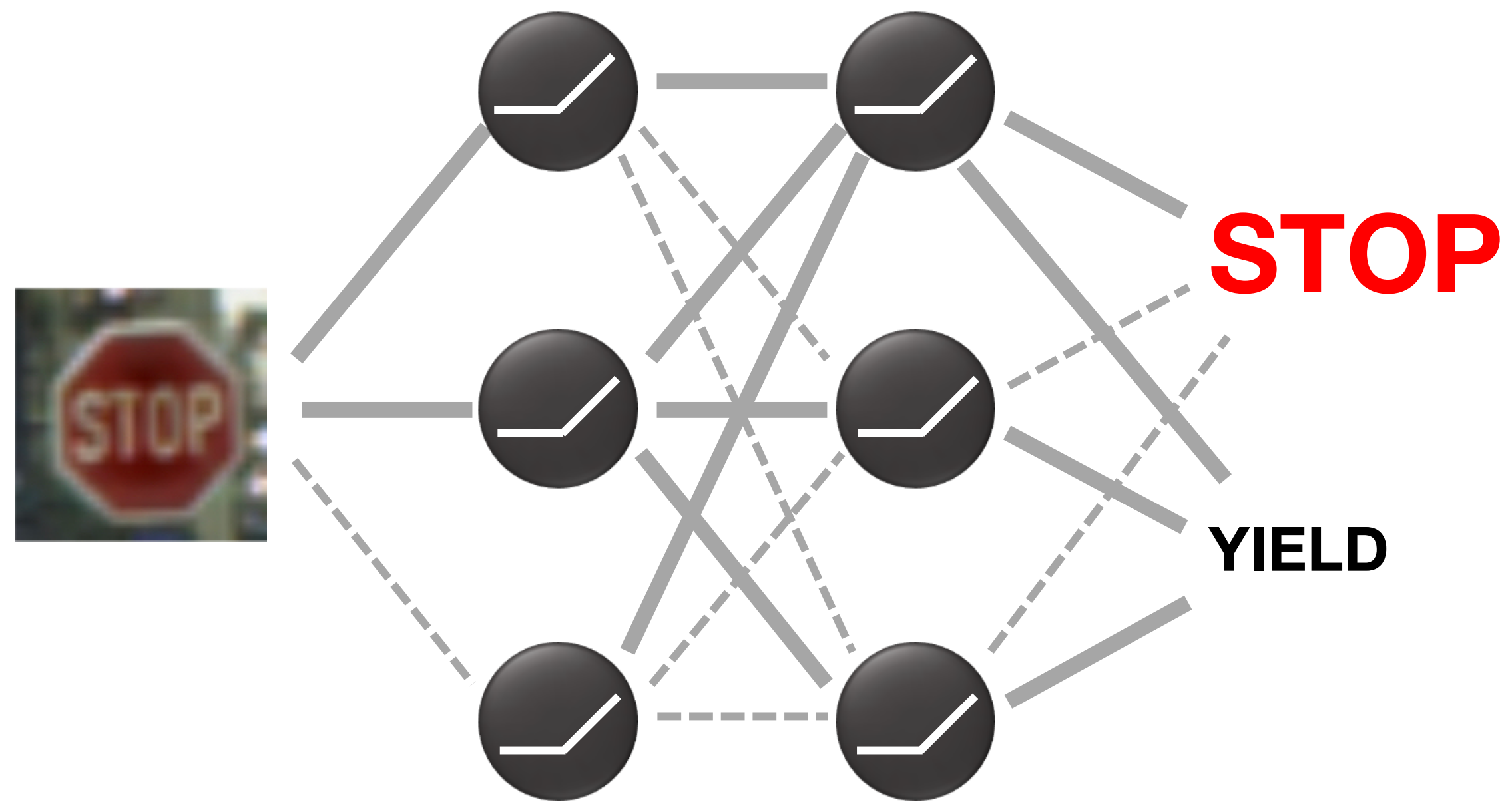
$$\sum_{s=1}^S \text{mem}(s) \cdot x_{s,m} \leq \text{cap-mem}(m) \quad \forall m$$

$$\sum_{s=1}^S \text{cpu}(s) \cdot x_{s,m} \leq \text{cap-cpu}(m) \quad \forall m$$

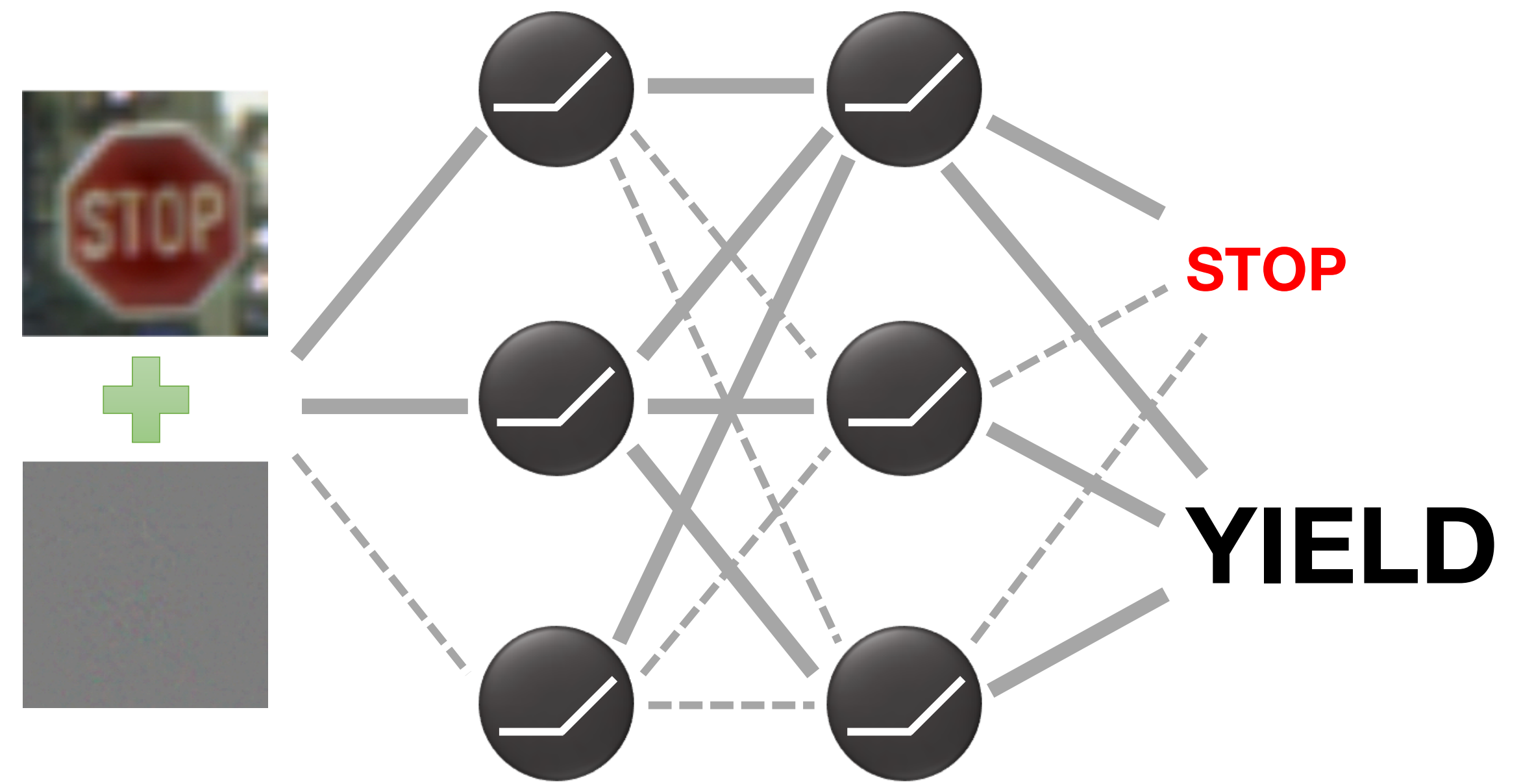
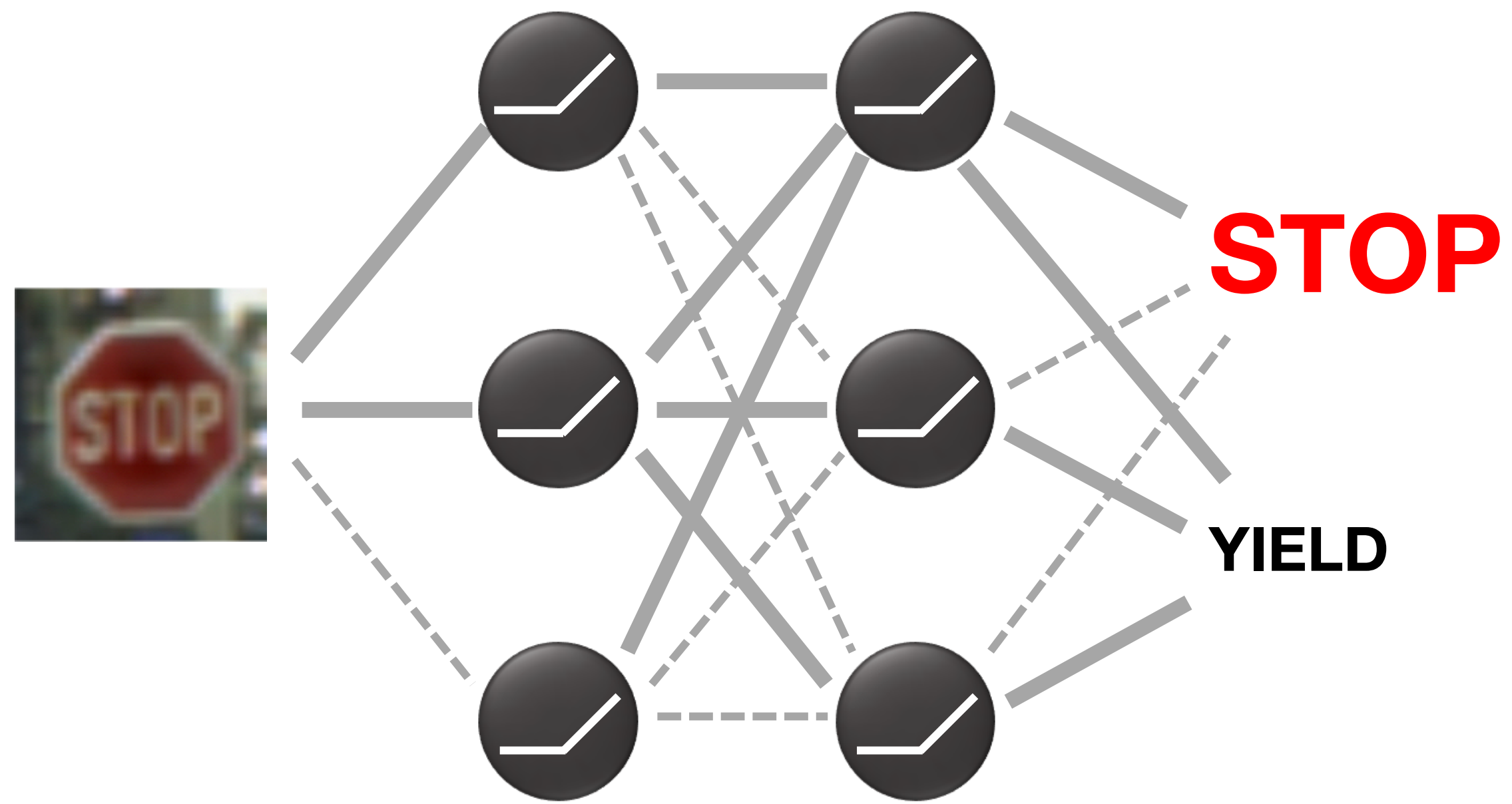
Processor capacity

Safety-Critical Machine Learning

Safety-Critical Machine Learning

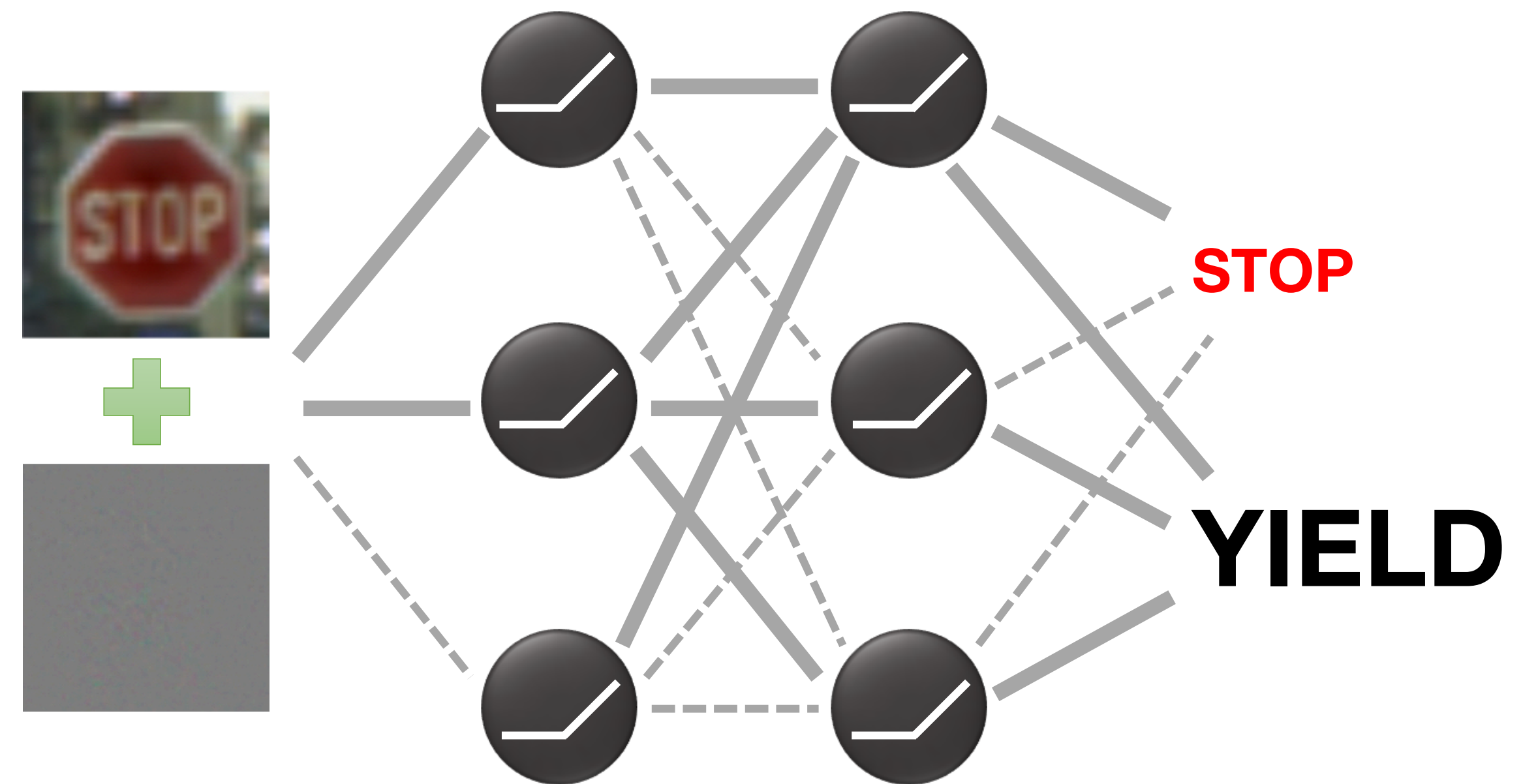
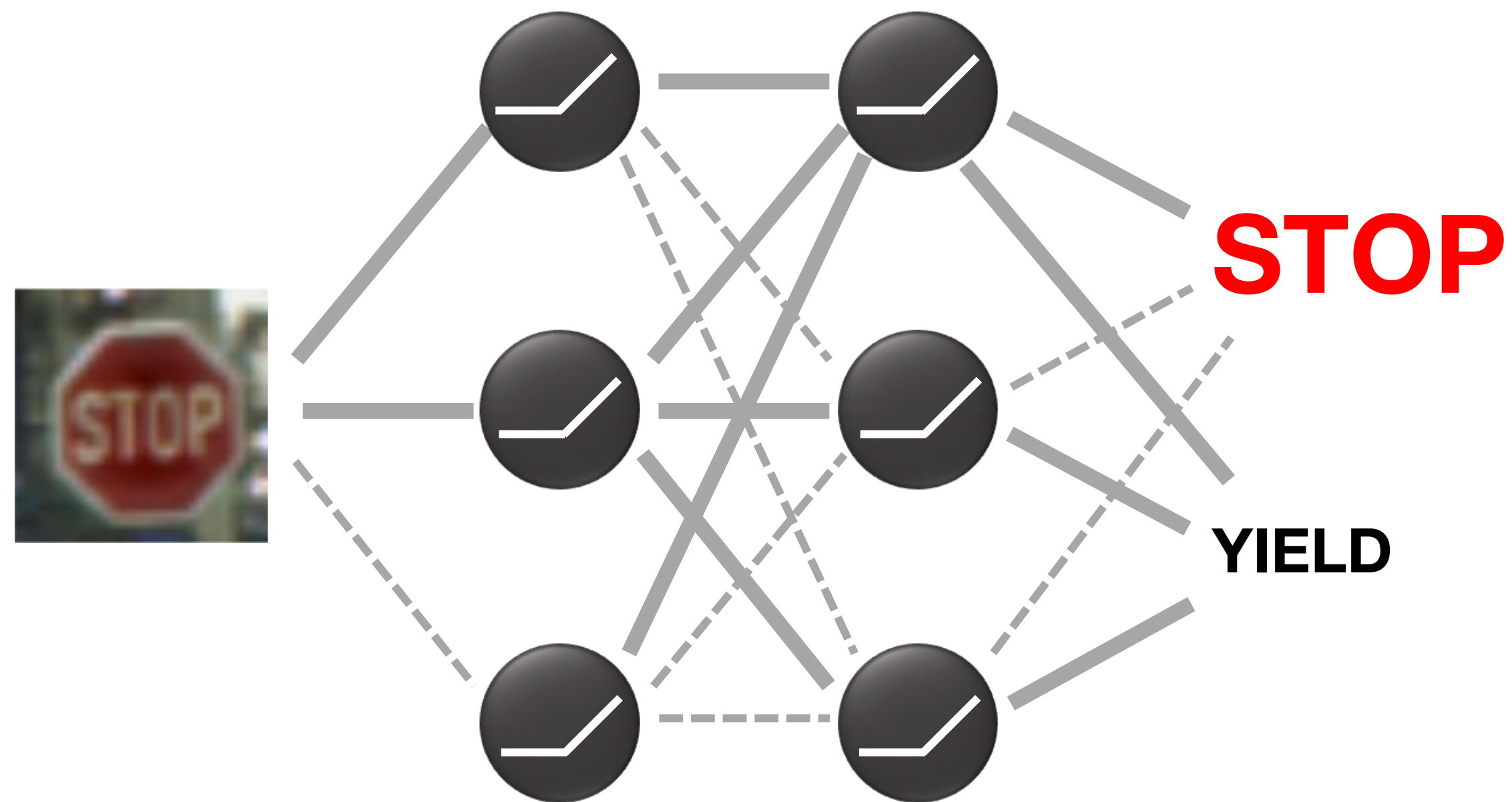


Safety-Critical Machine Learning



Safety-Critical Machine Learning

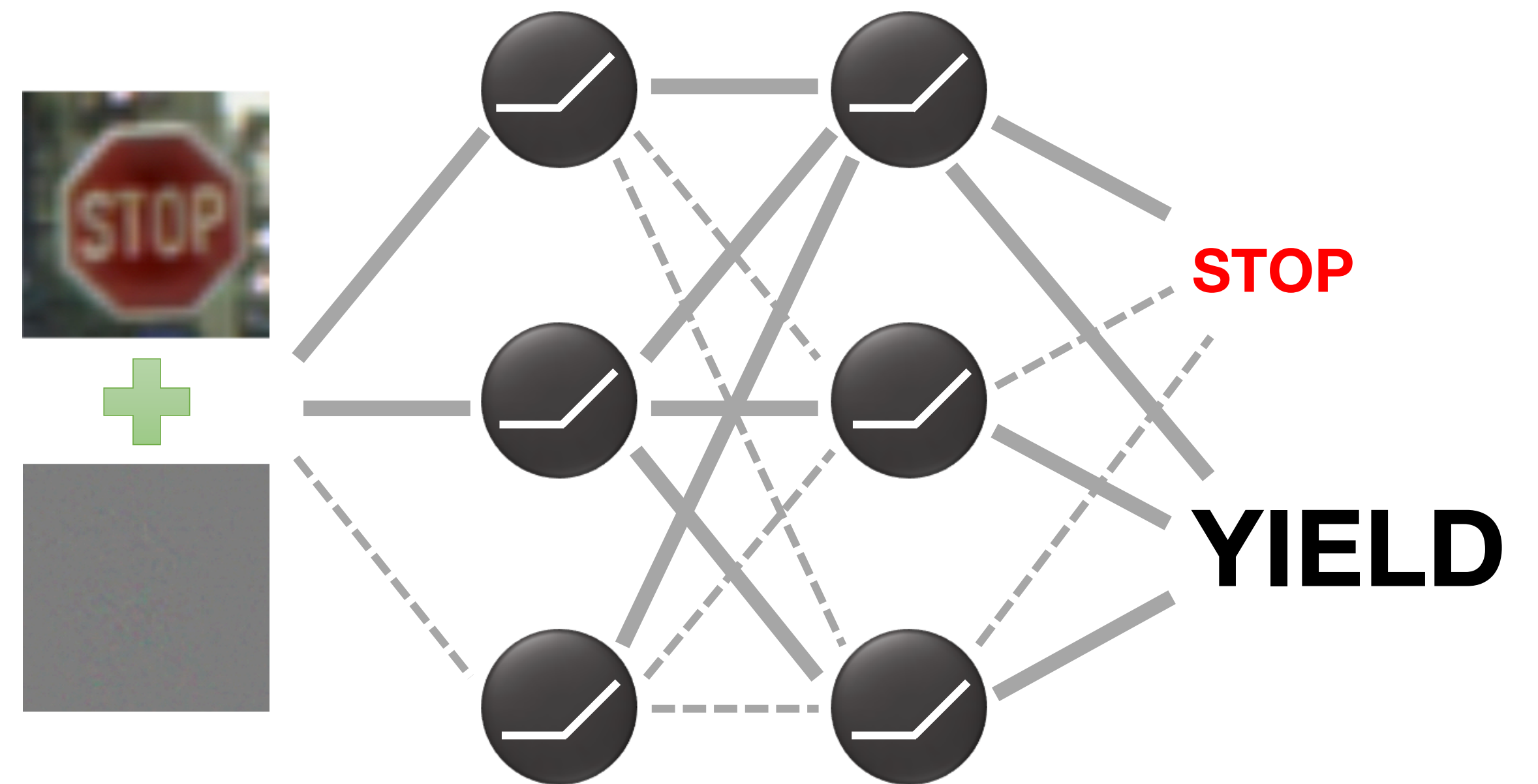
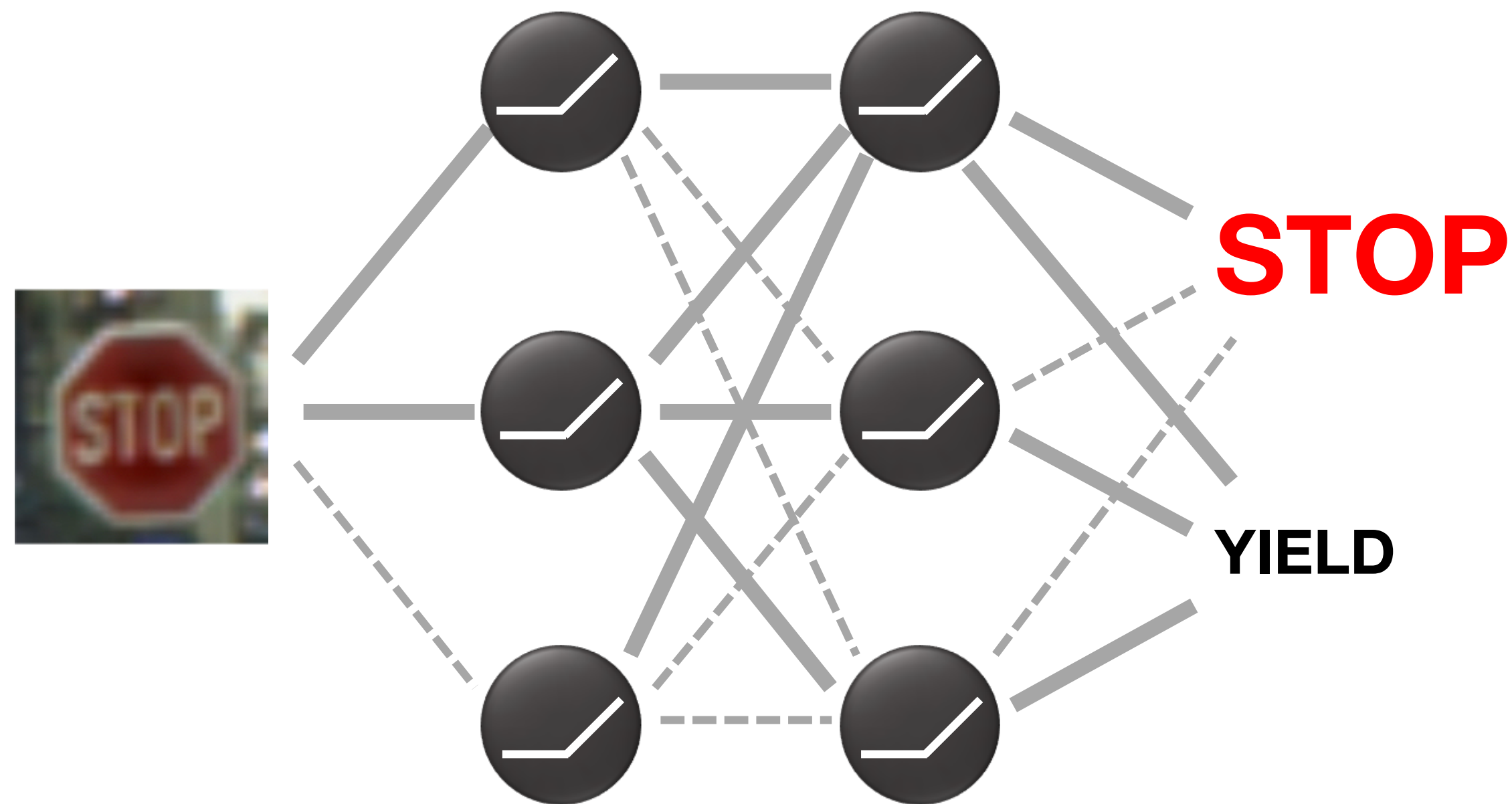
Goal: **Guarantee** that trained model has **desirable behavior**



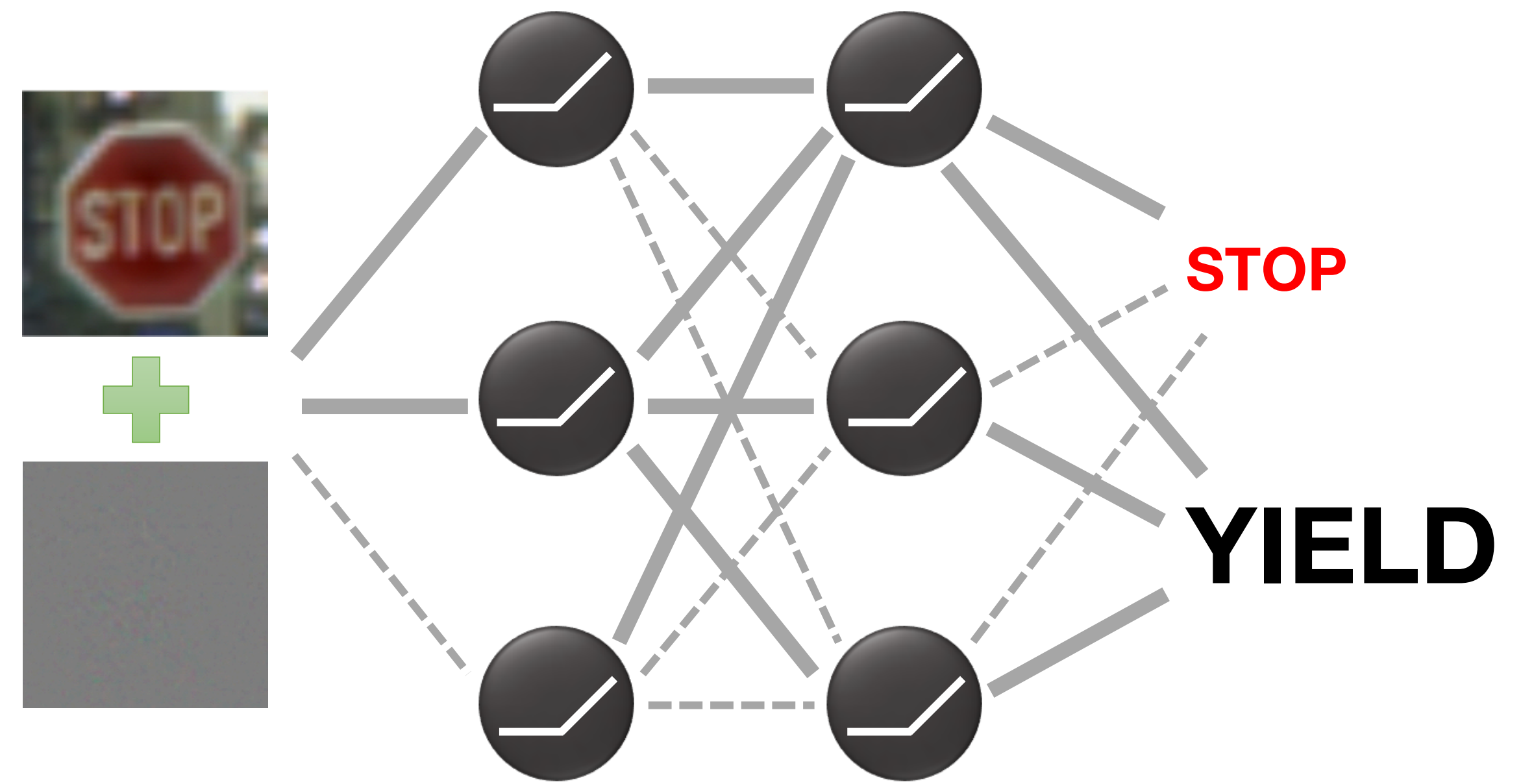
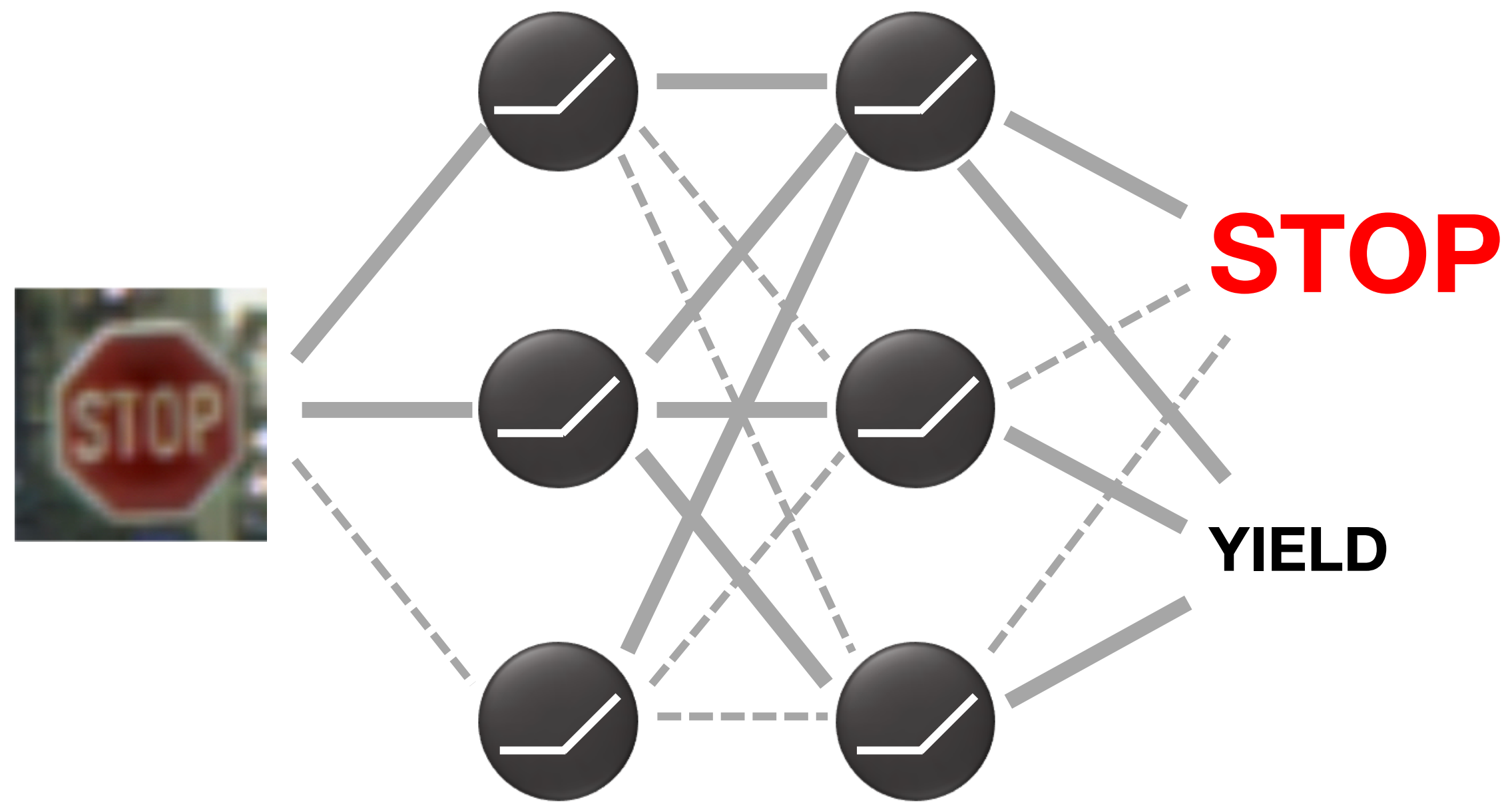
Safety-Critical Machine Learning

Goal: **Guarantee** that trained model has **desirable behavior**

Model ReLU with **Binary** variables + Linear **Inequalities**



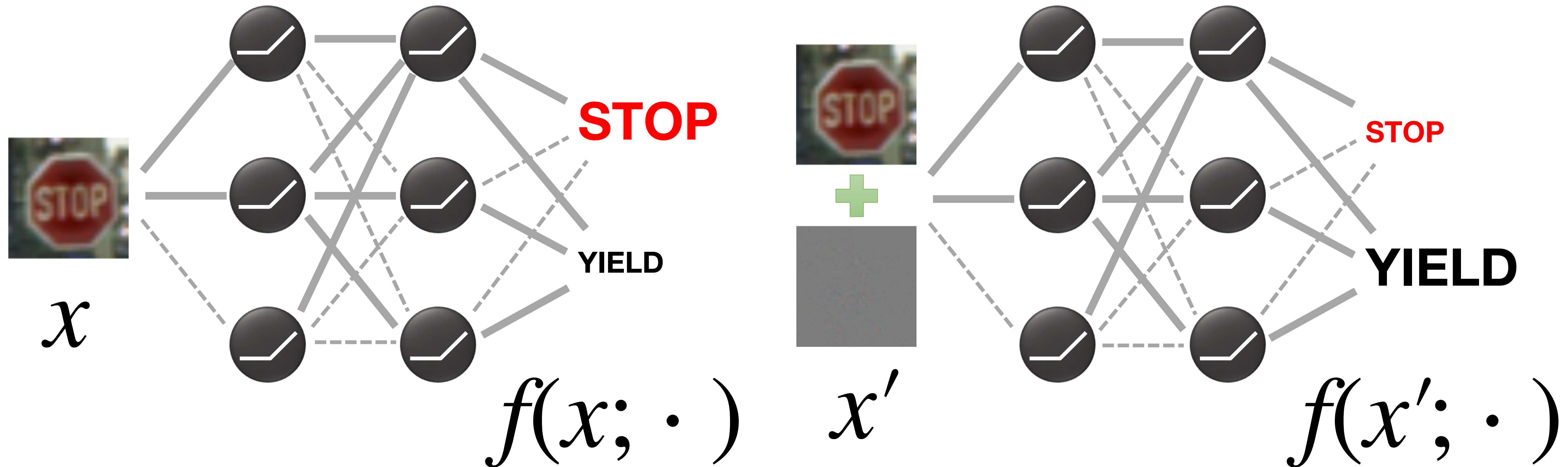
Safety-Critical Machine Learning



Safety-Critical Machine Learning

Verification Problem

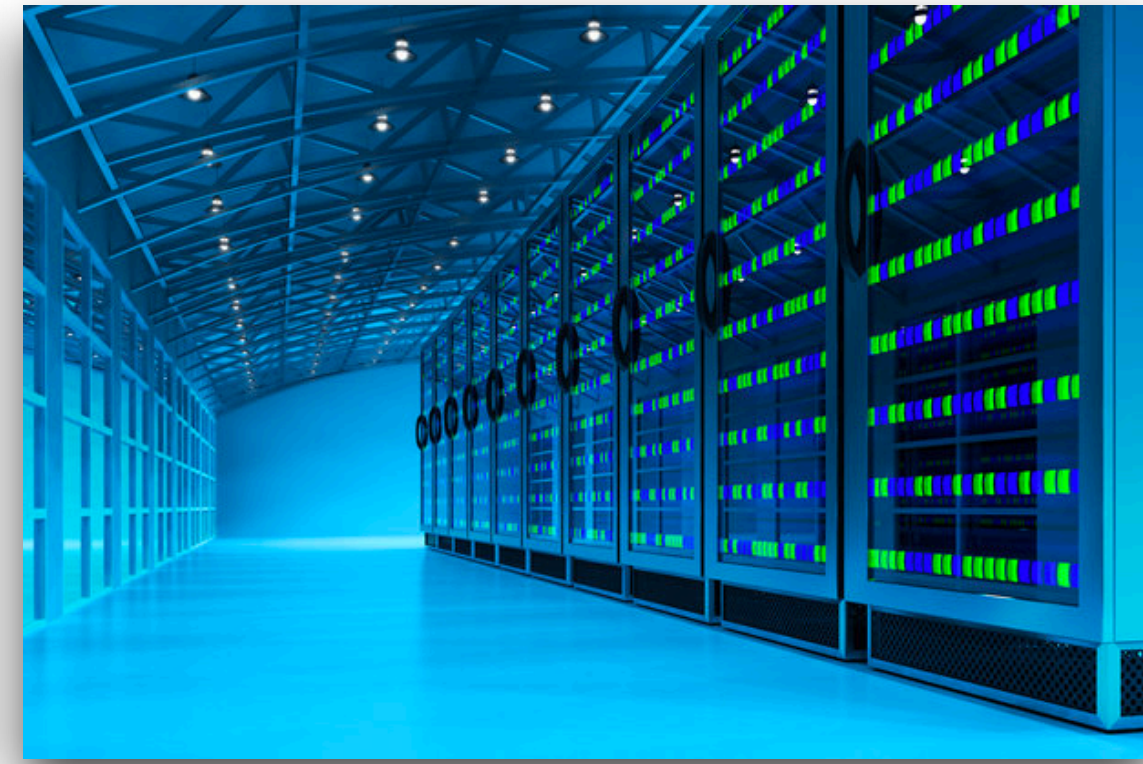
prove $\nexists x'$ close to x
such that $f(x'; \text{STOP}) < f(x'; \text{YIELD})$



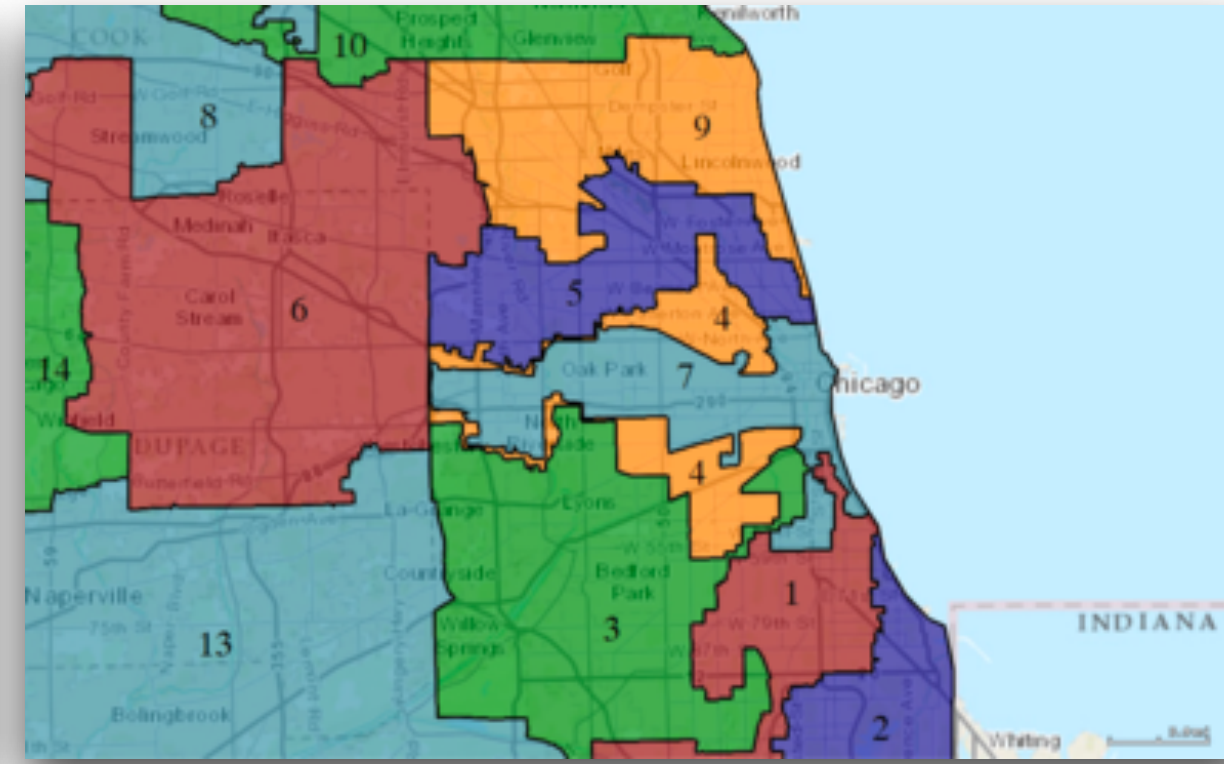
Auction Design



Data Center Management



Political Districting



Kidney Exchange



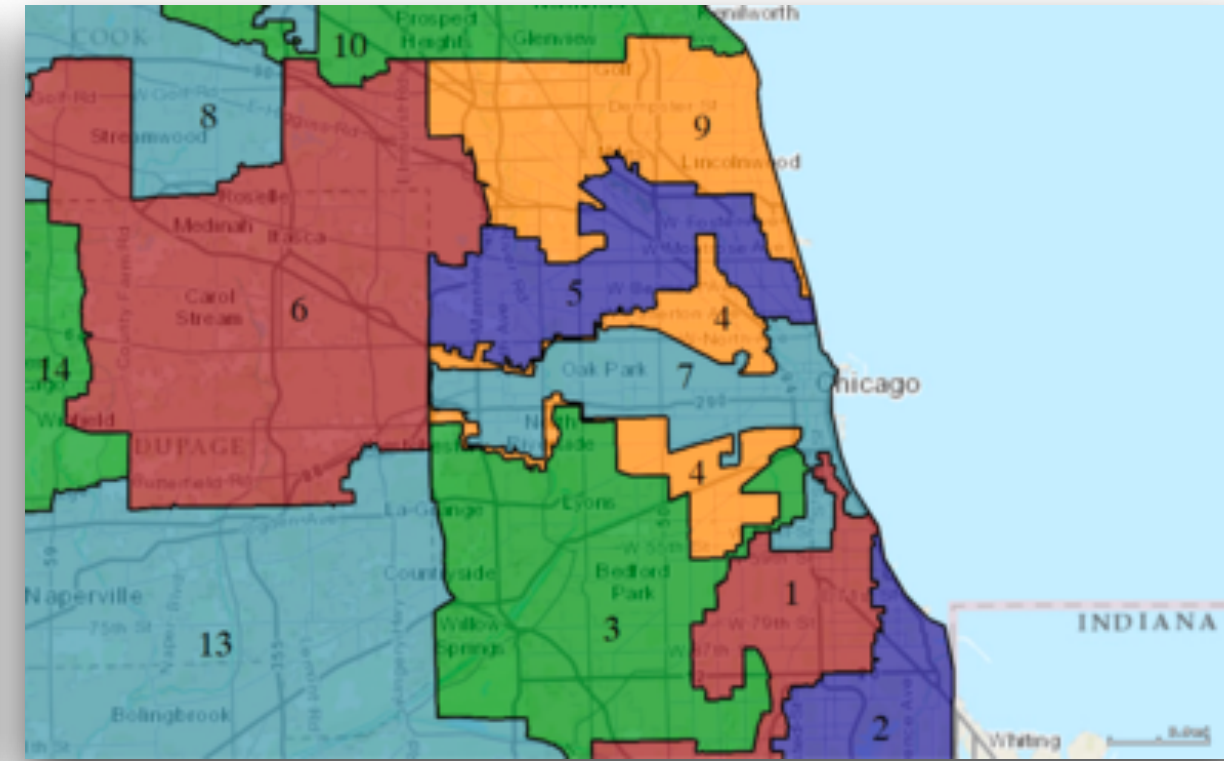
Auction Design



Data Center Management



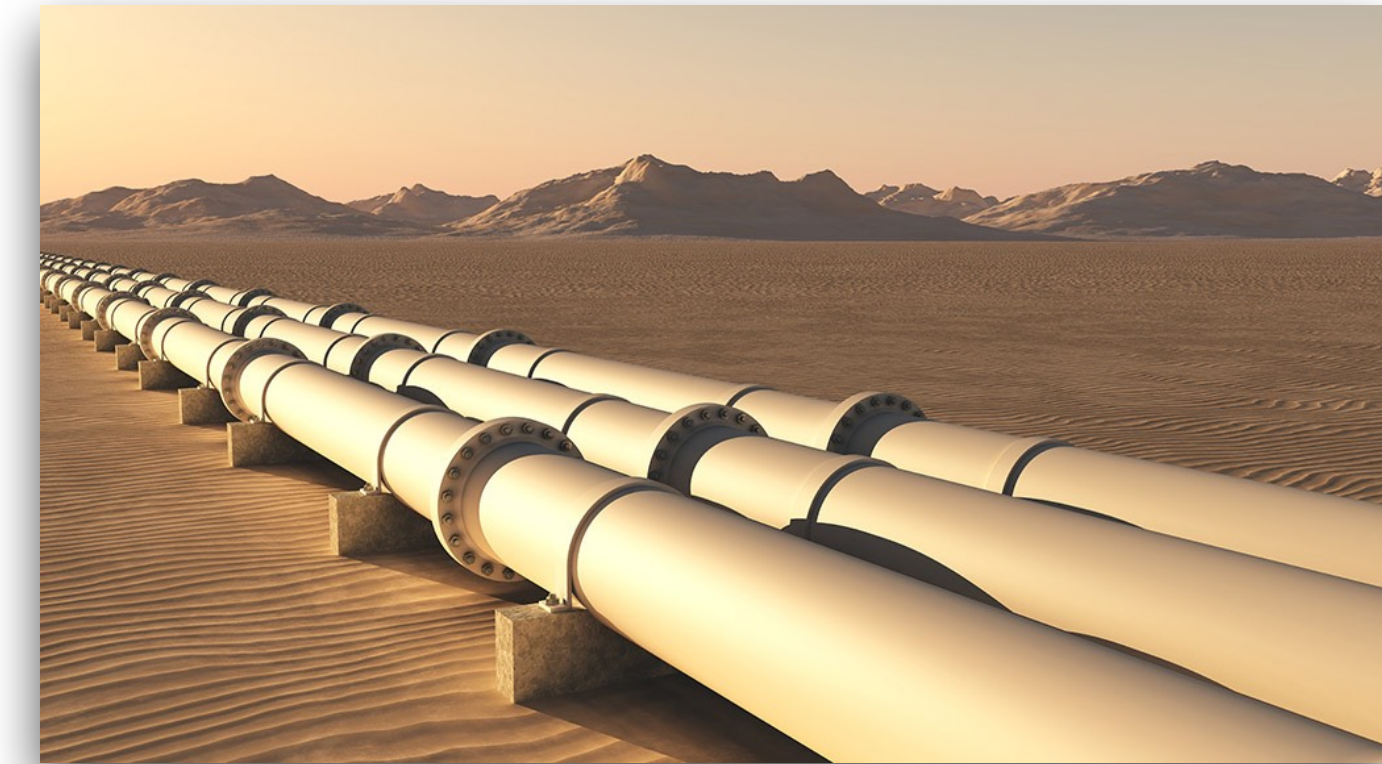
Political Districting



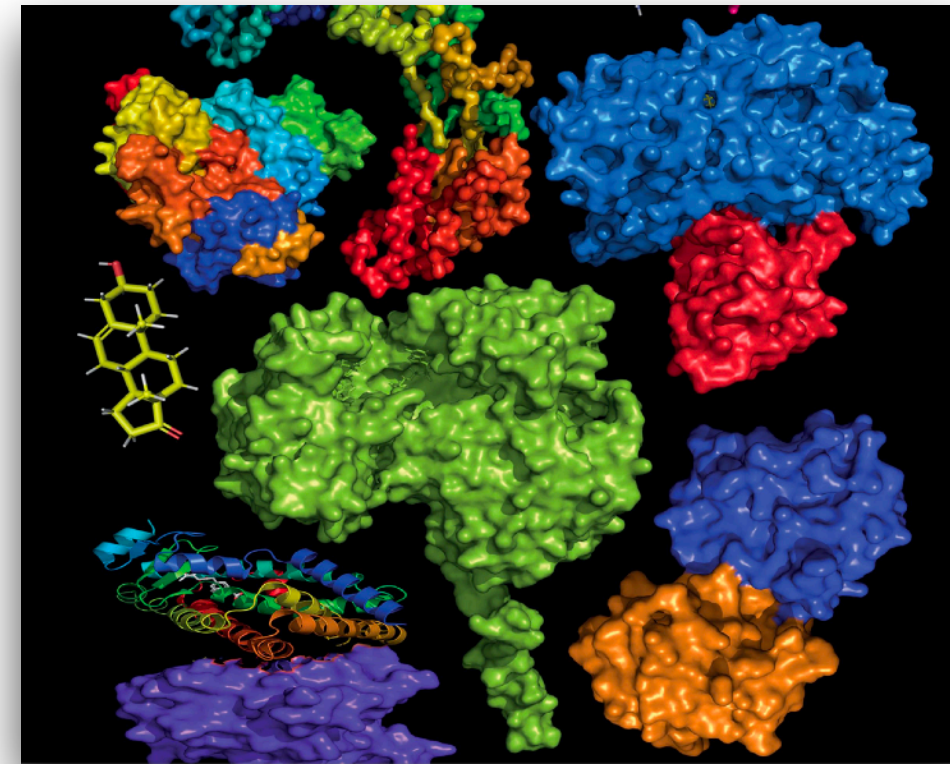
Kidney Exchange



Energy Systems



Scientific Discovery



Ridesharing



Cancer Therapeutics



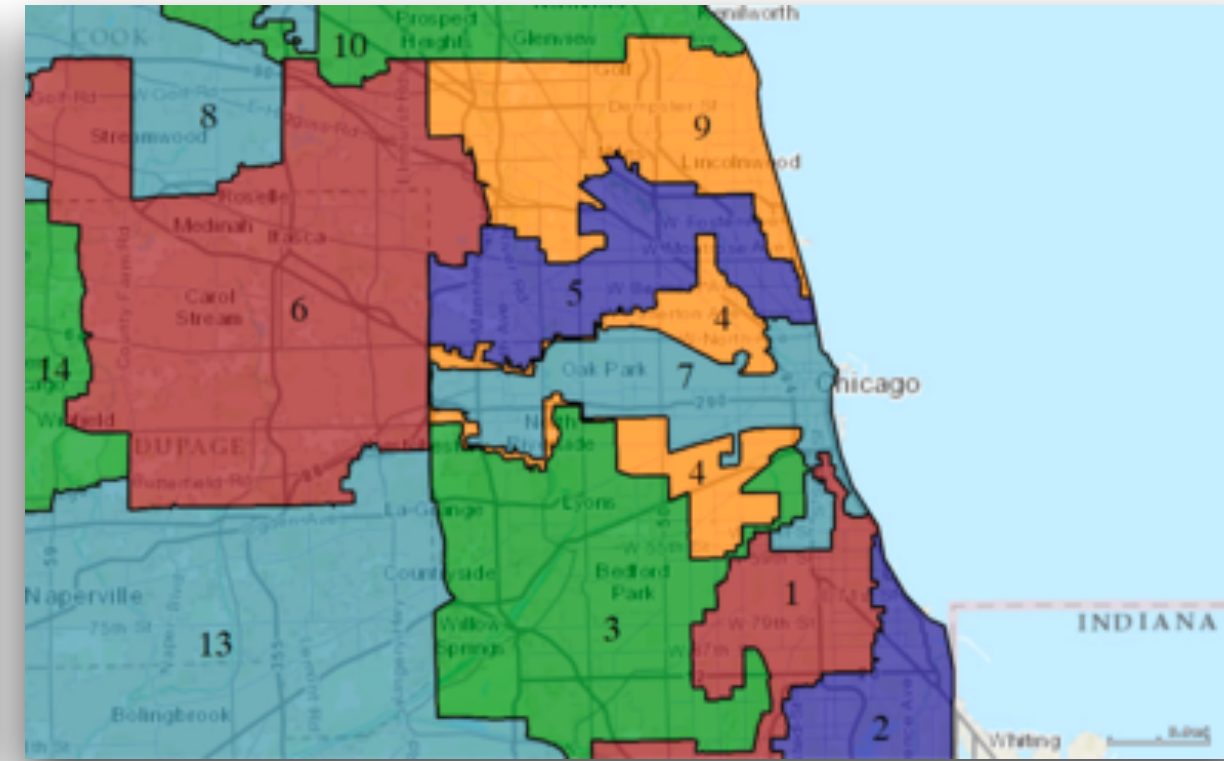
Auction Design



Data Center Management



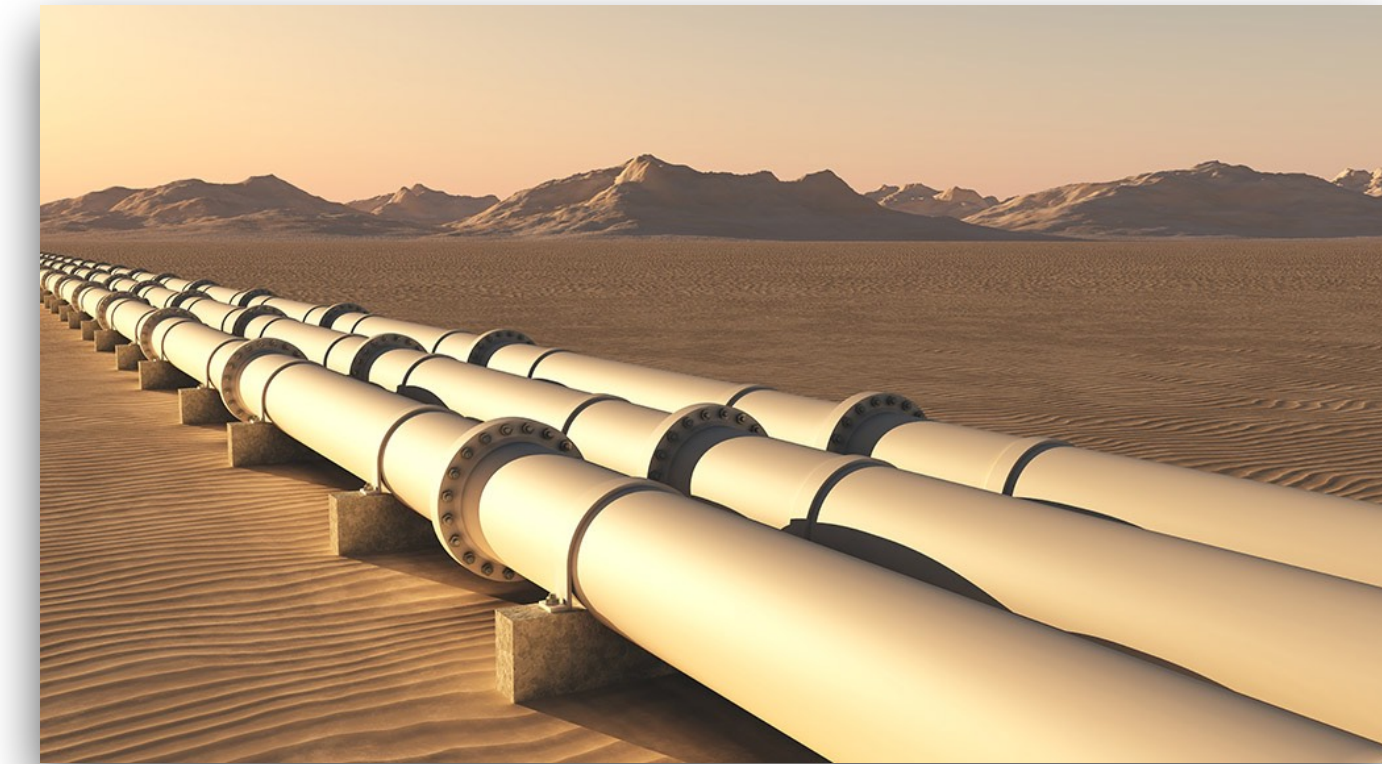
Political Districting



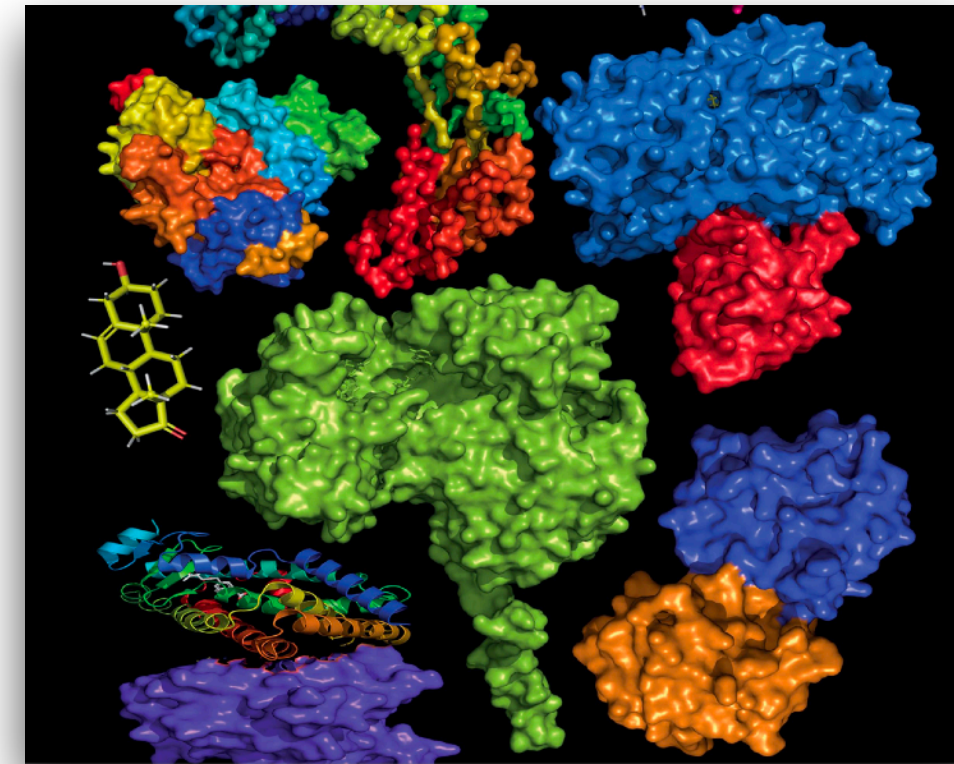
Kidney Exchange



Energy Systems



Scientific Discovery



Ridesharing



Cancer Therapeutics



Airline Scheduling



Conservation Planning



Disaster Response



College Admissions



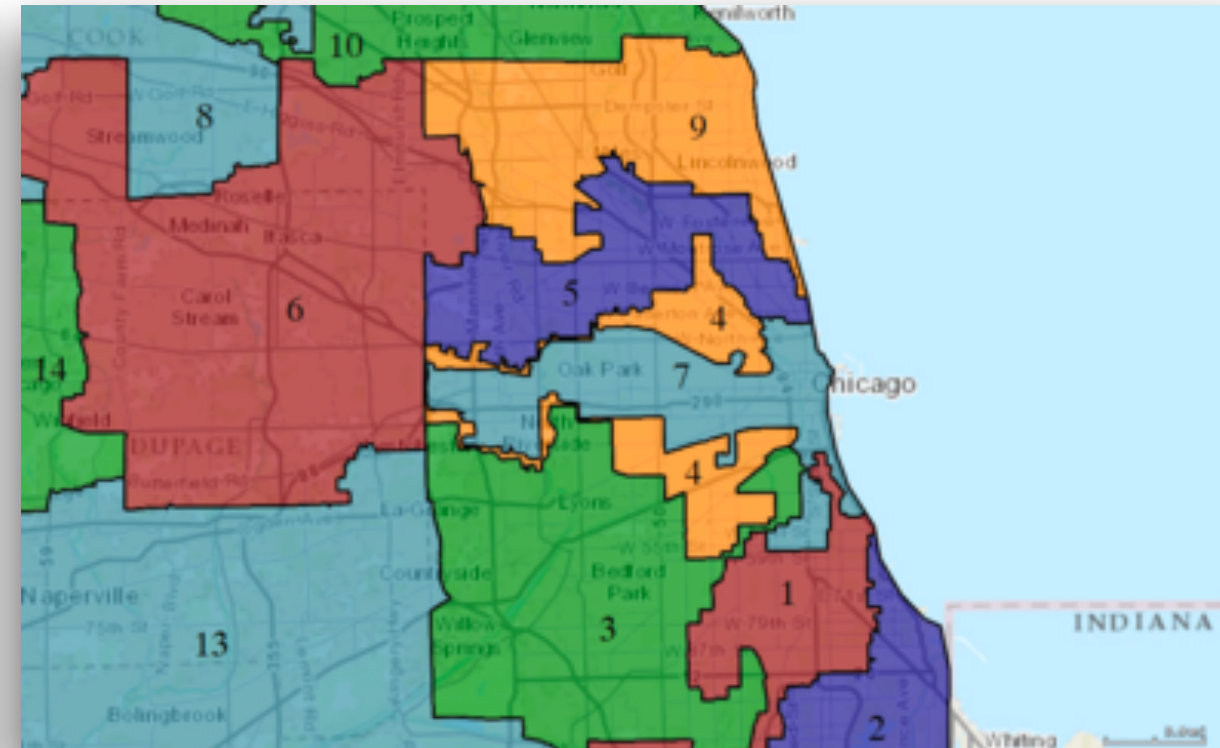
Auction Design



Data Center Management



Political Districting



Kidney Exchange



> 50% of INFORMS Edelman Award winners use Discrete Optimization
→ Billions (\$) in savings/profit

George Nemhauser, Plenary at EURO INFORMS, 2013



Airlin



otics



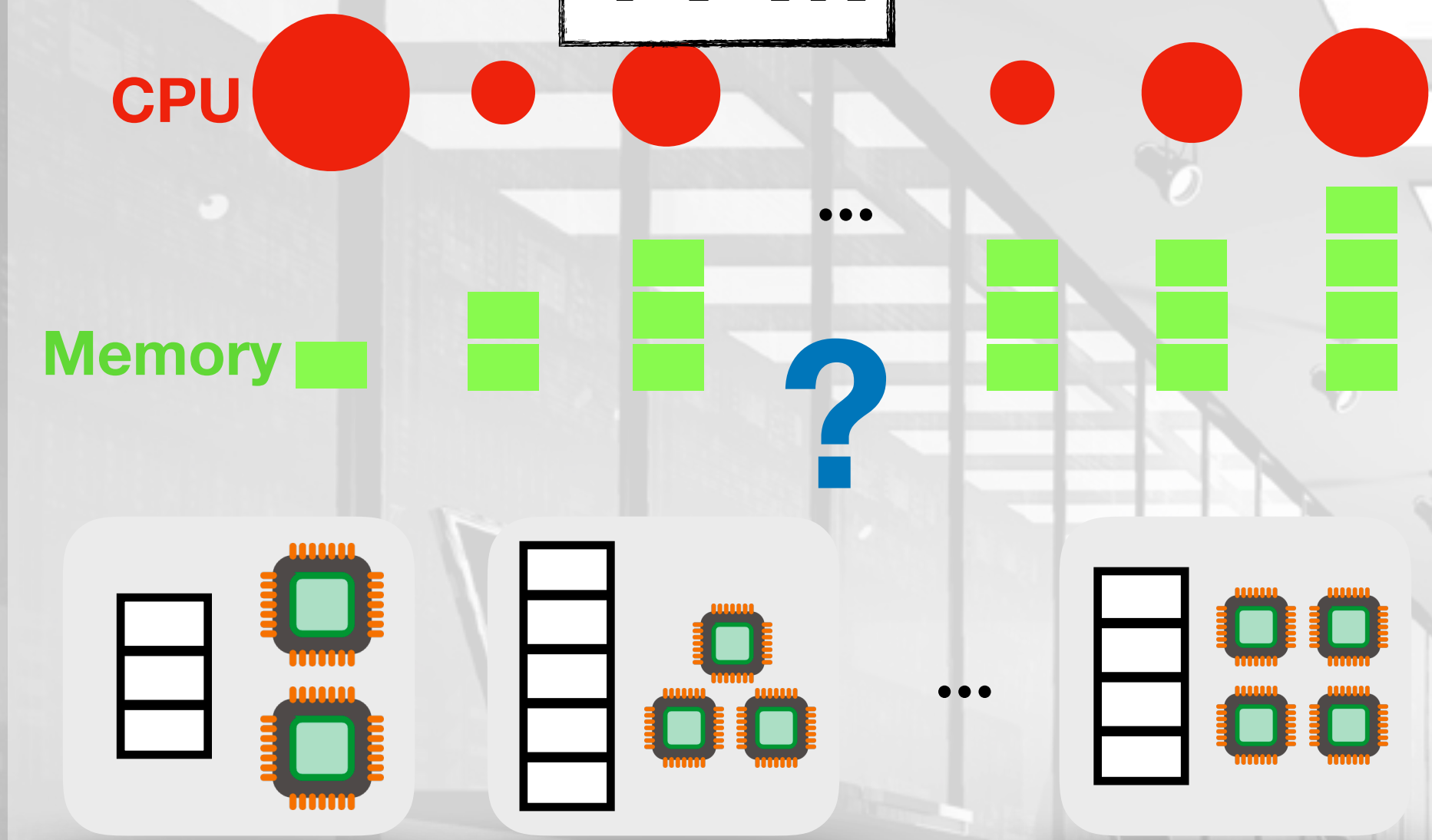
ions

Data Center Resource Management



Data Center Resource Management

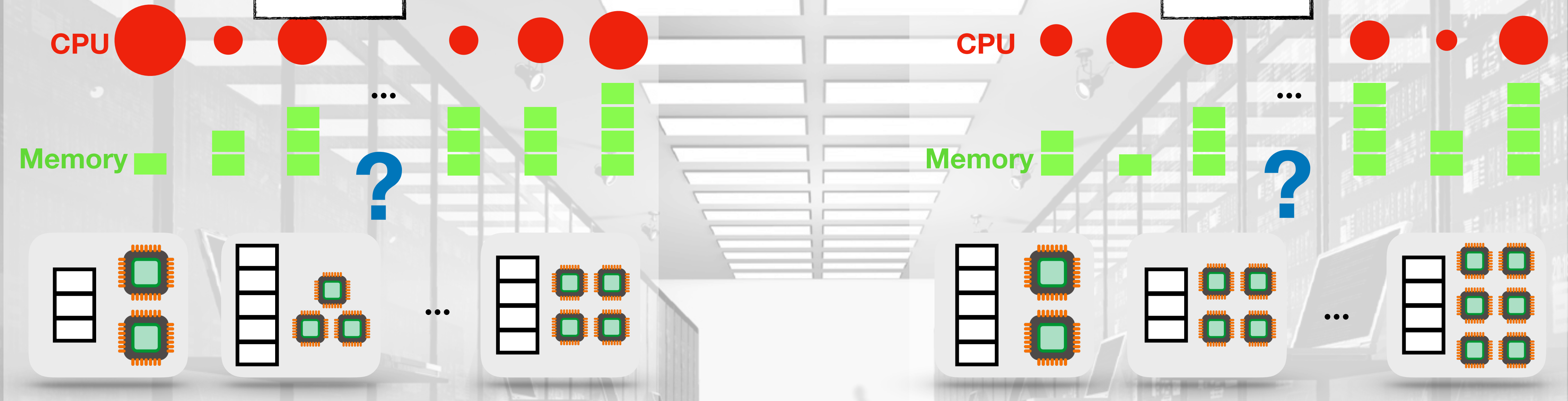
4 PM



Data Center Resource Management

4 PM

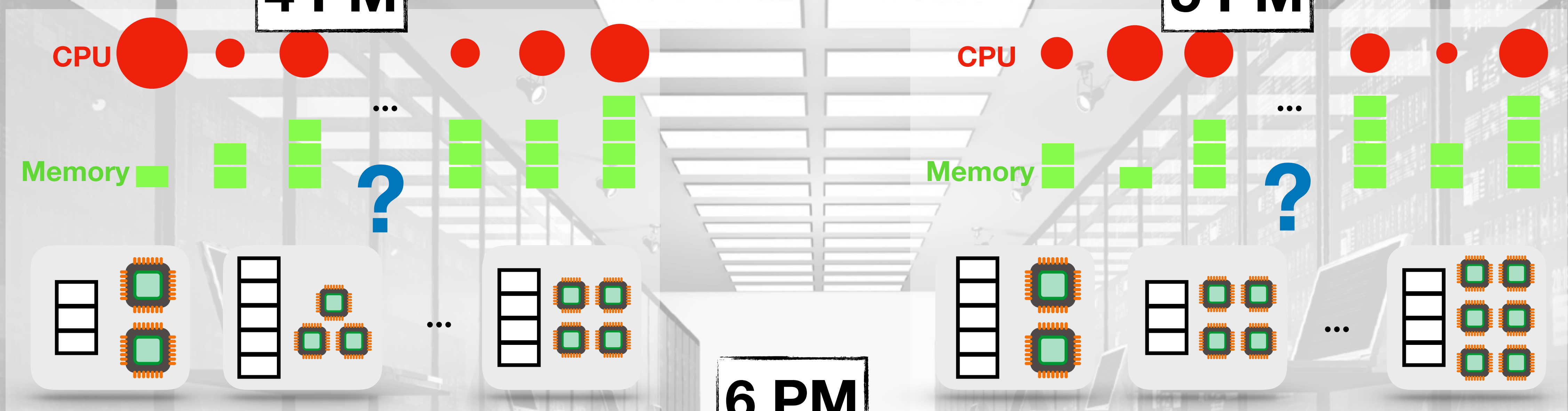
5 PM



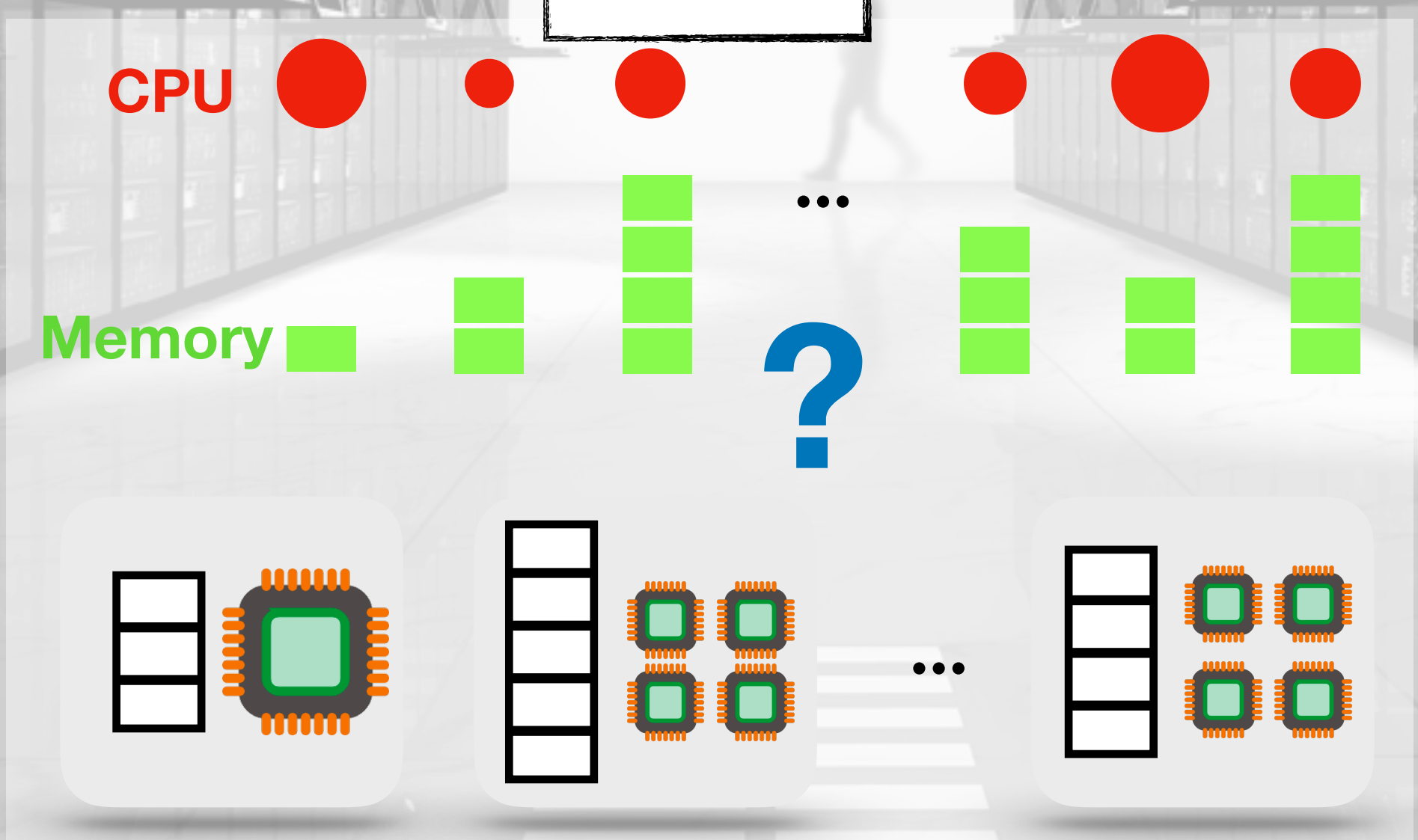
Data Center Resource Management

4 PM

5 PM



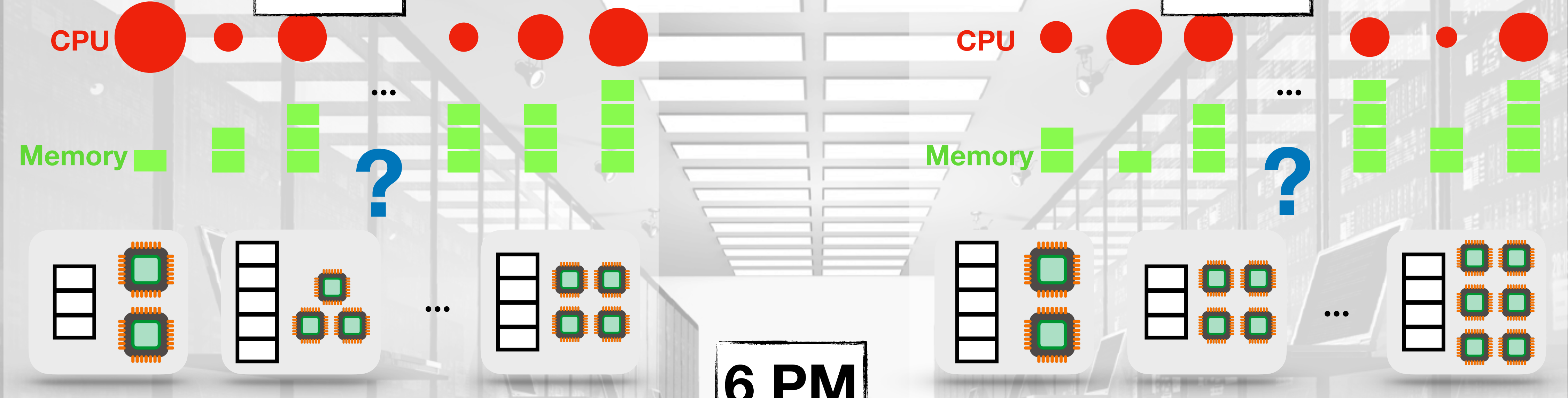
6 PM



Data Center Resource Management

4 PM

5 PM



6 PM

Tackling NP-Hard Problems

Paradigm	Design Rationale

Tackling NP-Hard Problems

Paradigm	Design Rationale
Exhaustive Search	Tight formulations Powerful Branch-and-Bound solvers

Tackling NP-Hard Problems

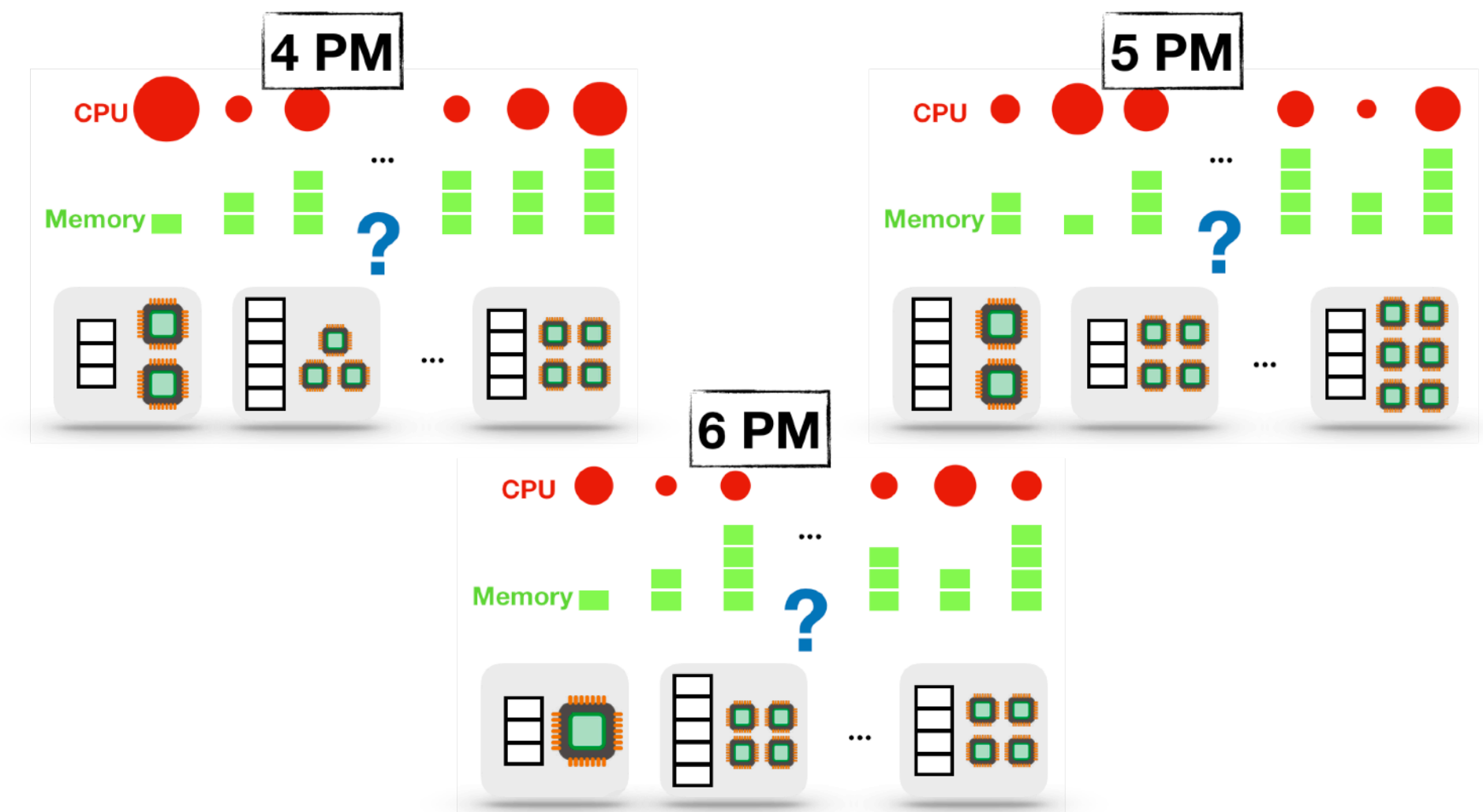
Paradigm	Design Rationale
Exhaustive Search	Tight formulations Powerful Branch-and-Bound solvers
Approximation Algorithms	Good worst-case guarantees

Tackling NP-Hard Problems

Paradigm	Design Rationale
Exhaustive Search	Tight formulations Powerful Branch-and-Bound solvers
Approximation Algorithms	Good worst-case guarantees
Heuristics	Intuition exploiting problem structure Empirical trial-and-error

Tackling NP-Hard Problems

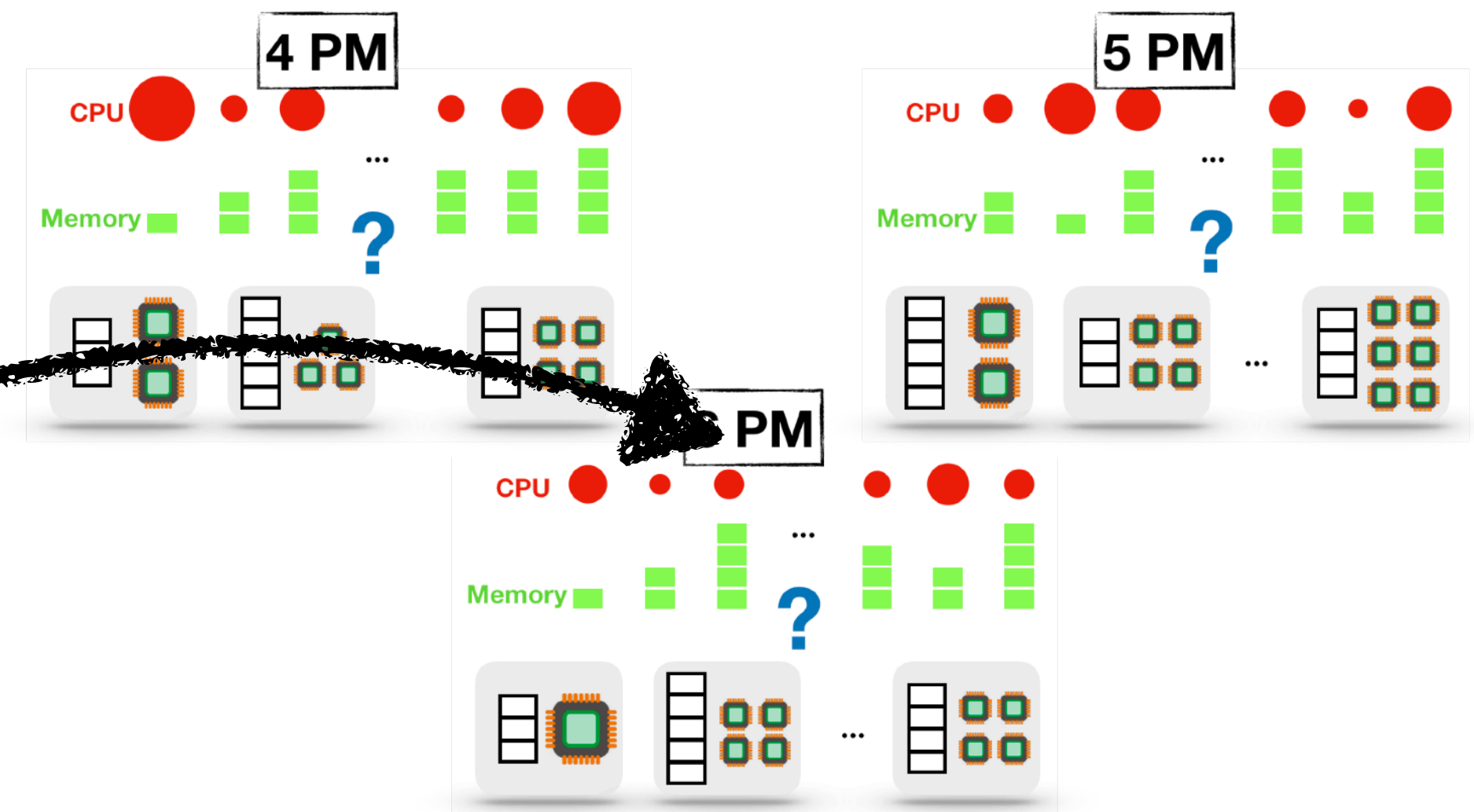
Paradigm	Design Rationale
Exhaustive Search	Tight formulations Powerful Branch-and-Bound solvers
Approximation Algorithms	Good worst-case guarantees
Heuristics	Intuition exploiting problem structure Empirical trial-and-error



Tackling NP-Hard Problems

Paradigm	Design Rationale
Exhaustive Search	Tight formulations Powerful Branch-and-Bound solvers
Approximation Algorithms	Good worst-case guarantees
Heuristics	Intuition exploiting problem structure Empirical trial-and-error

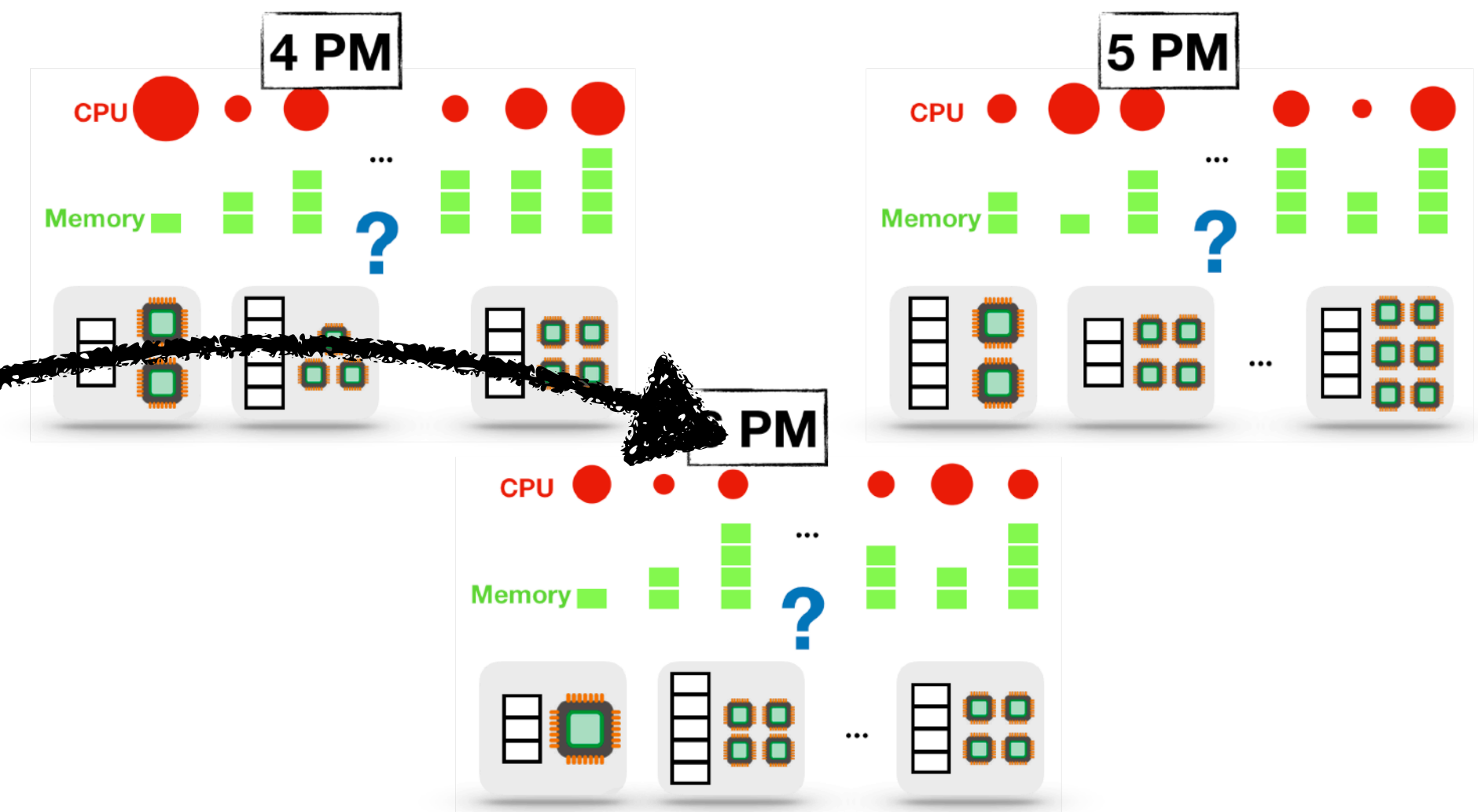
How do you **tailor** the algorithm to **YOUR** instances?



Tackling NP-Hard Problems

Paradigm	Customization via...
Exhaustive Search	Tight formulations Powerful Branch-and-Bound solvers
Approximation Algorithms	Good worst-case guarantees
Heuristics	Intuition exploiting problem structure Empirical trial-and-error

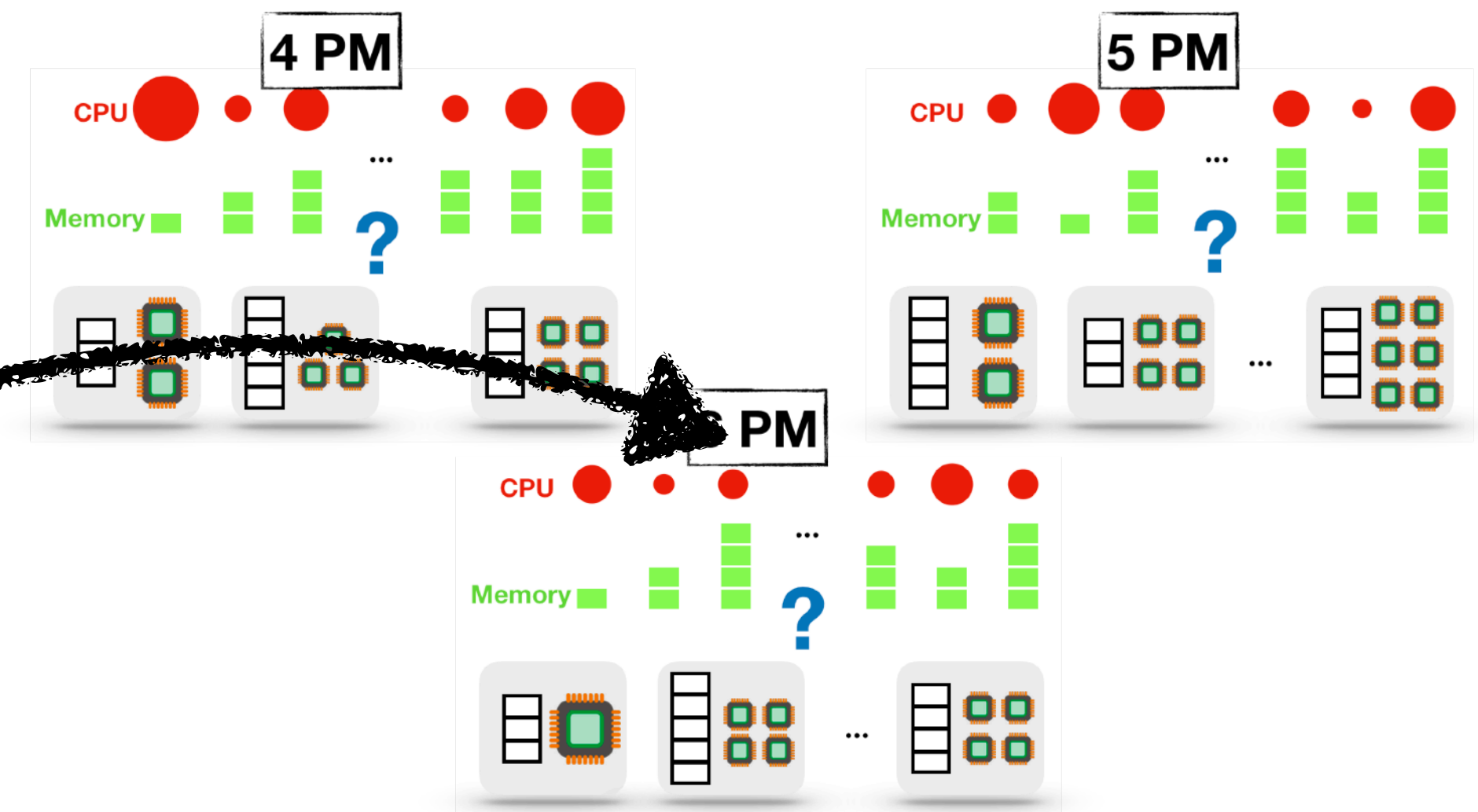
How do you **tailor** the algorithm to **YOUR** instances?



Tackling NP-Hard Problems

Paradigm	Customization via...
Exhaustive Search	Problem-Specific Bounding functions or search rules
Approximation Algorithms	Good worst-case guarantees
Heuristics	Intuition exploiting problem structure Empirical trial-and-error

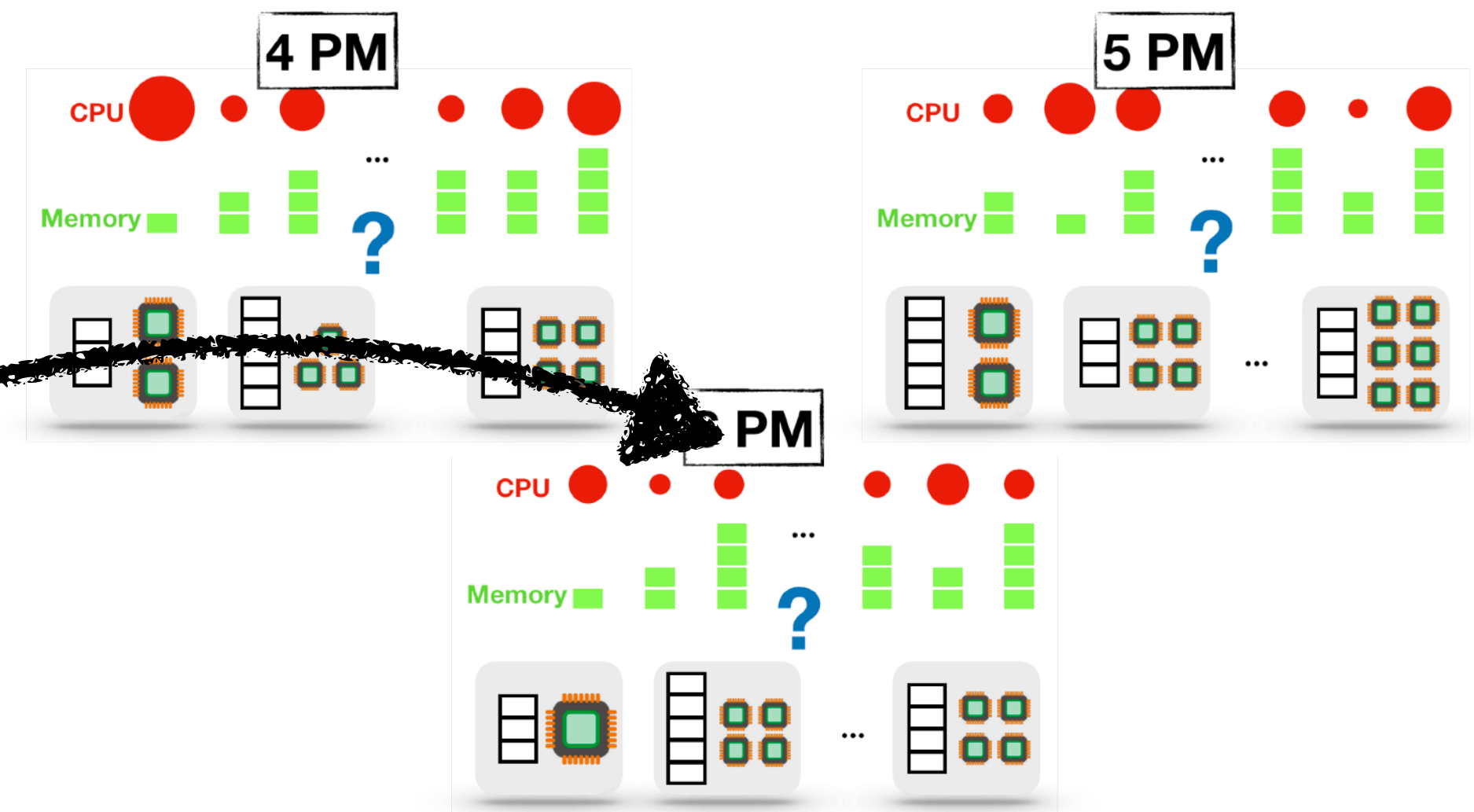
How do you **tailor** the algorithm to **YOUR** instances?



Tackling NP-Hard Problems

Paradigm	Customization via...
Exhaustive Search	Problem-Specific Bounding functions or search rules
Approximation Algorithms	Make explicit assumptions on input distribution and redesign algo.
Heuristics	Intuition exploiting problem structure Empirical trial-and-error

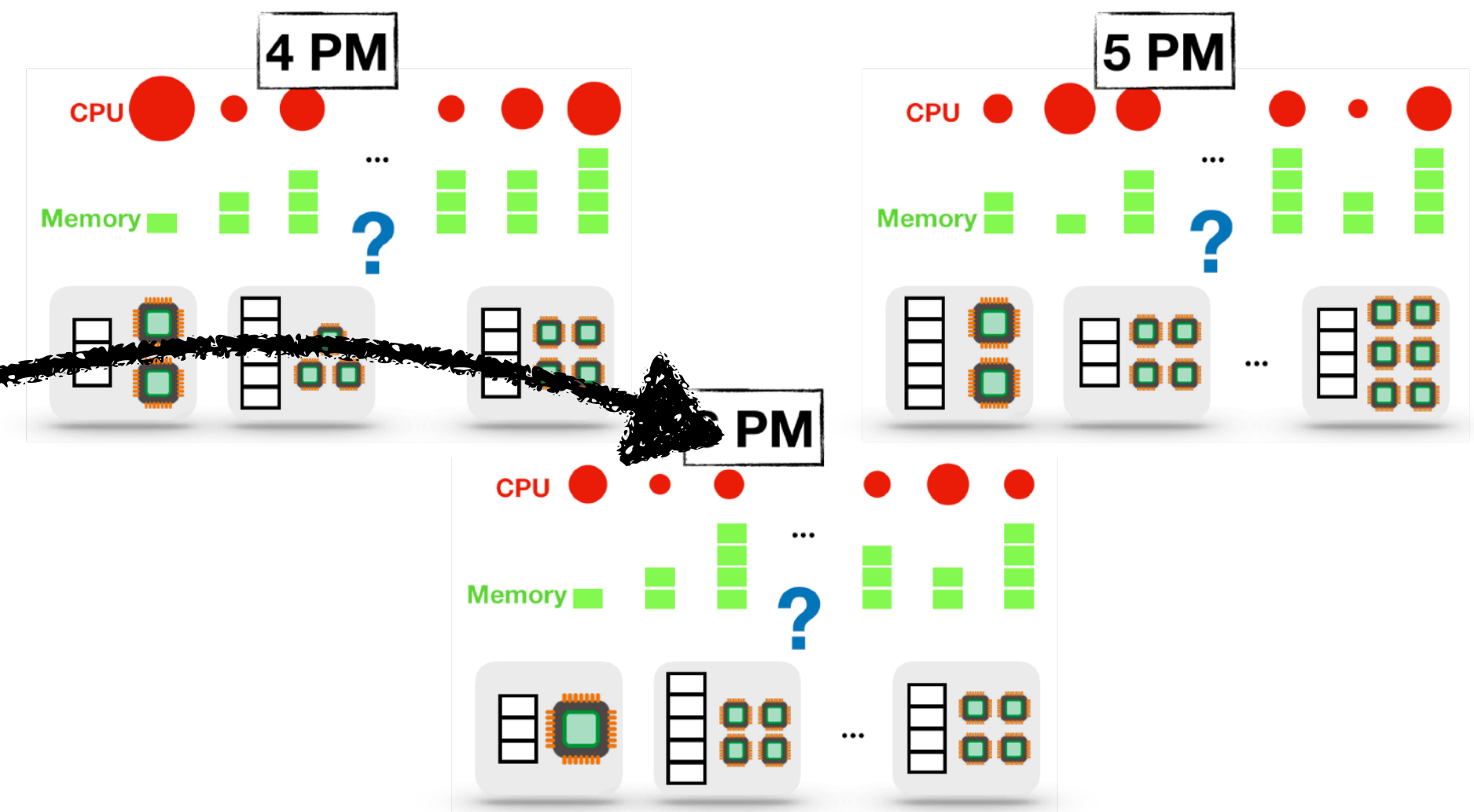
How do you **tailor** the algorithm to **YOUR** instances?



Tackling NP-Hard Problems

Paradigm	Customization via...
Exhaustive Search	Problem-Specific Bounding functions or search rules
Approximation Algorithms	Make explicit assumptions on input distribution and redesign algo.
Heuristics	Analyze algorithm behavior on your inputs; look for patterns to exploit

How do you **tailor** the algorithm to **YOUR** instances?



Tackling NP-Hard Problems

Paradigm

Customization via...

ANSWER:

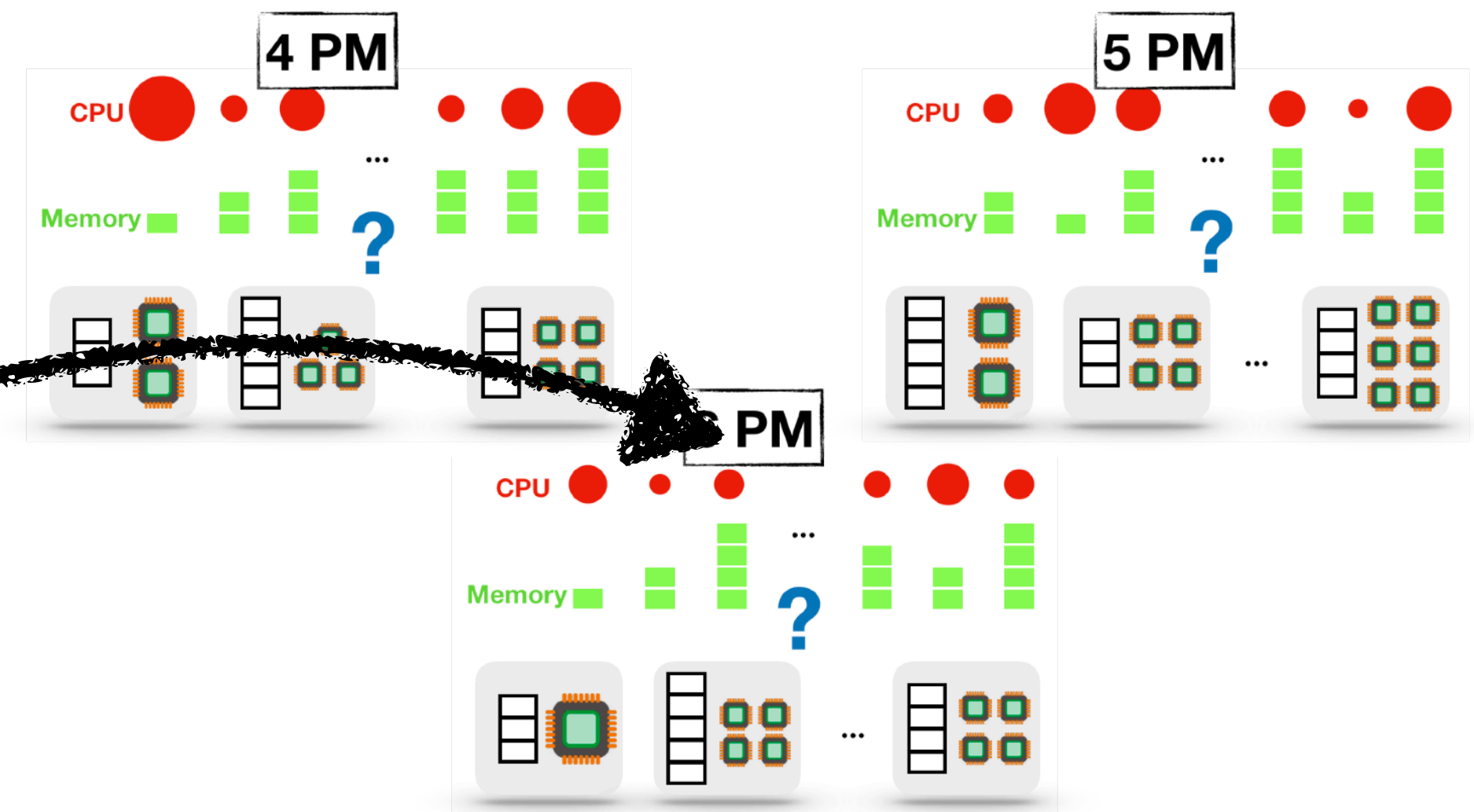
Manual intellectual/
experimental **effort** required

Problem-Specific Bounding
functions or **search rules**

Make explicit **assumptions** on input
distribution and **redesign algo.**

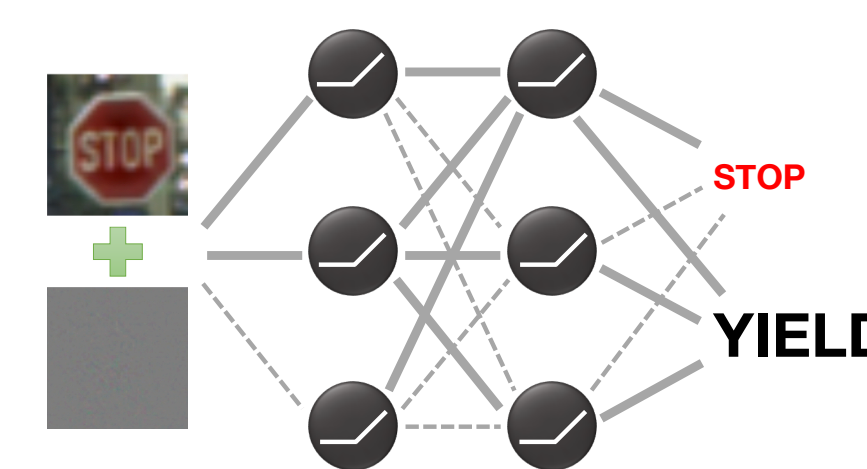
Analyze algorithm **behavior** on your
inputs; look for **patterns** to exploit

How do you **tailor** the
algorithm to **YOUR**
instances?



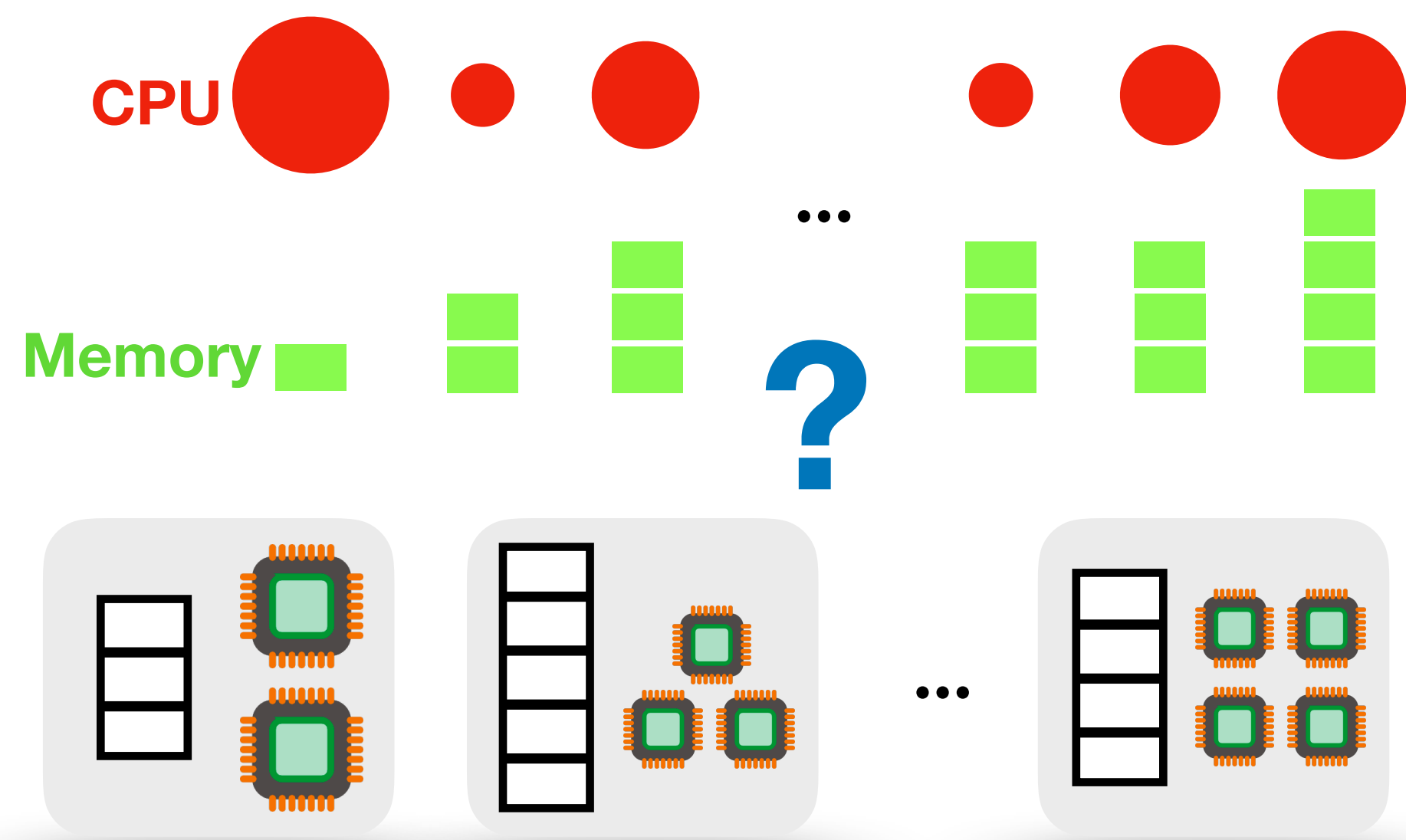
Opportunity

Adversarial ML

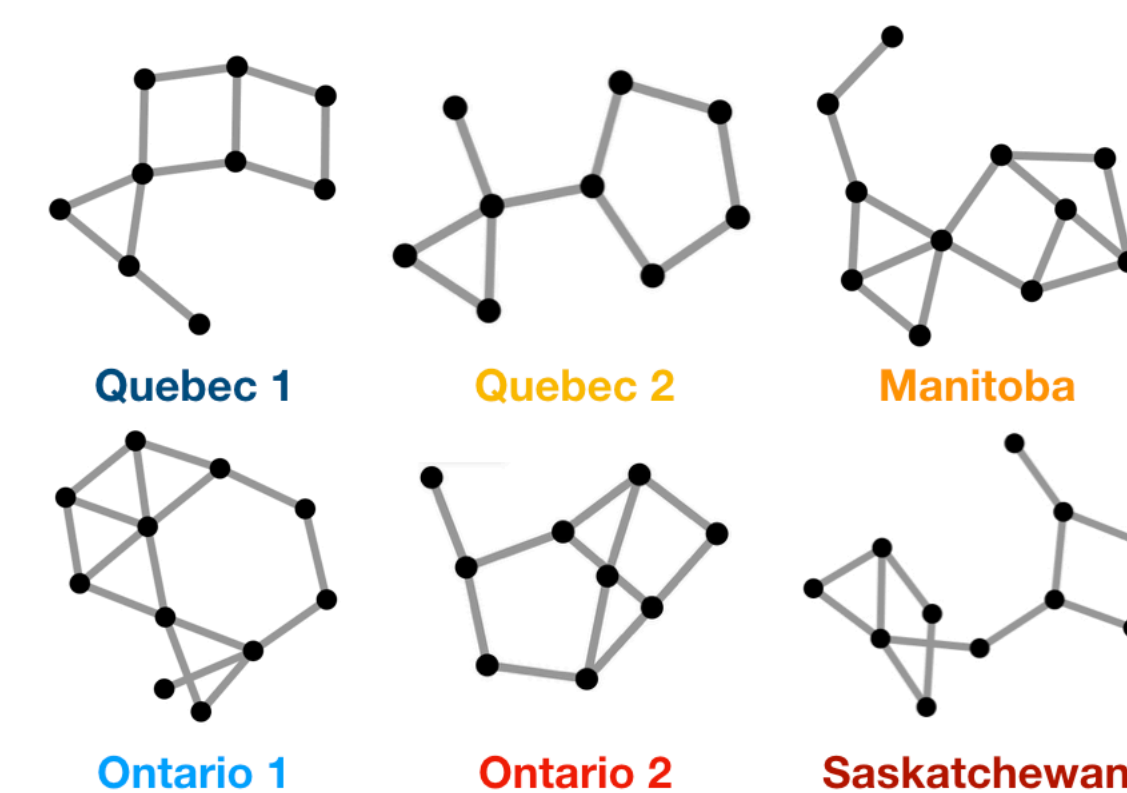
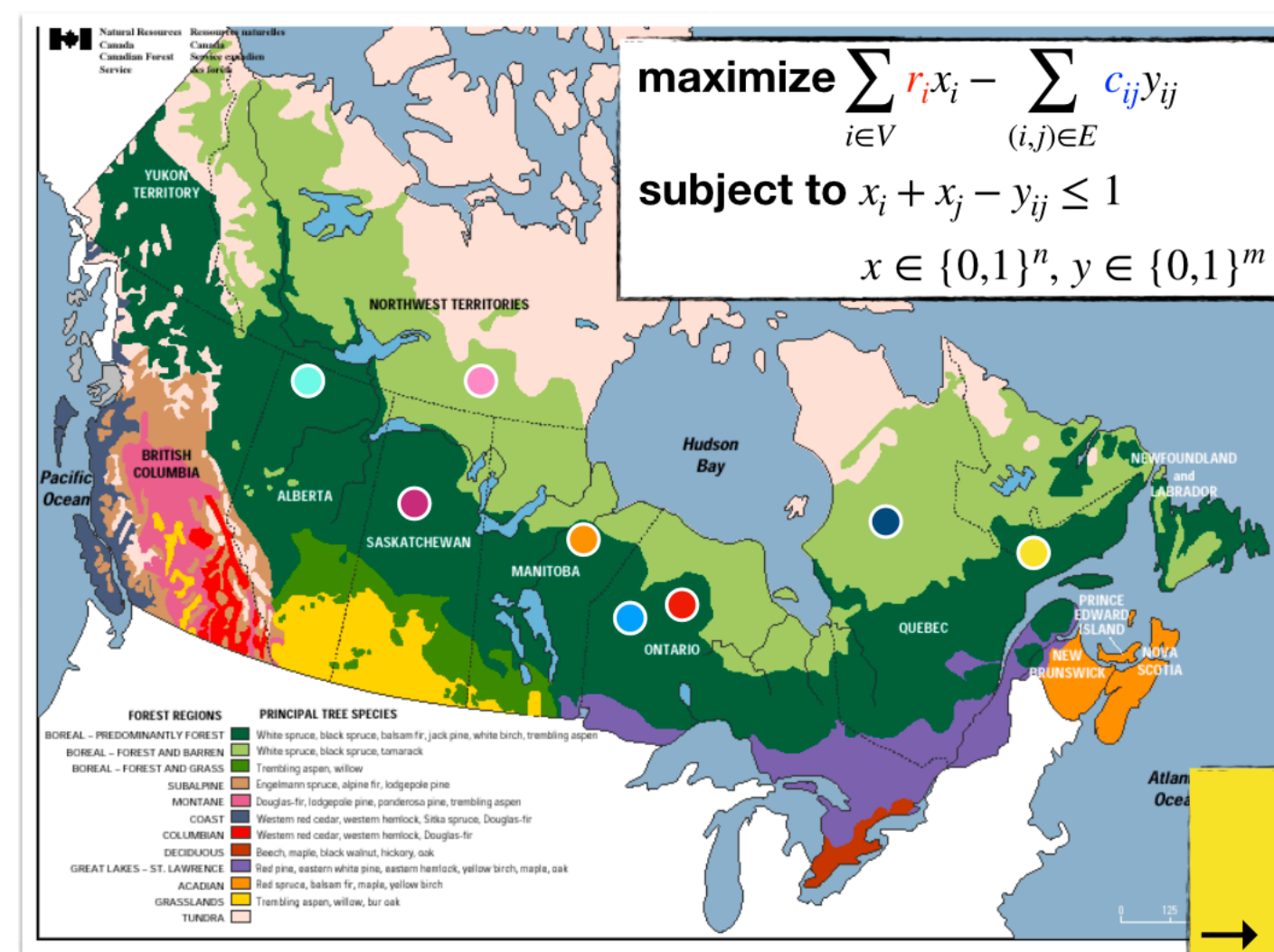


Automatically tailor algorithms to a family of instances

Data Center Resource Management



Forest Harvesting



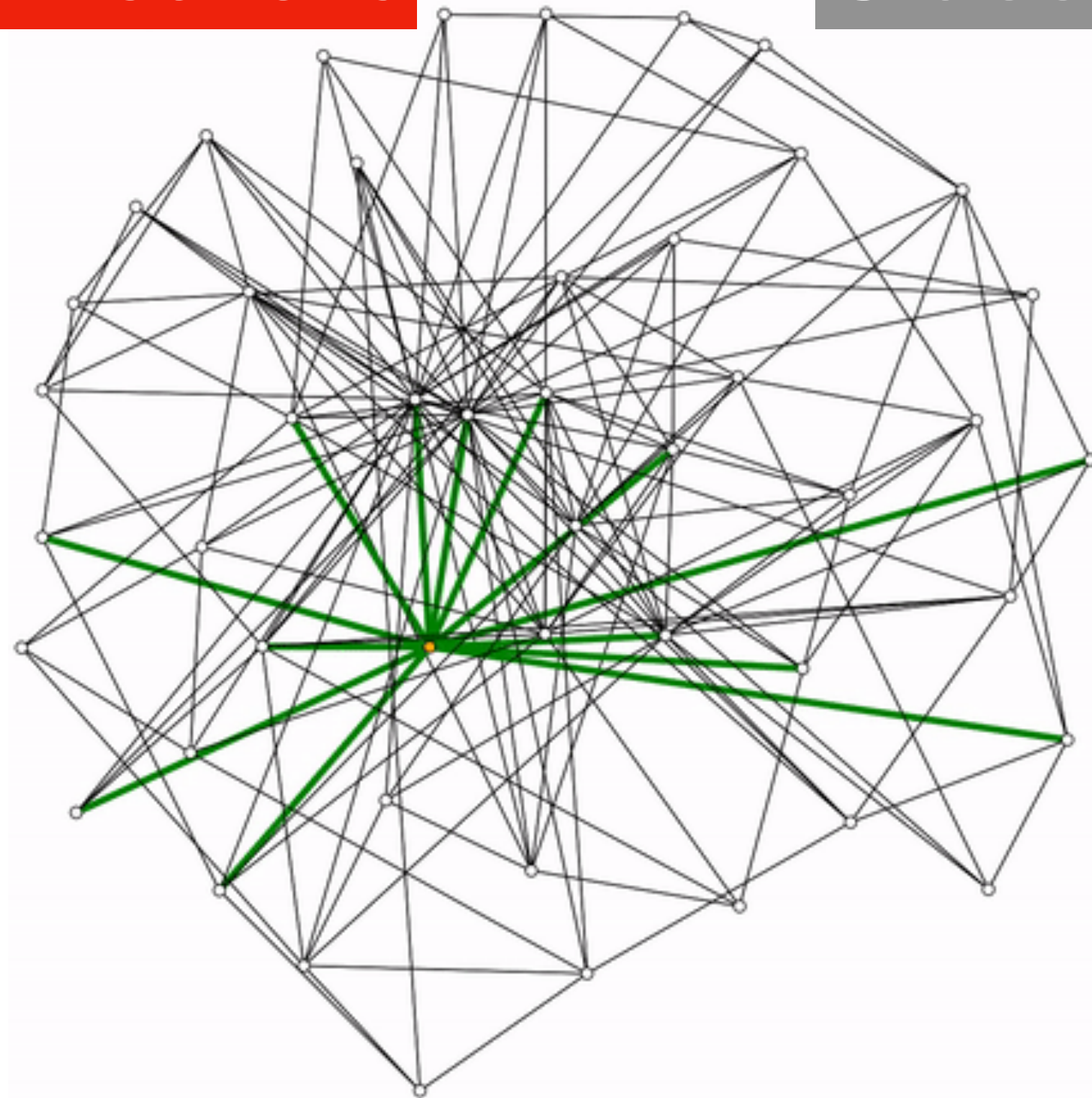
Revenue varies over time
→ Different instances, same problem

Data-Driven Algorithm Design

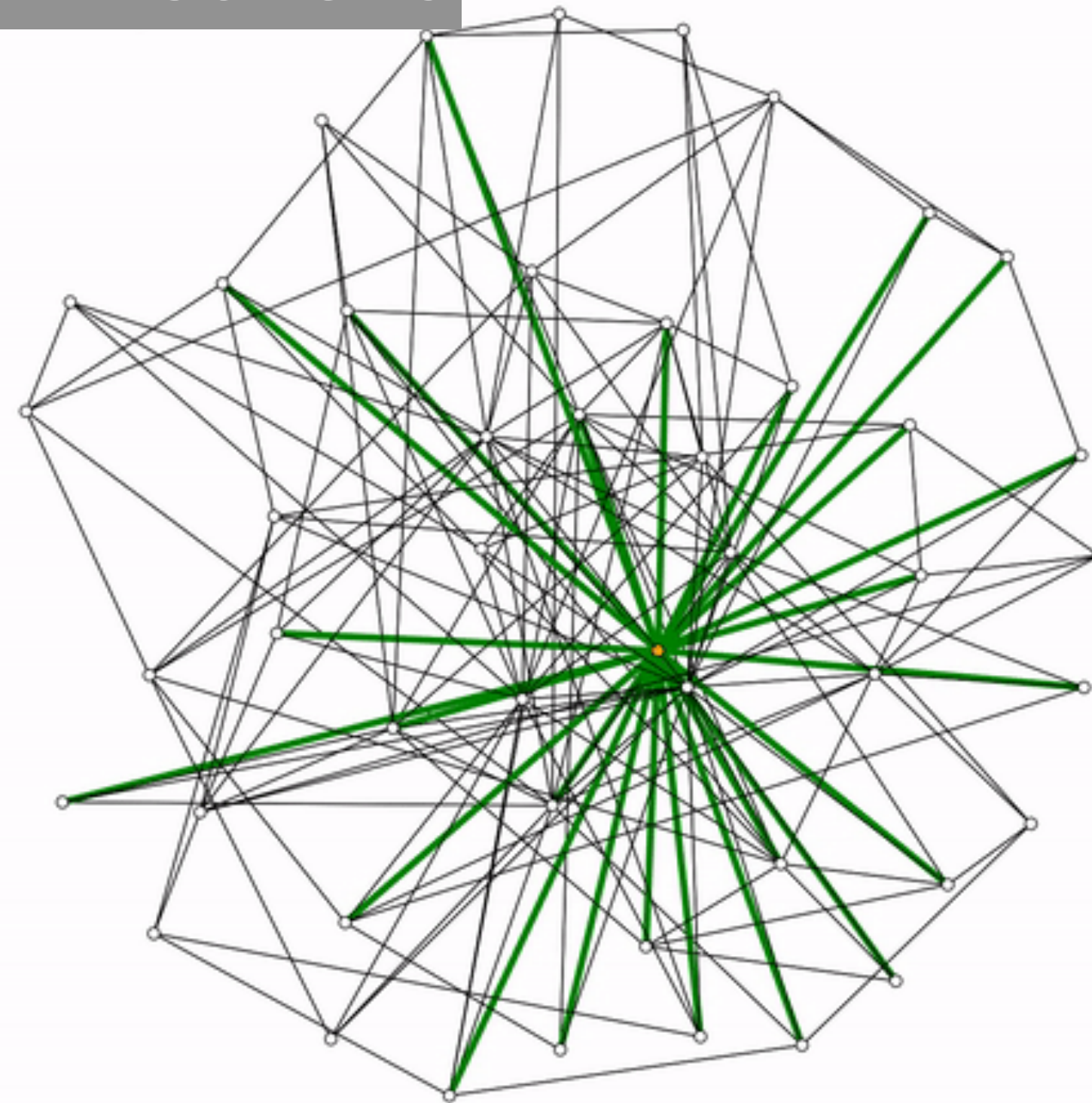
automatically **discovers**

novel search **strategies**

Learned Heuristic



Classical Heuristic



**Minimum
Vertex Cover**

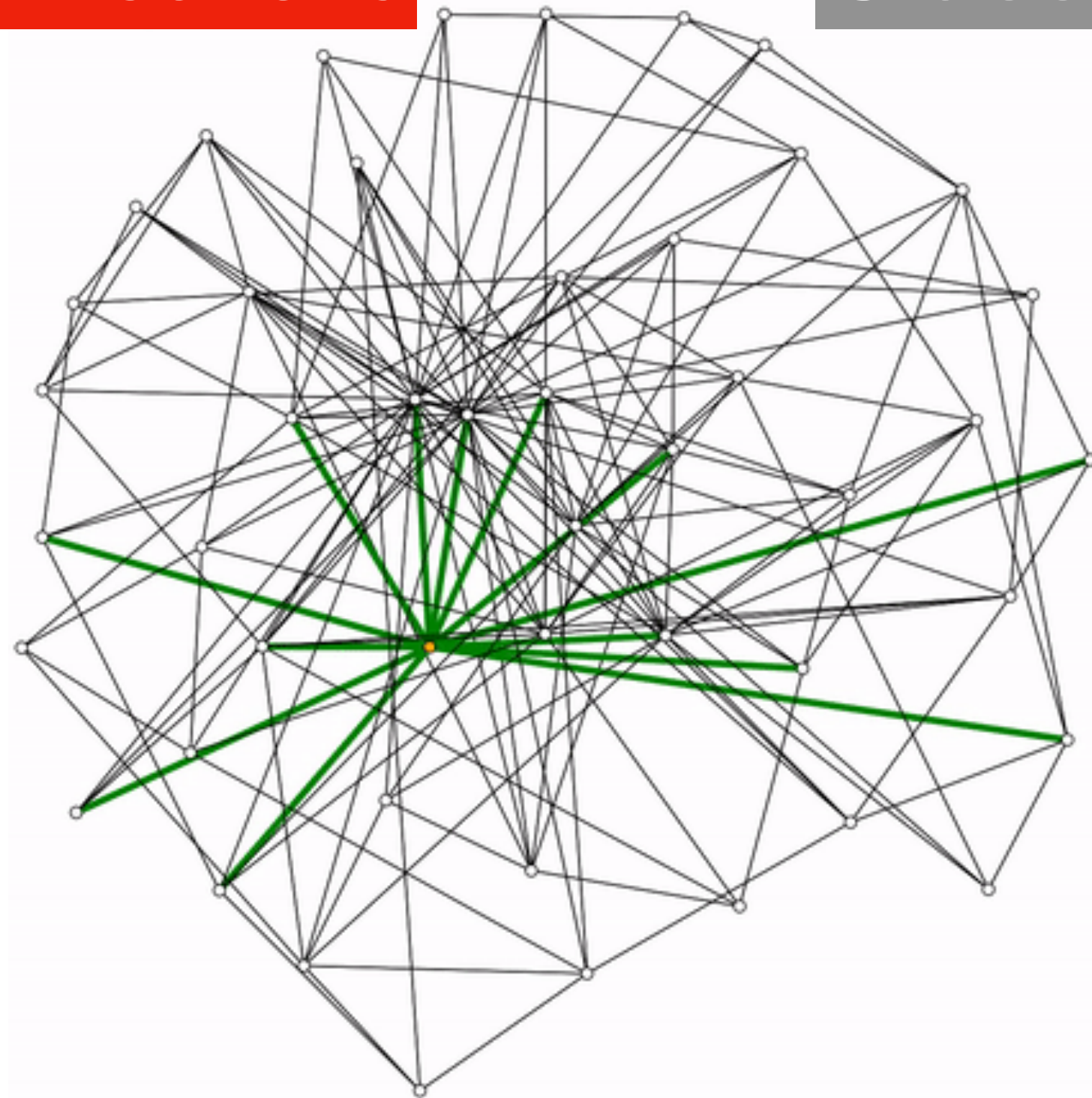
Find **smallest
vertex subset**
such that each
edge is covered

Data-Driven Algorithm Design

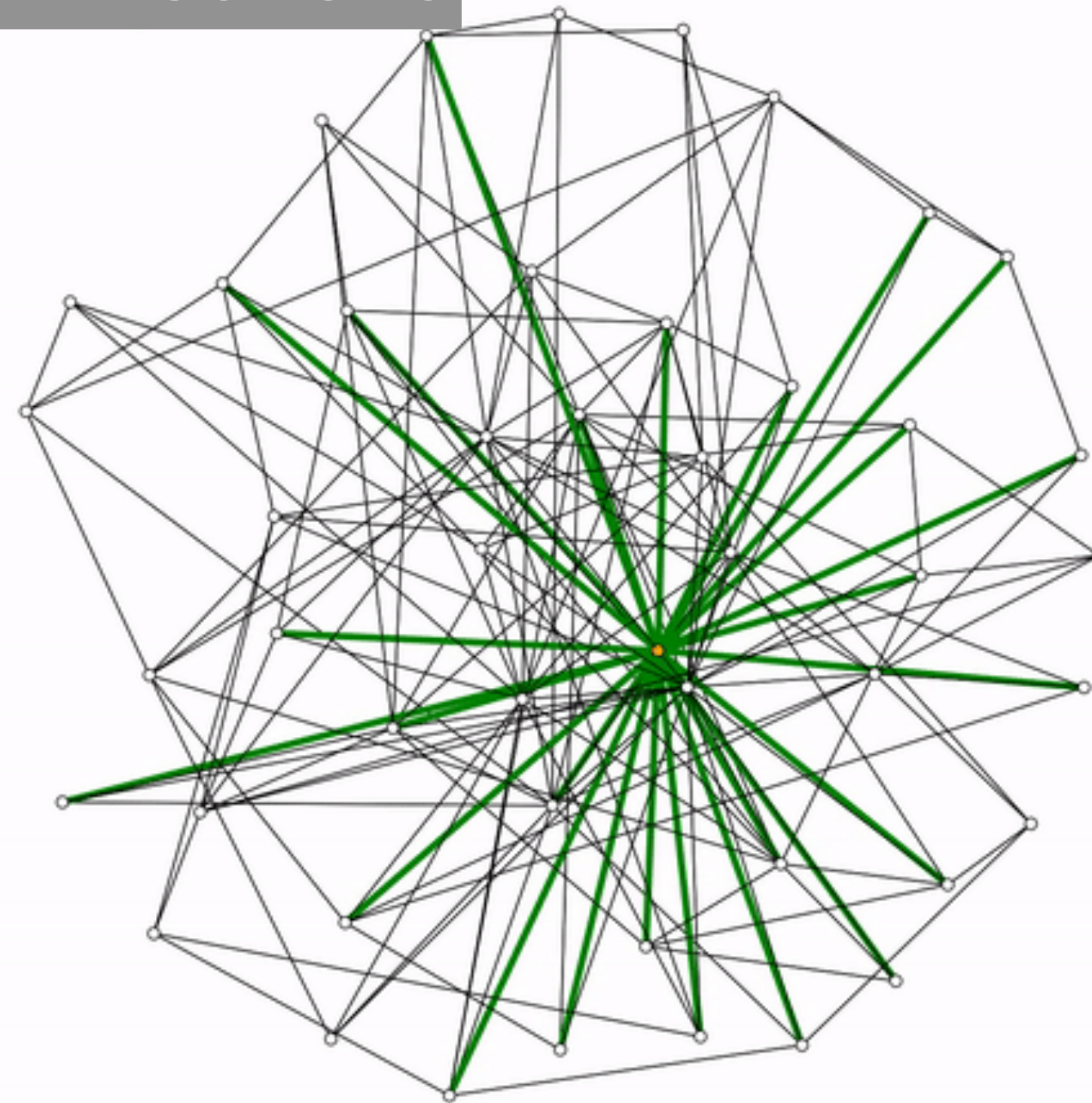
automatically **discovers**

novel search **strategies**

Learned Heuristic



Classical Heuristic



**Minimum
Vertex Cover**

Find **smallest
vertex subset**
such that each
edge is covered

Data-Driven Algorithm Design

ML Paradigm

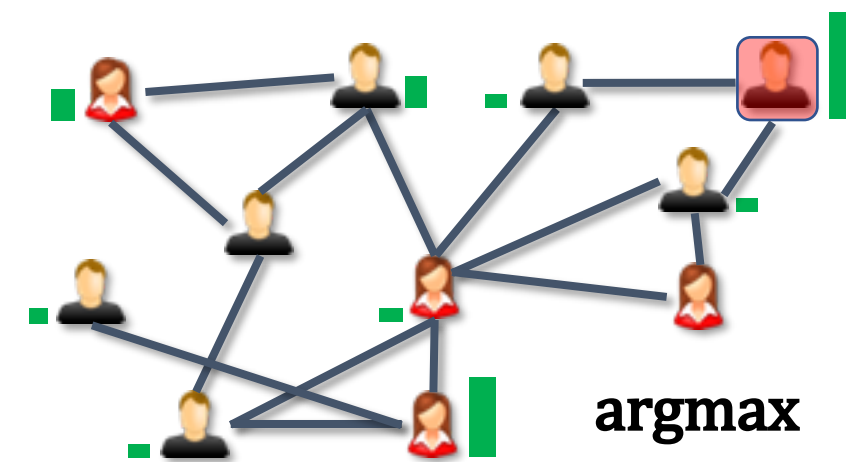
Self-Supervised Learning ■

Reinforcement Learning ■

Supervised Learning ■

NeurIPS-17

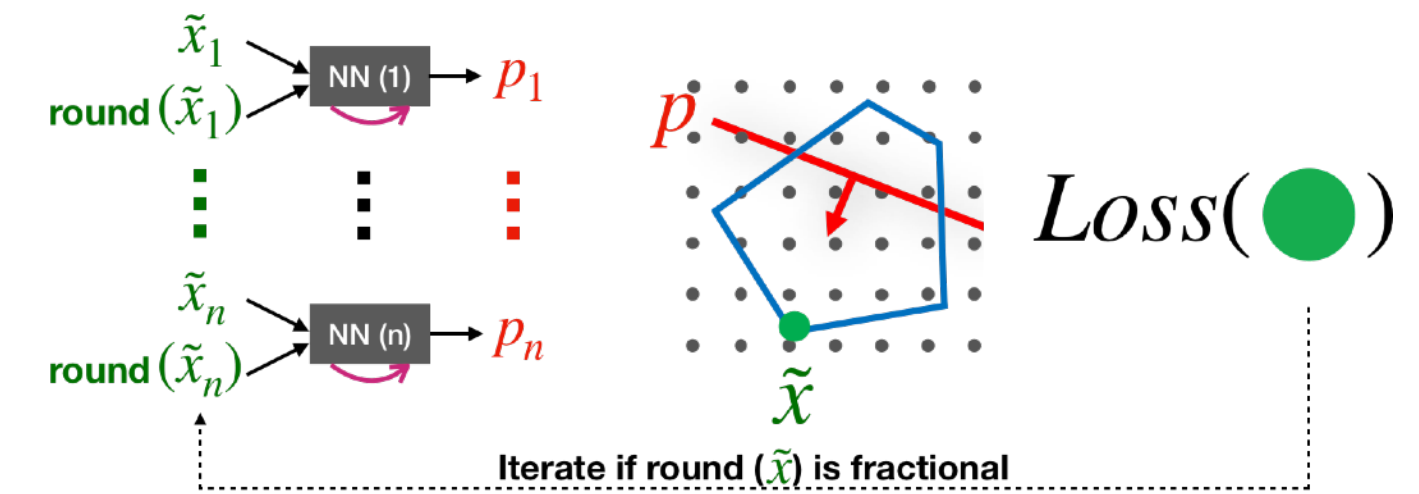
Greedy Heuristic



Graph Optimization

NeurIPS-19, hopefully?

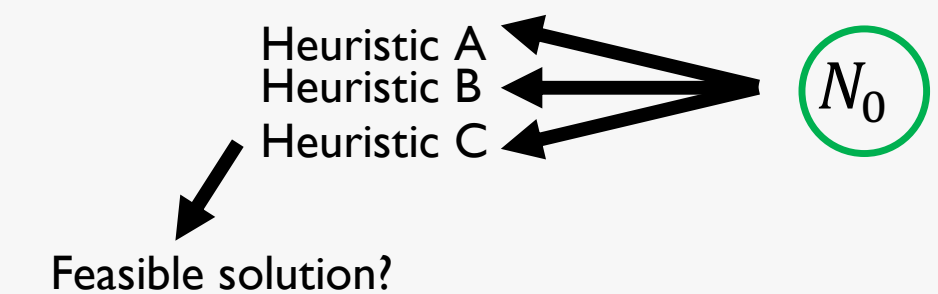
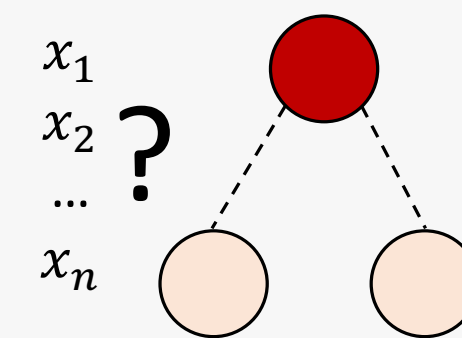
General Integer Programming Heuristic



AAAI-16 **Exact Solving** IJCAI-17

Branching

Heuristic Selection



Integer Programming

Problem Type

Branch & Bound for Integer Optimization

Land & Doig, 1960

LP-based $\min_x c^T x$ **s.t.** $Ax \leq b, x \in \{0,1\}^n$

Repeat:

- 1 Select Node**
- 2 Solve LP Relaxation**
- 3 Prune?**
- 4 Add Cuts**
- 5 Run Heuristics**
- 6 Branch**

Branch & Bound for Integer Optimization

Land & Doig, 1960

LP-based $\min_x c^T x$ **s.t.** $Ax \leq b, x \in \{0,1\}^n$

Repeat:

- 1 Select Node**
- 2 Solve LP Relaxation
- 3 Prune?
- 4 Add Cuts
- 5 Run Heuristics
- 6 Branch

N_0

Branch & Bound for Integer Optimization

Land & Doig, 1960

LP-based

$$\min_x c^T x \text{ s.t. } Ax \leq b, x \in \{0,1\}^n$$

$[0,1]^n$

Repeat:

- 1 **Select Node**
- 2 **Solve LP Relaxation**
- 3 **Prune?**
- 4 **Add Cuts**
- 5 **Run Heuristics**
- 6 **Branch**

N_0

→ Solve LP Relaxation
→ Lower Bound on OPT

Branch & Bound for Integer Optimization

Land & Doig, 1960

LP-based

$$\min_x c^T x \text{ s.t. } Ax \leq b, x \in \begin{matrix} \{0,1\}^n \\ [0,1]^n \end{matrix}$$

Repeat:

- 1 Select Node**
- 2 Solve LP Relaxation**
- 3 Prune?**
- 4 Add Cuts**
- 5 Run Heuristics**
- 6 Branch**

N_0

Solve LP Relaxation
→ Lower Bound on OPT

worse than best solution?
Prune!

Branch & Bound for Integer Optimization

Land & Doig, 1960

LP-based $\min_x c^T x$ **s.t.** $Ax \leq b, x \in \{0,1\}^n$

Repeat:

- 1 Select Node**
- 2 Solve LP Relaxation
- 3 Prune?
- 4 Add Cuts**
- 5 Run Heuristics
- 6 Branch

N_0

Add Cuts:
Tightening Constraints

Branch & Bound for Integer Optimization

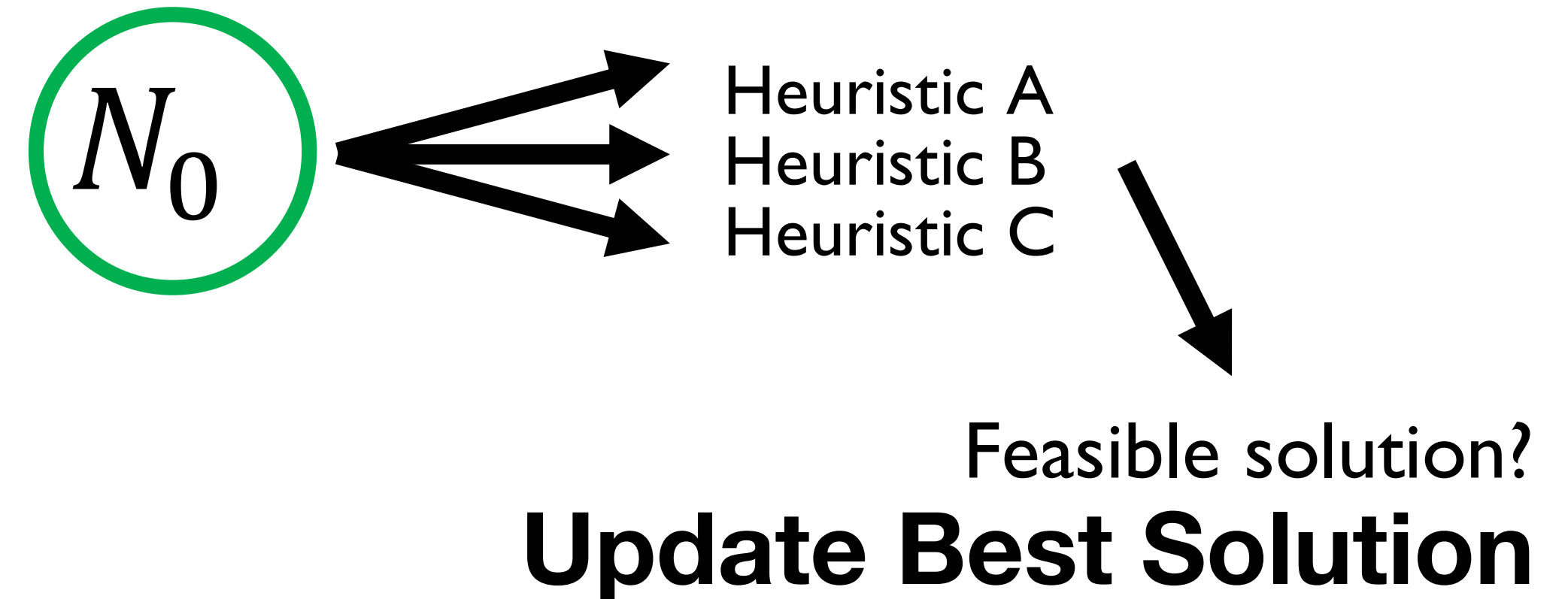
LP-based

$$\min_x c^T x \text{ s.t. } Ax \leq b, x \in \{0,1\}^n$$

Land & Doig, 1960

Repeat:

- 1 Select Node**
- 2 Solve LP Relaxation
- 3 Prune?
- 4 Add Cuts
- 5 Run Heuristics**
- 6 Branch



Branch & Bound for Integer Optimization

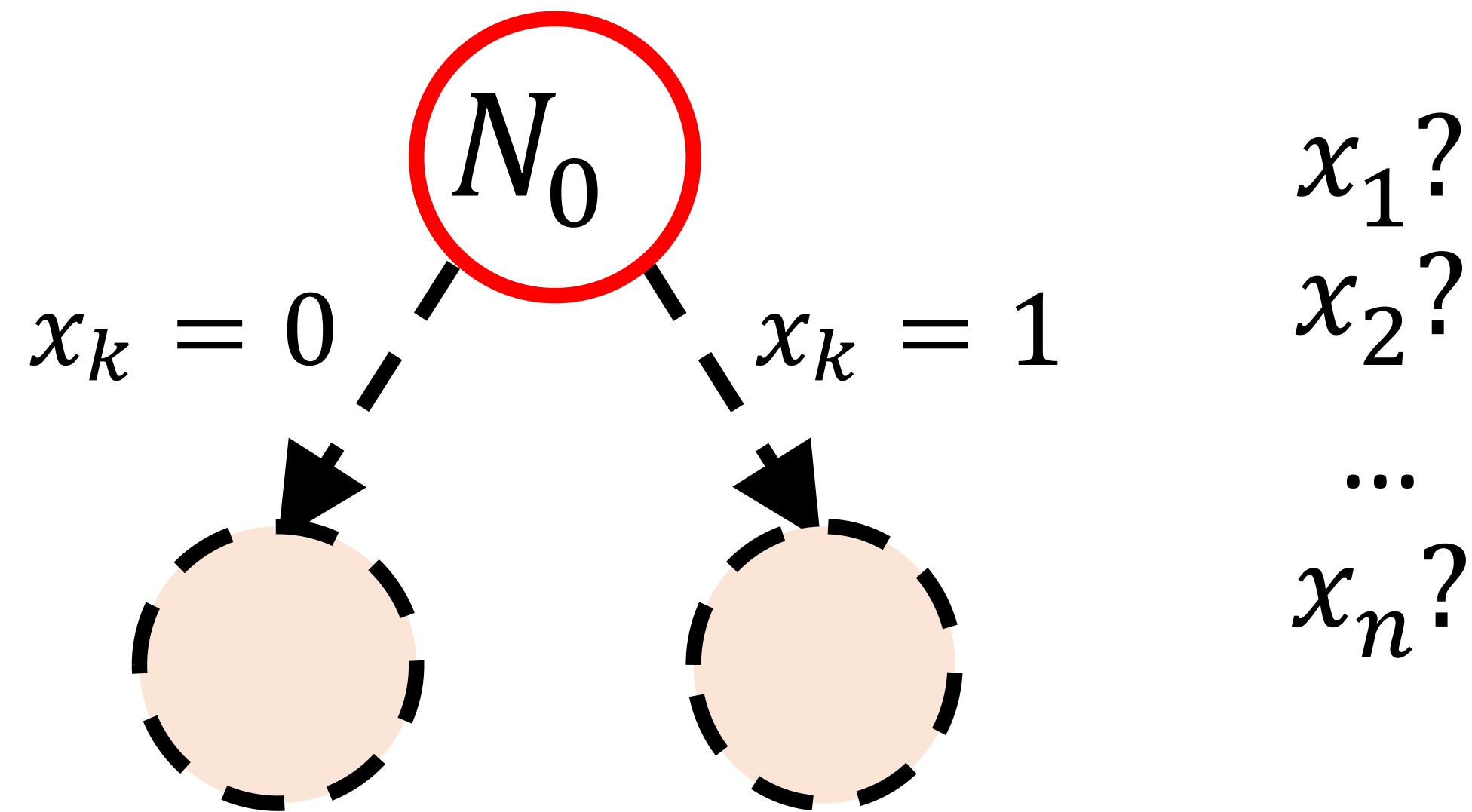
Land & Doig, 1960

LP-based

$$\min_x c^T x \text{ s.t. } Ax \leq b, x \in \{0,1\}^n$$

Repeat:

- 1 **Select Node**
- 2 **Solve LP Relaxation**
- 3 **Prune?**
- 4 **Add Cuts**
- 5 **Run Heuristics**
- 6 **Branch**



Branch & Bound for Integer Optimization

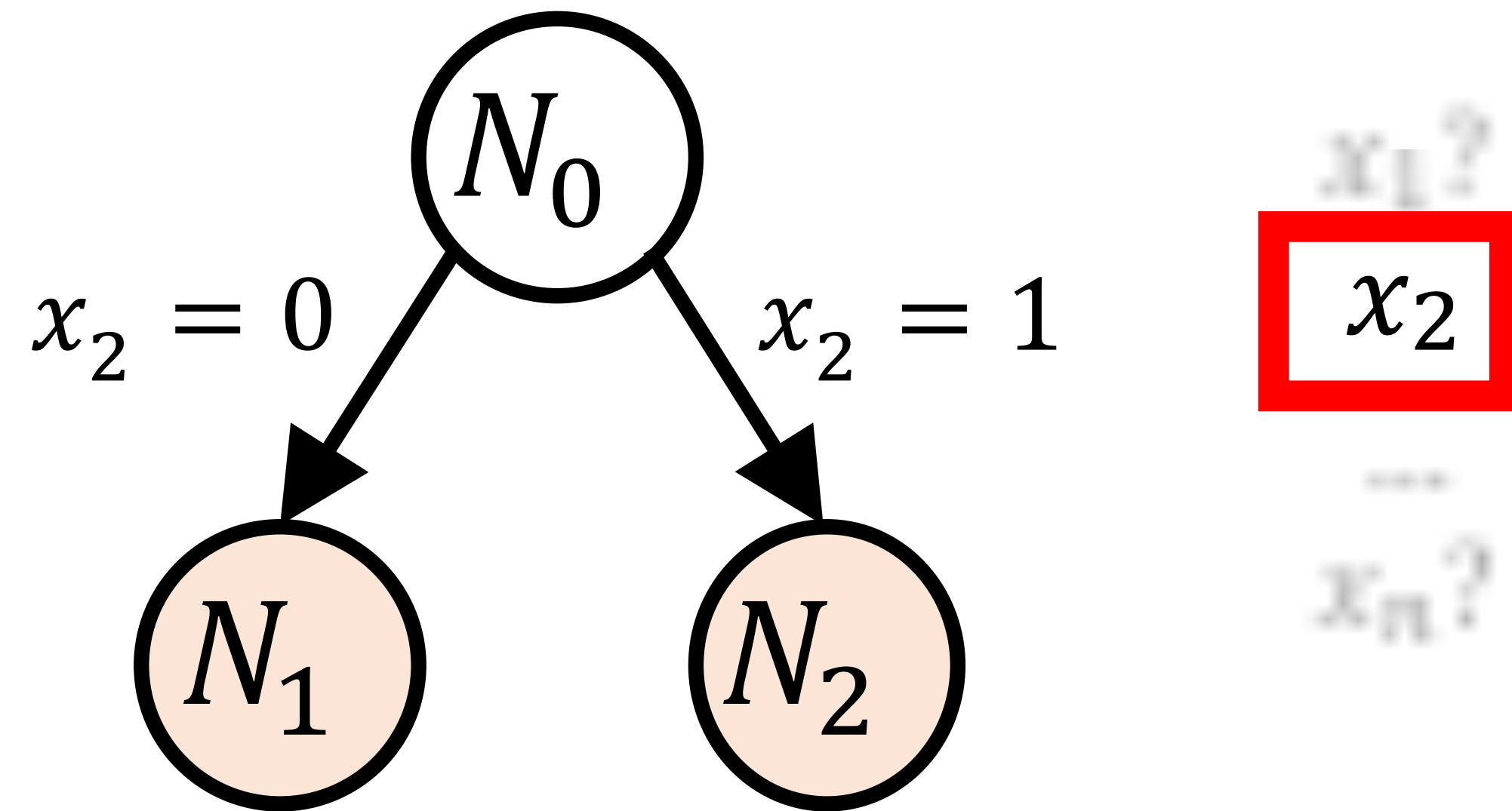
Land & Doig, 1960

LP-based

$$\min_x c^T x \text{ s.t. } Ax \leq b, x \in \{0,1\}^n$$

Repeat:

- 1 **Select Node**
- 2 **Solve LP Relaxation**
- 3 **Prune?**
- 4 **Add Cuts**
- 5 **Run Heuristics**
- 6 **Branch**



Branch & Bound for Integer Optimization

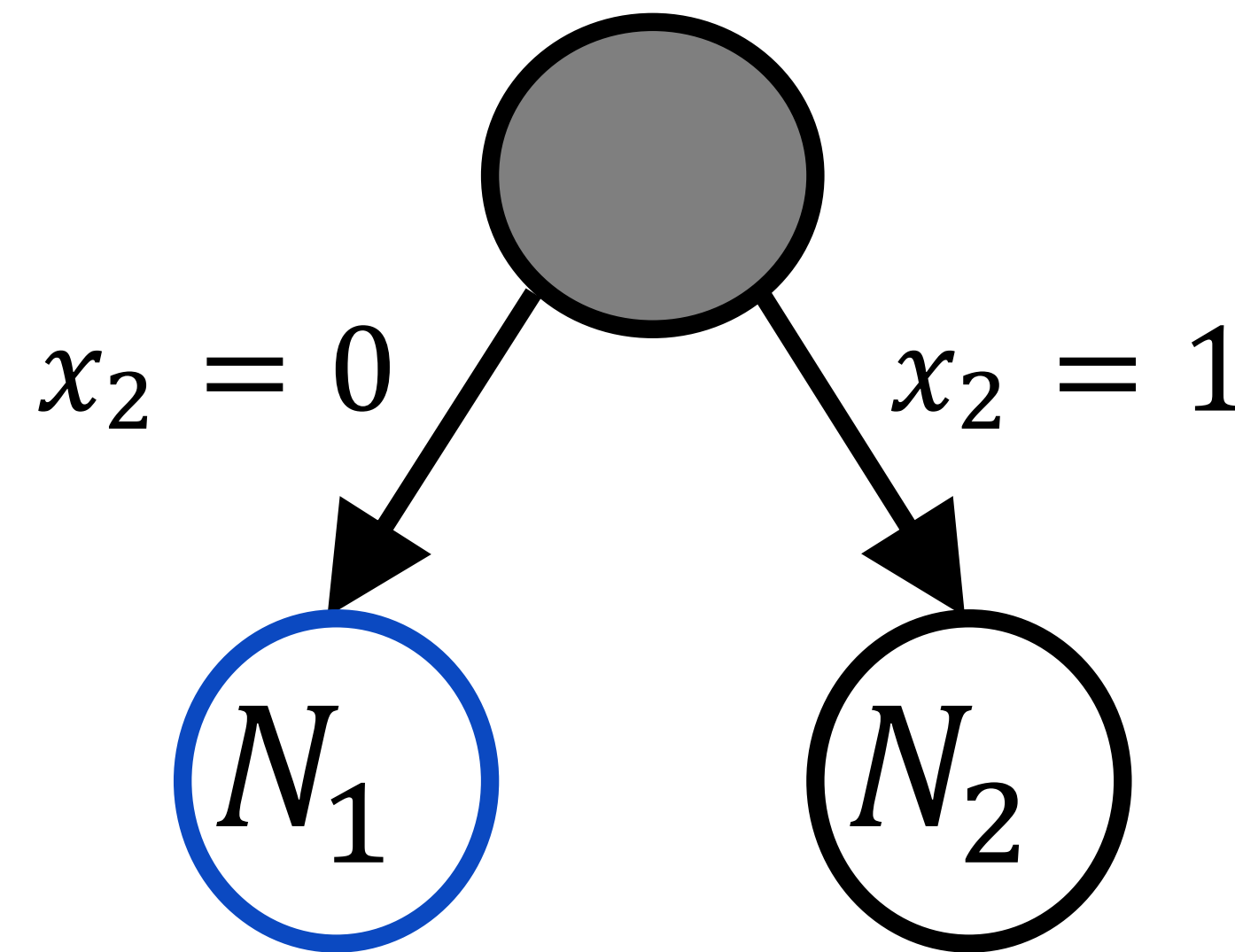
LP-based

$$\min_x c^T x \text{ s.t. } Ax \leq b, x \in \{0,1\}^n$$

Land & Doig, 1960

Repeat:

- 1 Select Node**
- 2 Solve LP Relaxation
- 3 Prune?
- 4 Add Cuts
- 5 Run Heuristics
- 6 Branch



Branch & Bound for Integer Optimization

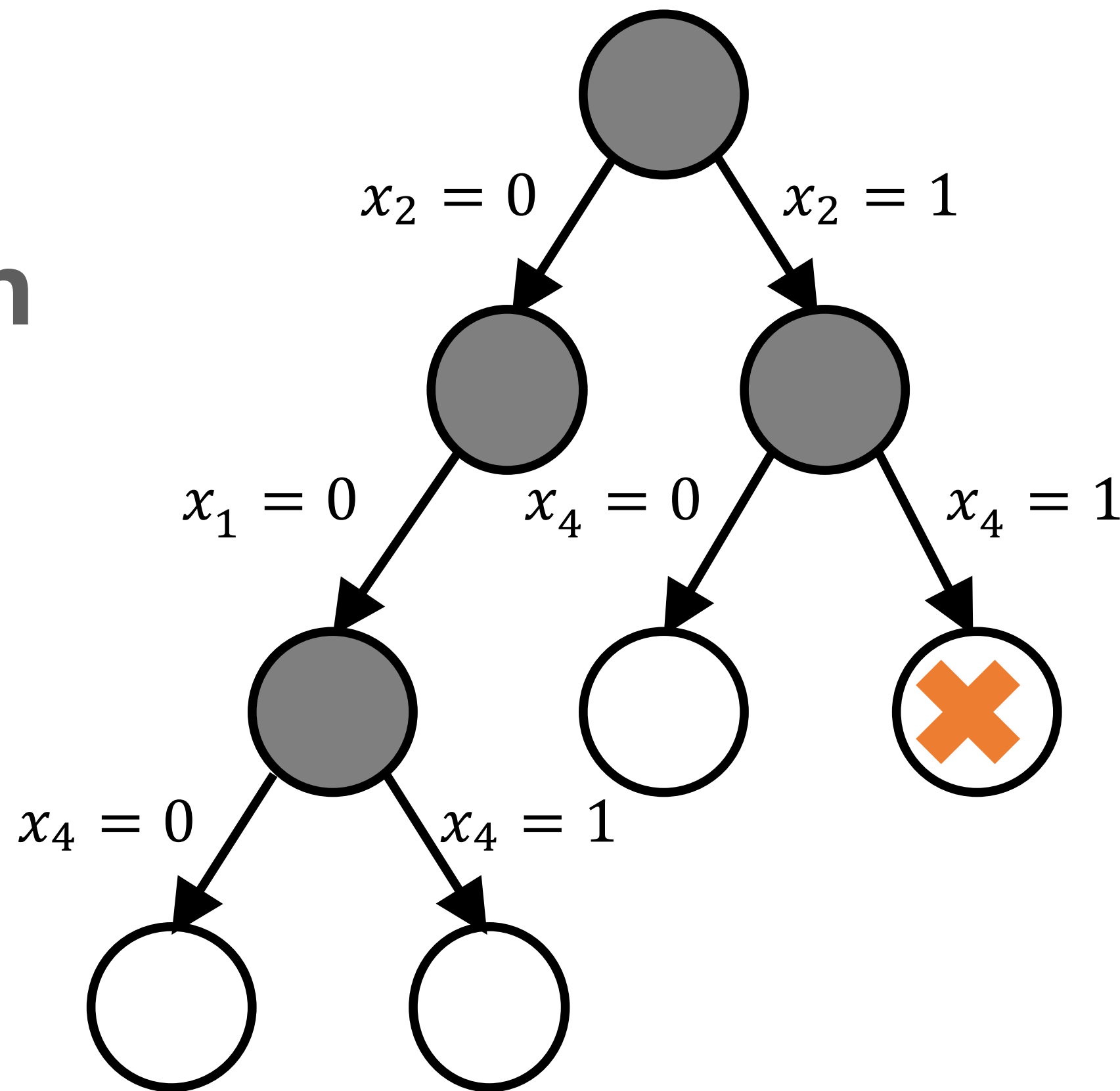
LP-based

$$\min_x c^T x \text{ s.t. } Ax \leq b, x \in \{0,1\}^n$$

Land & Doig, 1960

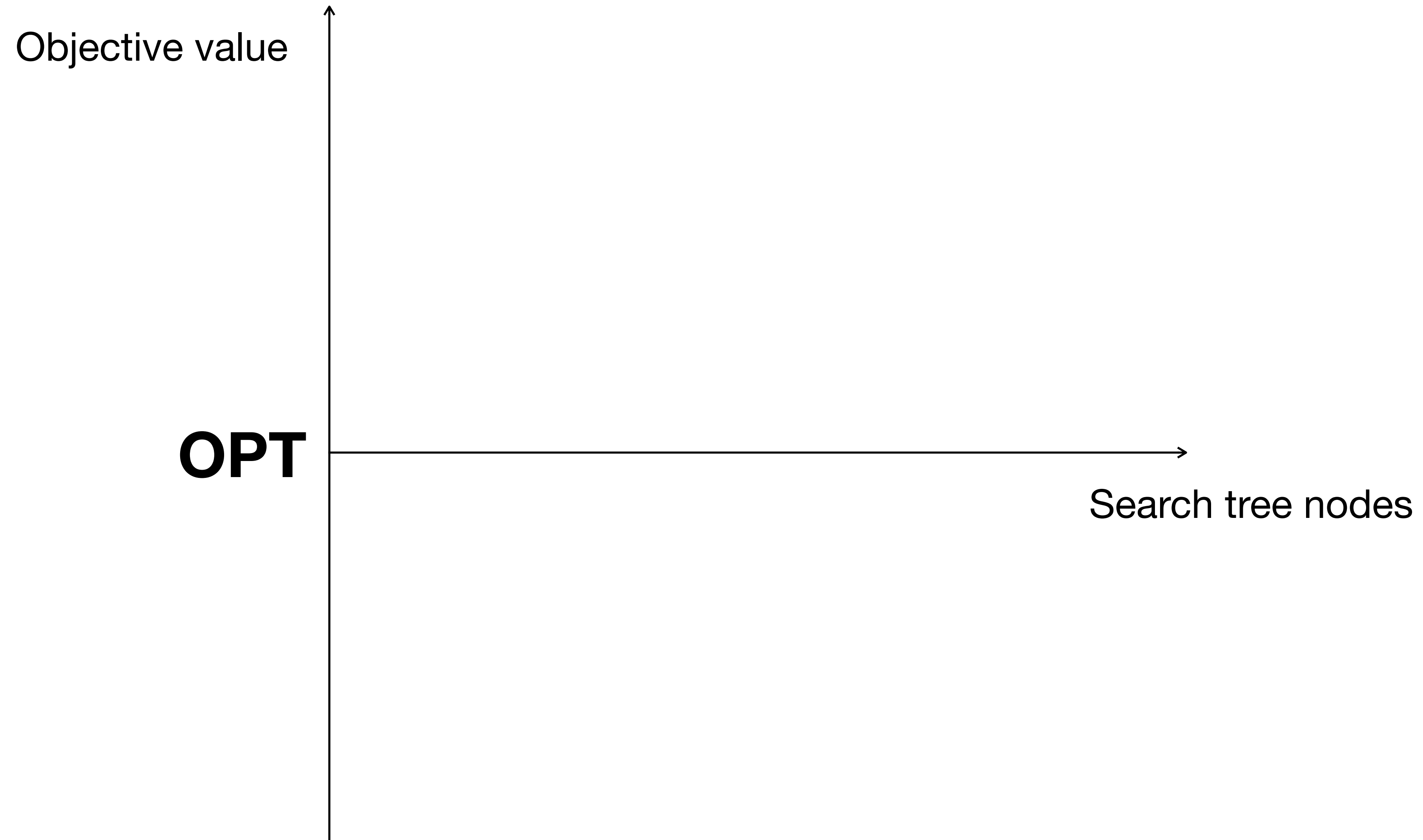
Repeat:

- 1 **Select Node**
- 2 **Solve LP Relaxation**
- 3 **Prune?**
- 4 **Add Cuts**
- 5 **Run Heuristics**
- 6 **Branch**

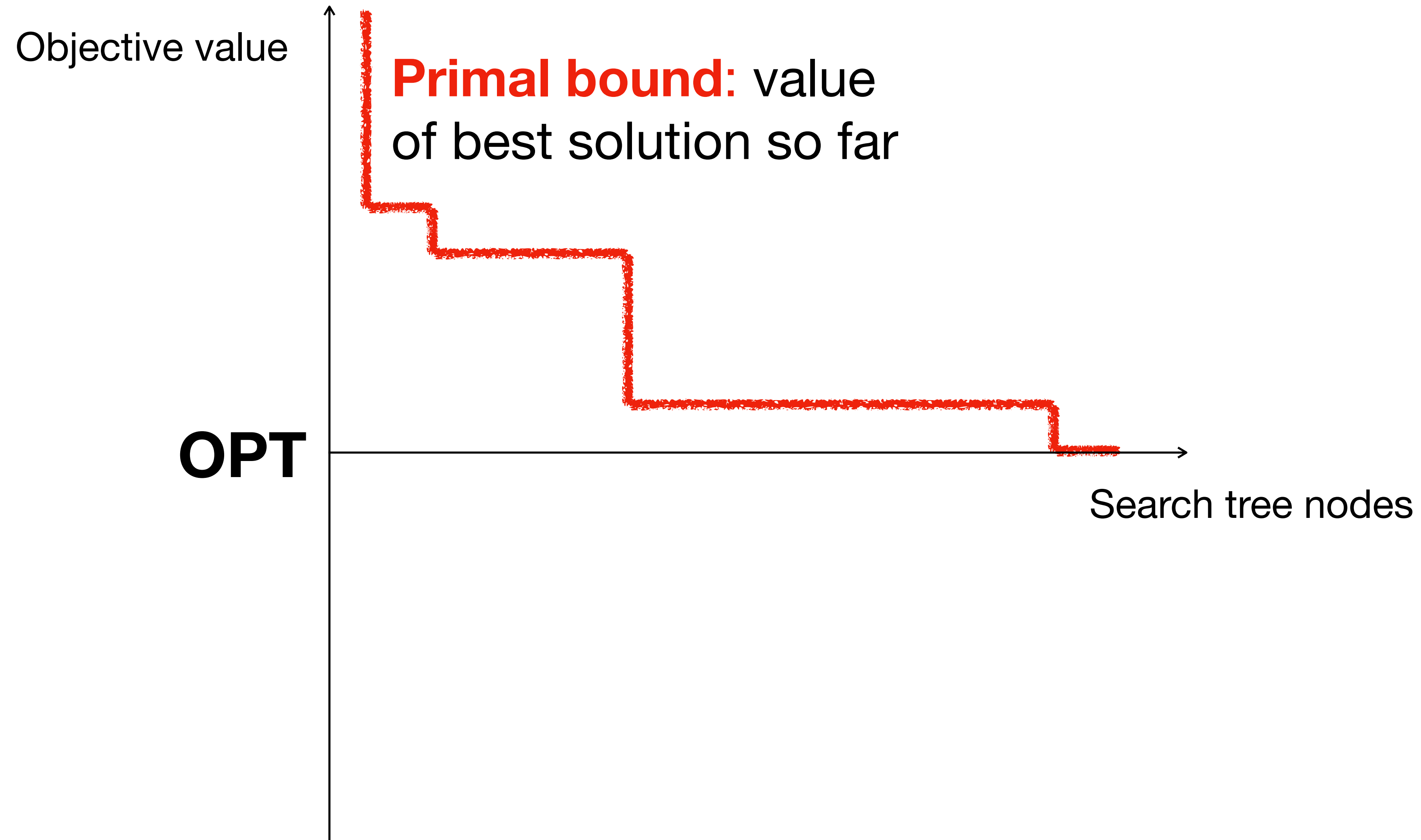


$$\min_x c^T x \quad \mathbf{s.t.} \quad Ax \leq b, x \in \{0,1\}^n$$

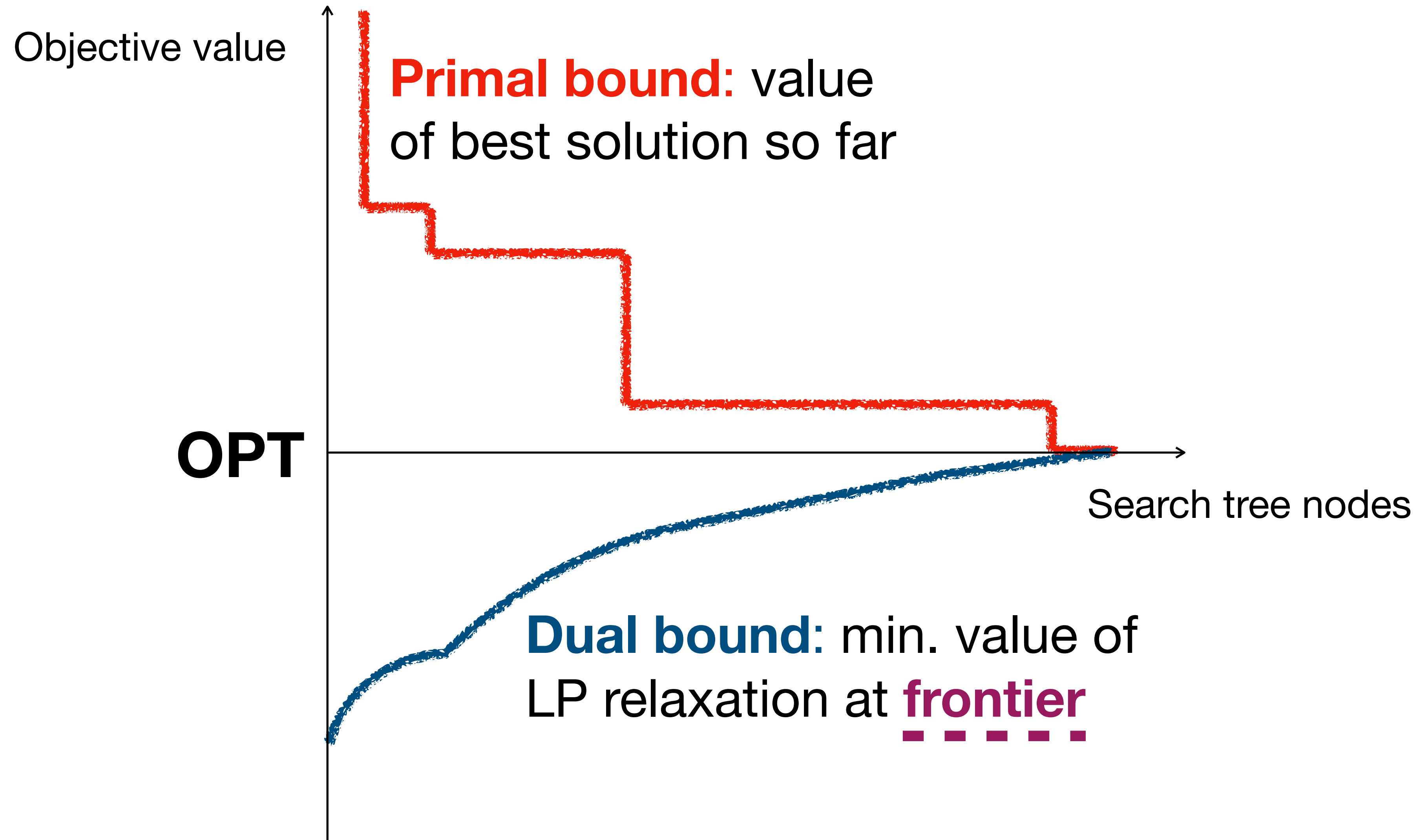
$$\min_x c^T x \text{ s.t. } Ax \leq b, x \in \{0,1\}^n$$



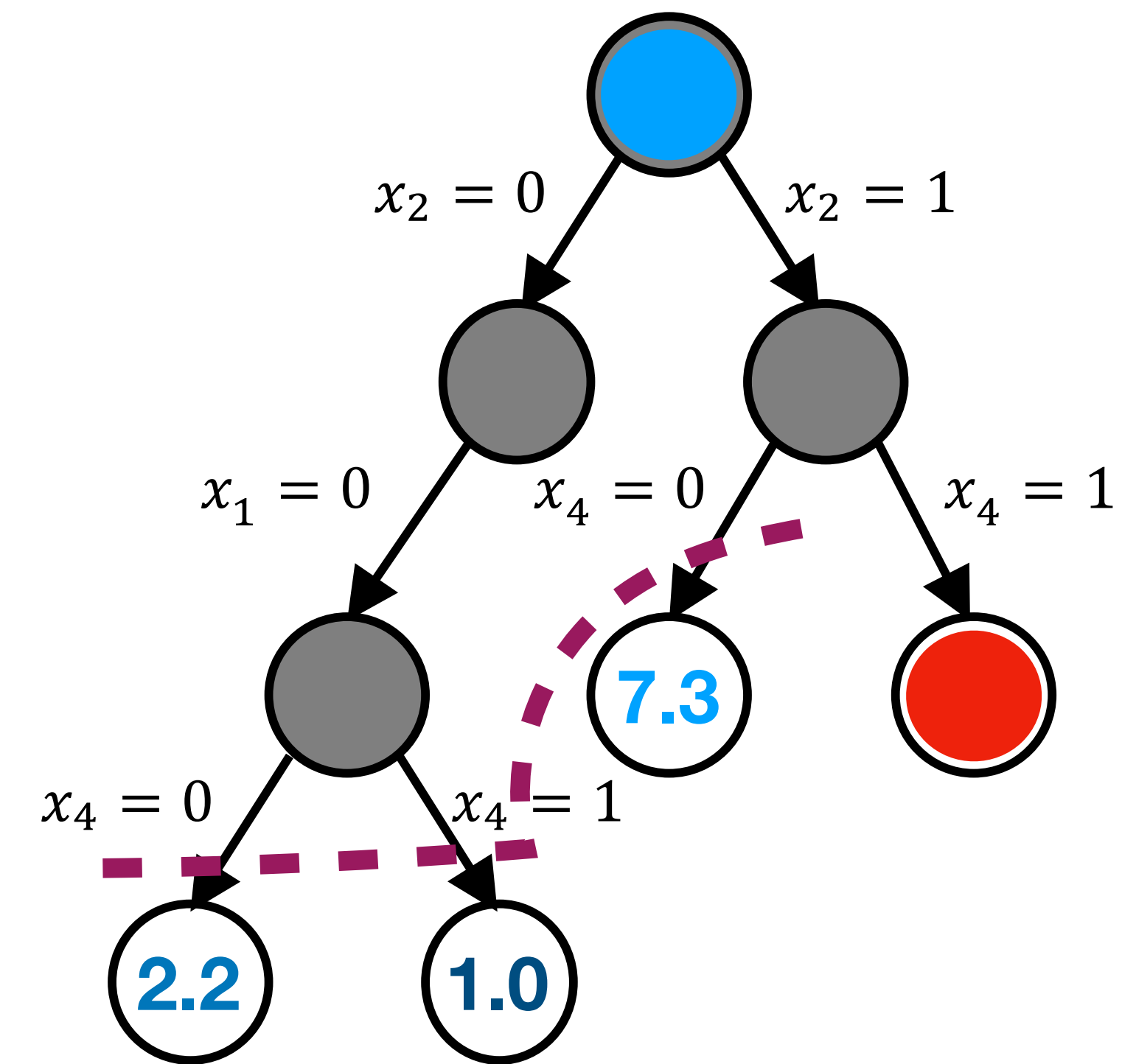
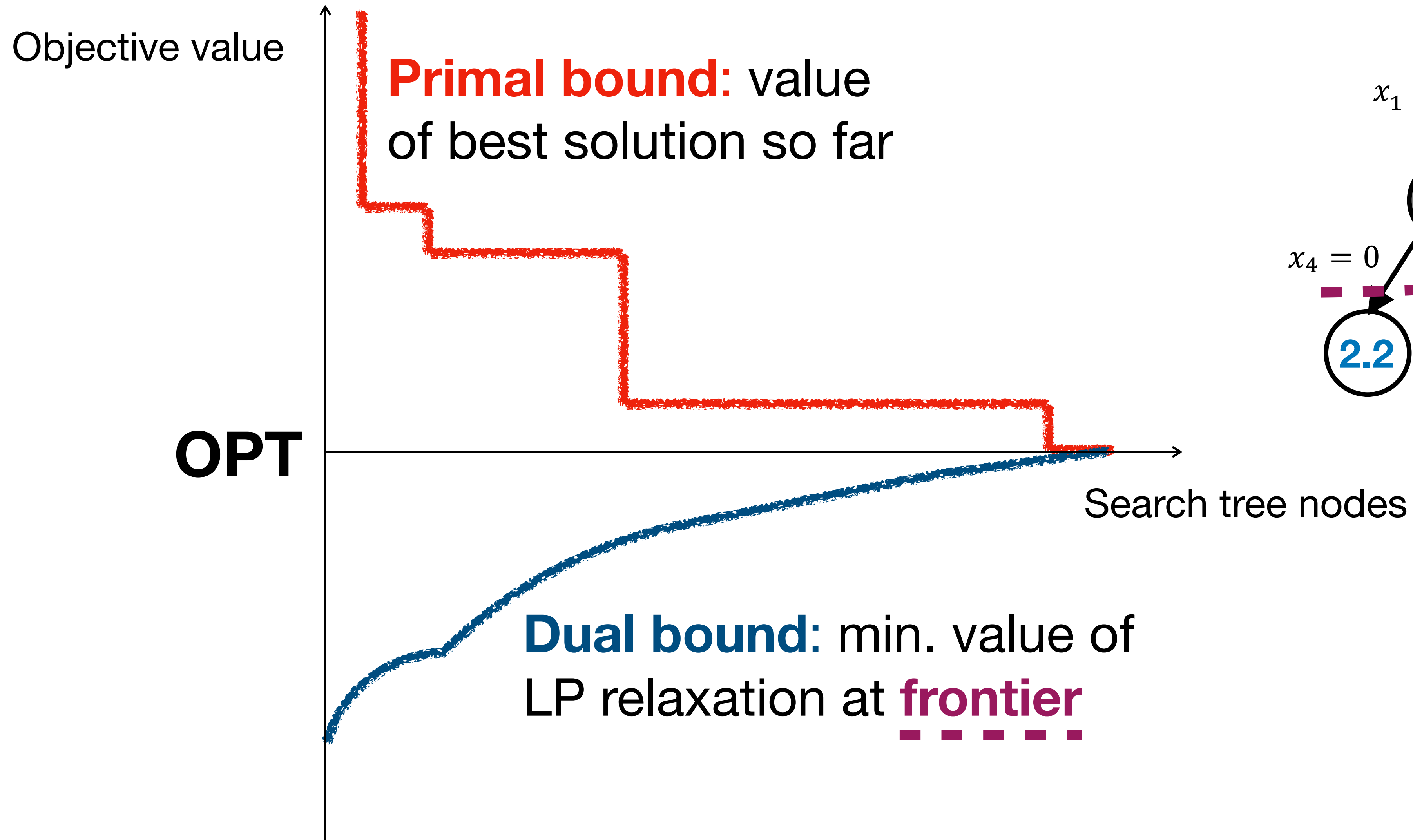
$$\min_x c^T x \text{ s.t. } Ax \leq b, x \in \{0,1\}^n$$



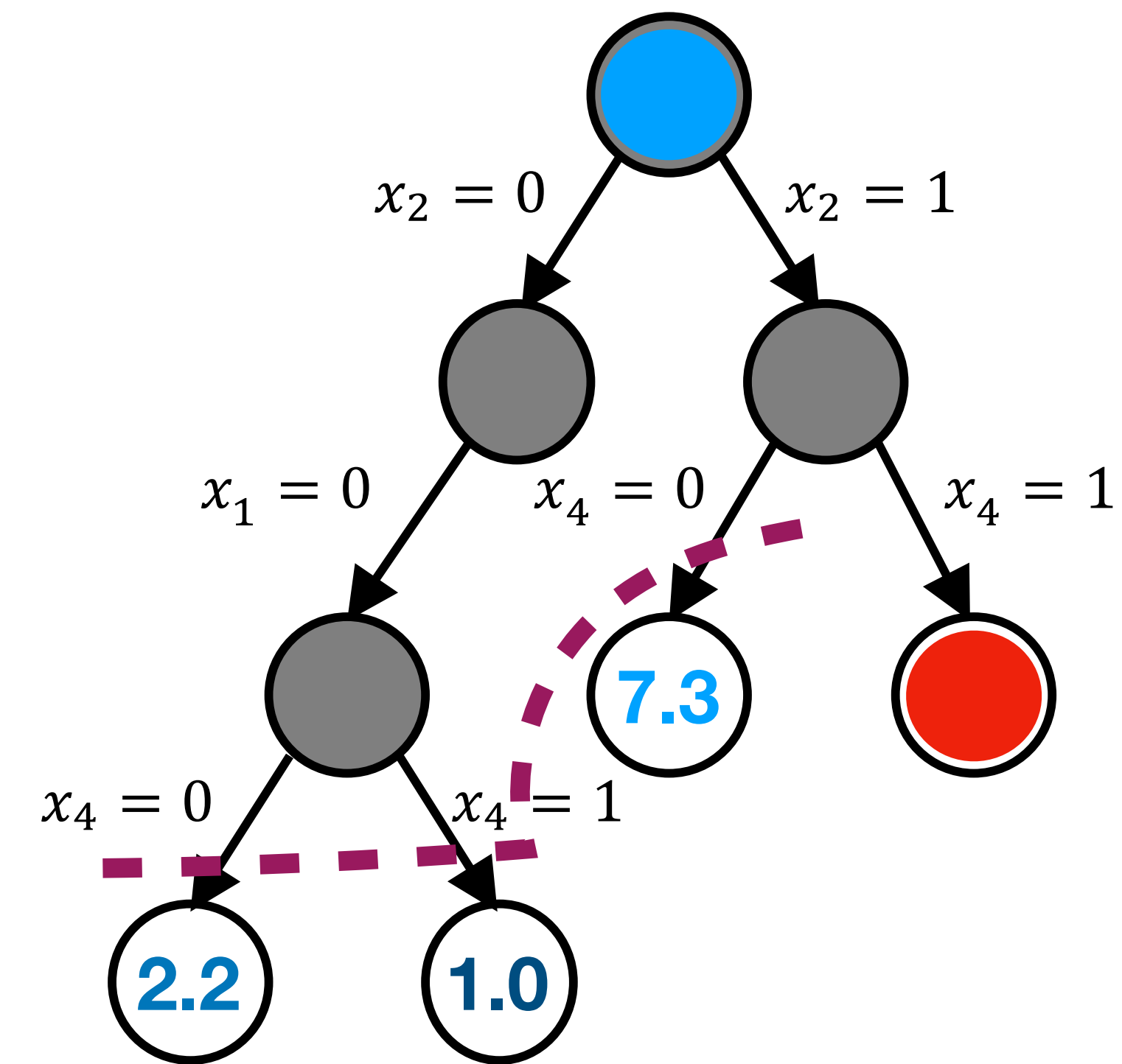
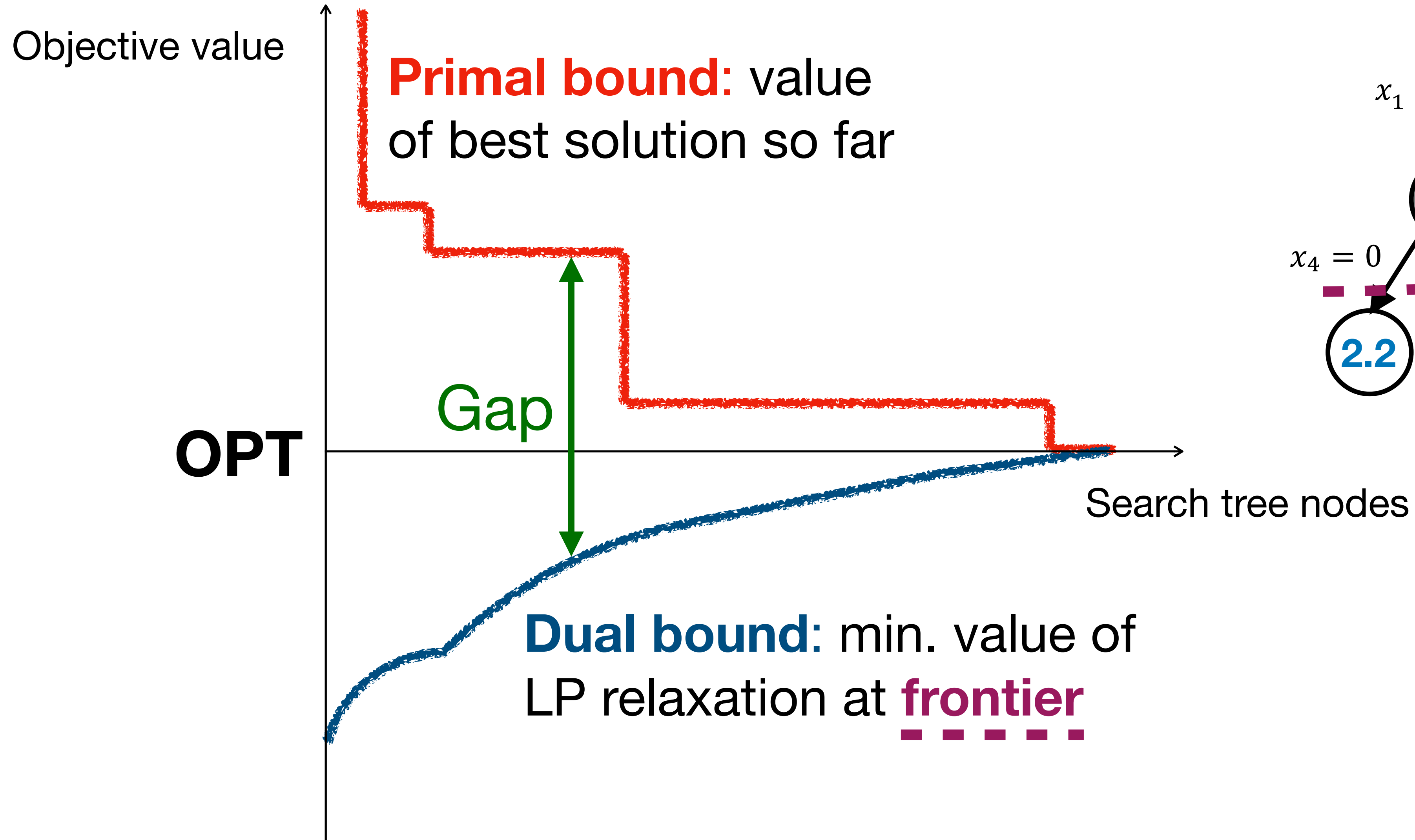
$$\min_x c^T x \text{ s.t. } Ax \leq b, x \in \{0,1\}^n$$



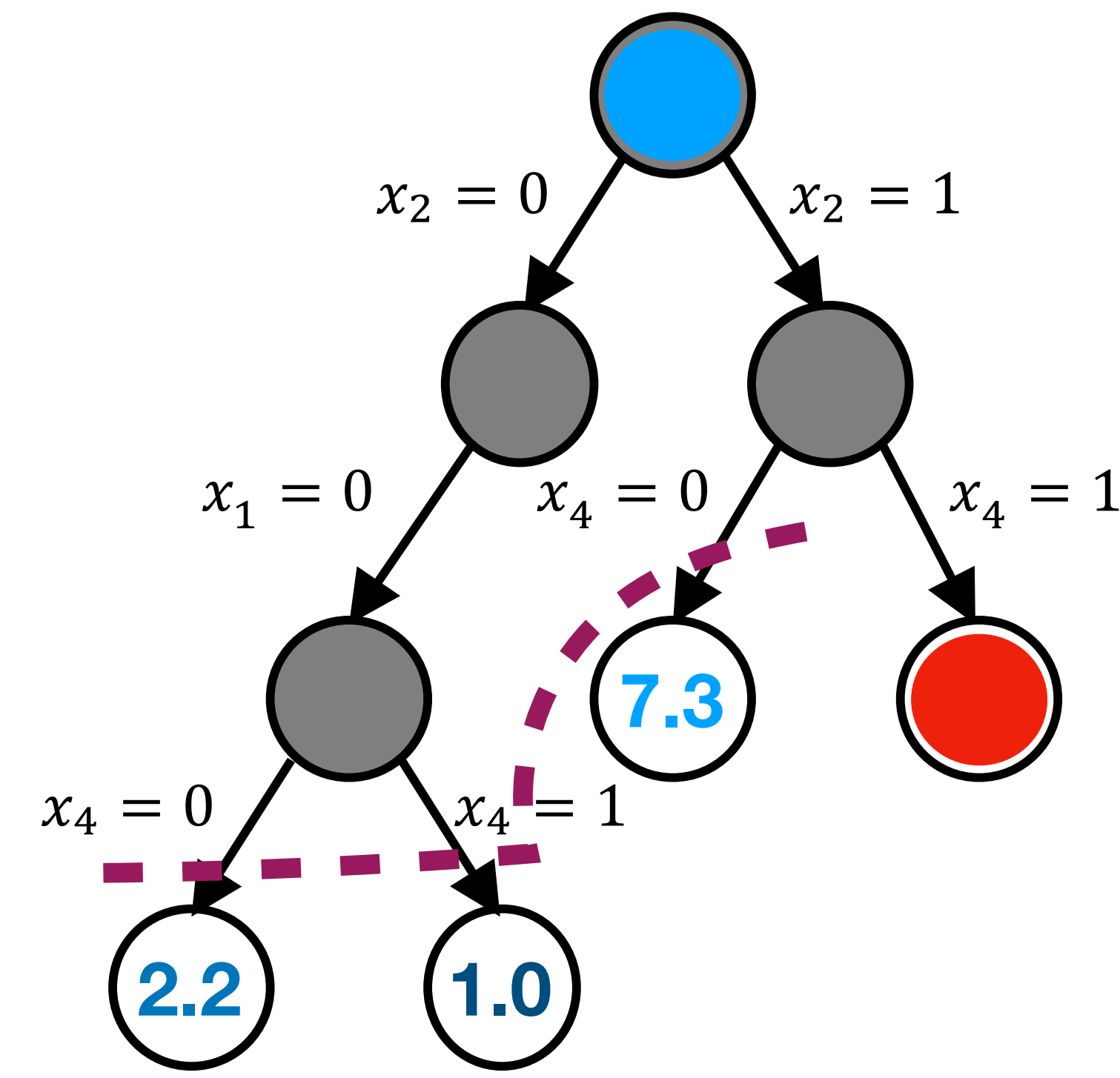
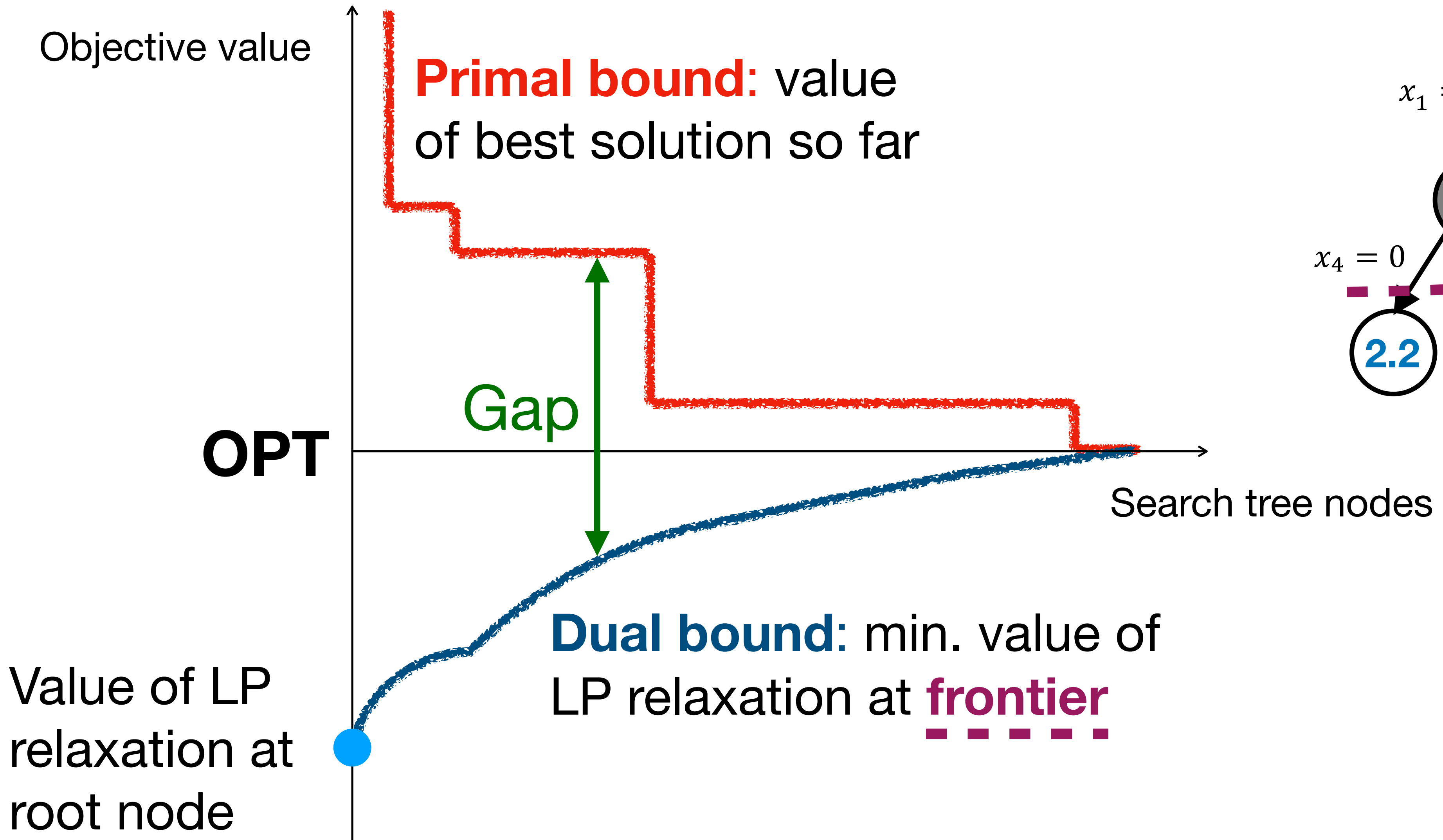
$$\min_x c^T x \text{ s.t. } Ax \leq b, x \in \{0,1\}^n$$



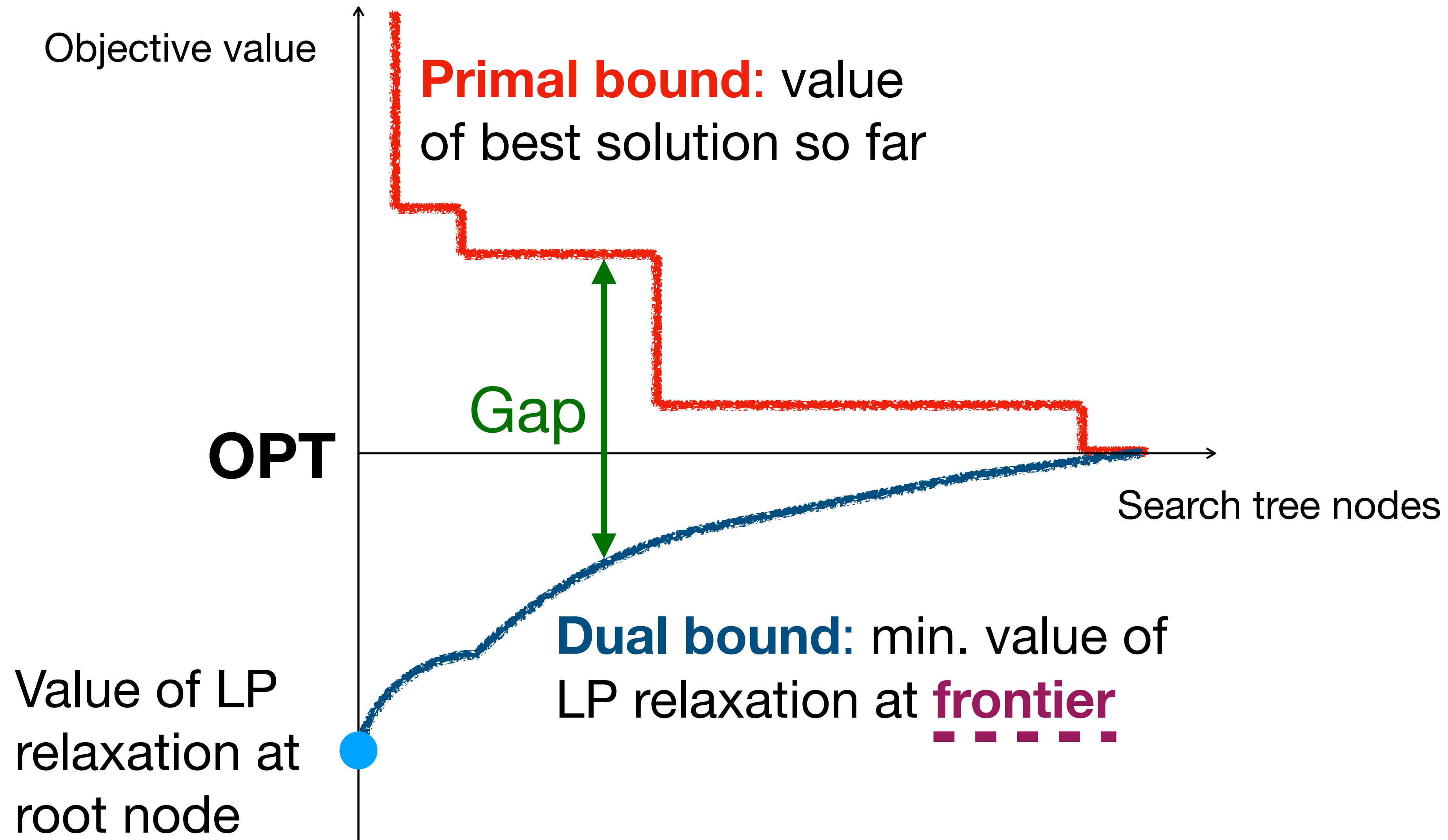
$$\min_x c^T x \text{ s.t. } Ax \leq b, x \in \{0,1\}^n$$



$$\min_x c^T x \text{ s.t. } Ax \leq b, x \in \{0,1\}^n$$

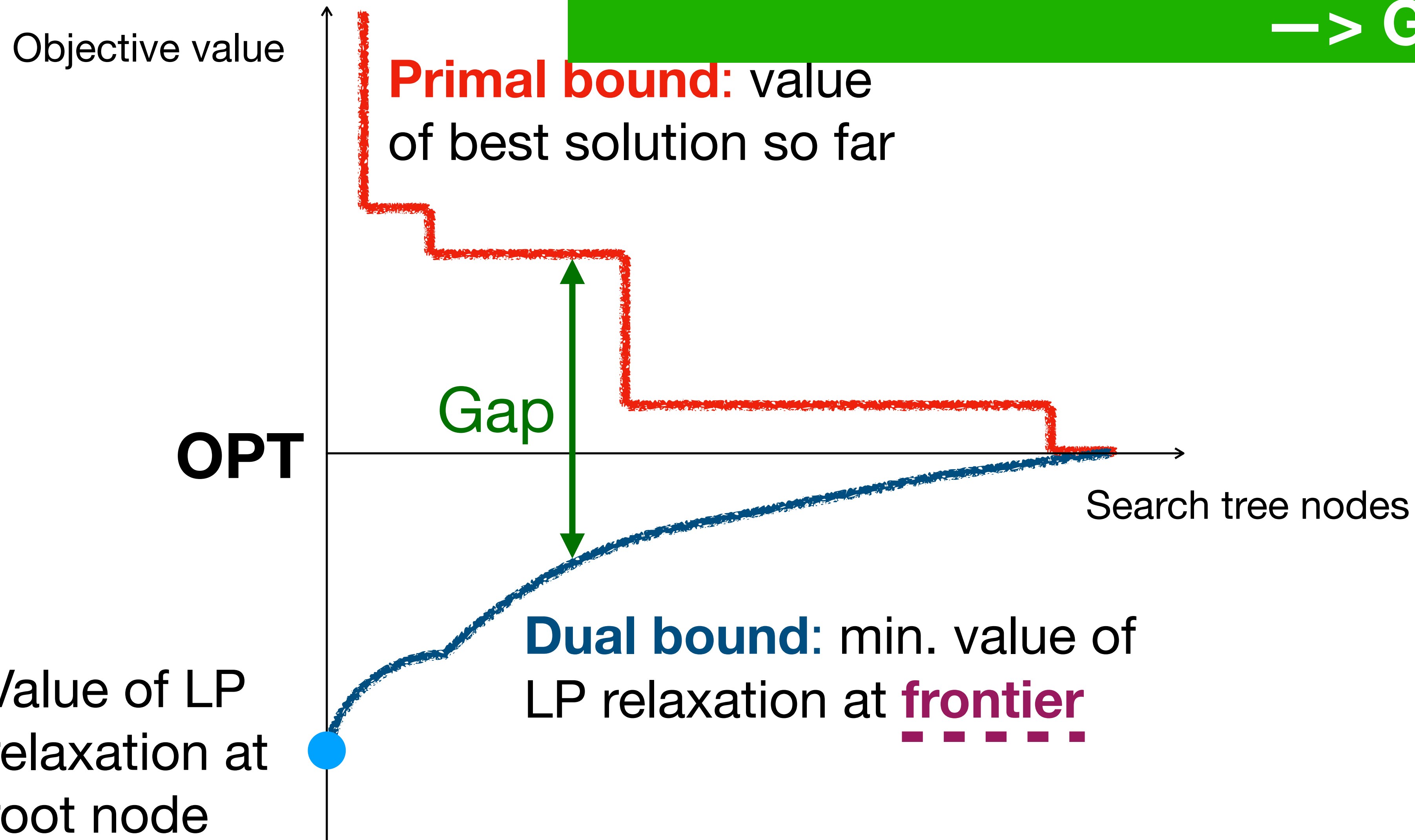


Heuristics matter!



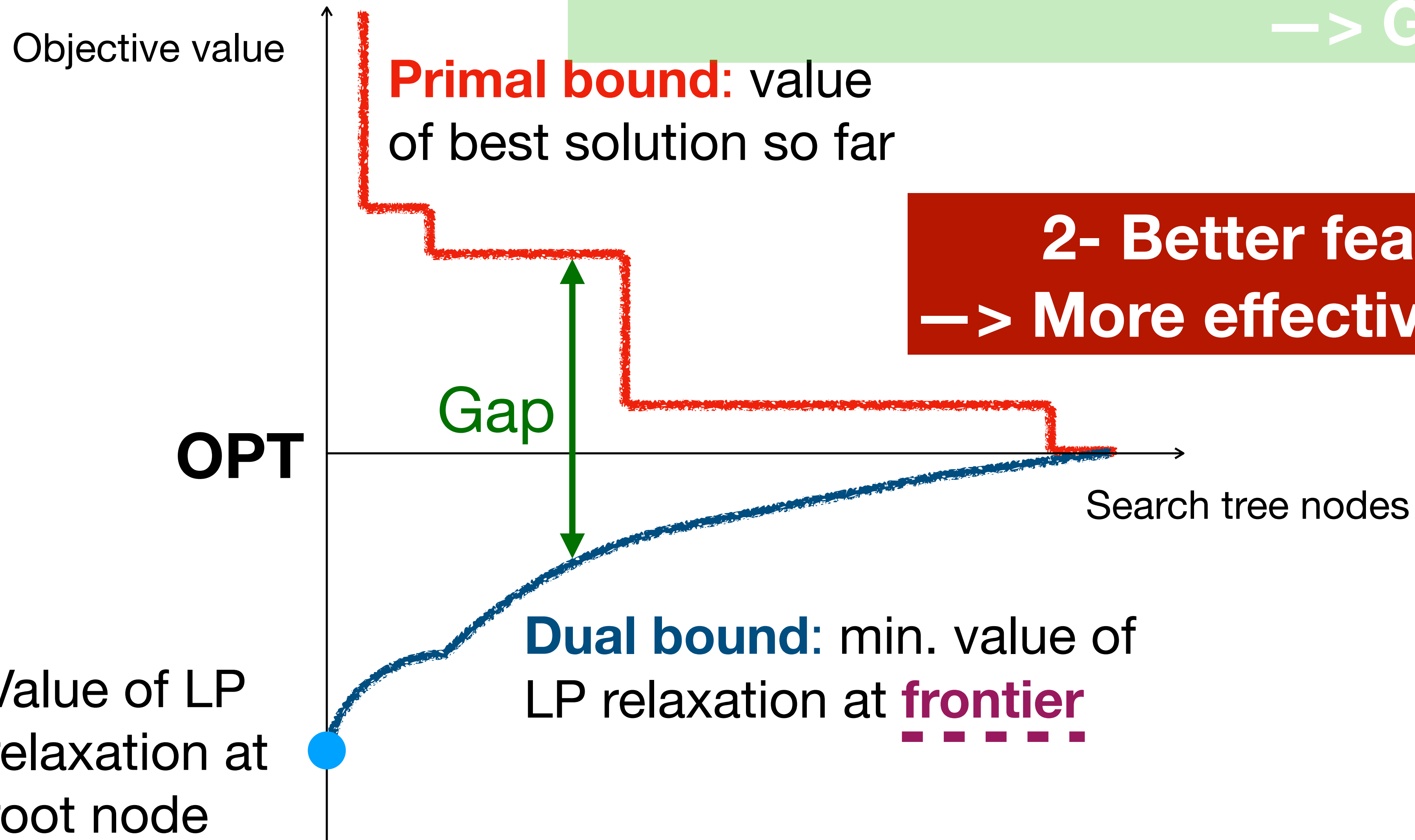
Heuristics matter!

1- Better primal bound \rightarrow More nodes pruned
 \rightarrow Gap closed faster!



Heuristics matter!

1- Better primal bound \rightarrow More nodes pruned
 \rightarrow Gap closed faster!



Data-Driven Algorithm Design

ML Paradigm

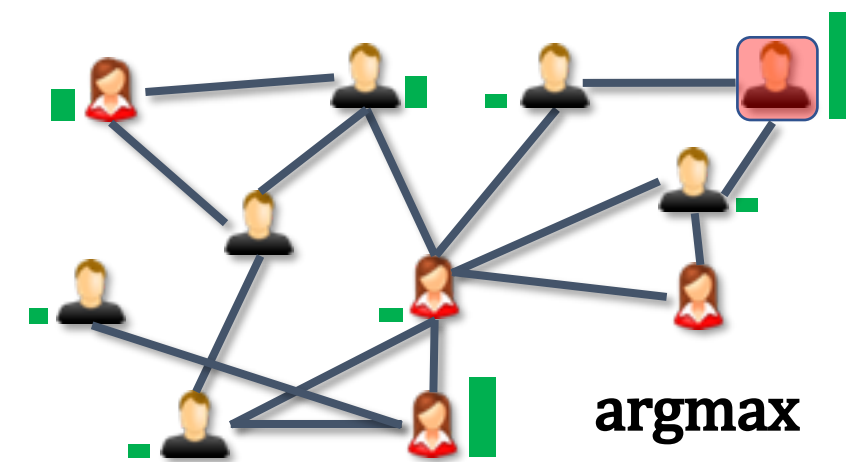
Self-Supervised Learning ■

Reinforcement Learning ■

Supervised Learning ■

NeurIPS-17

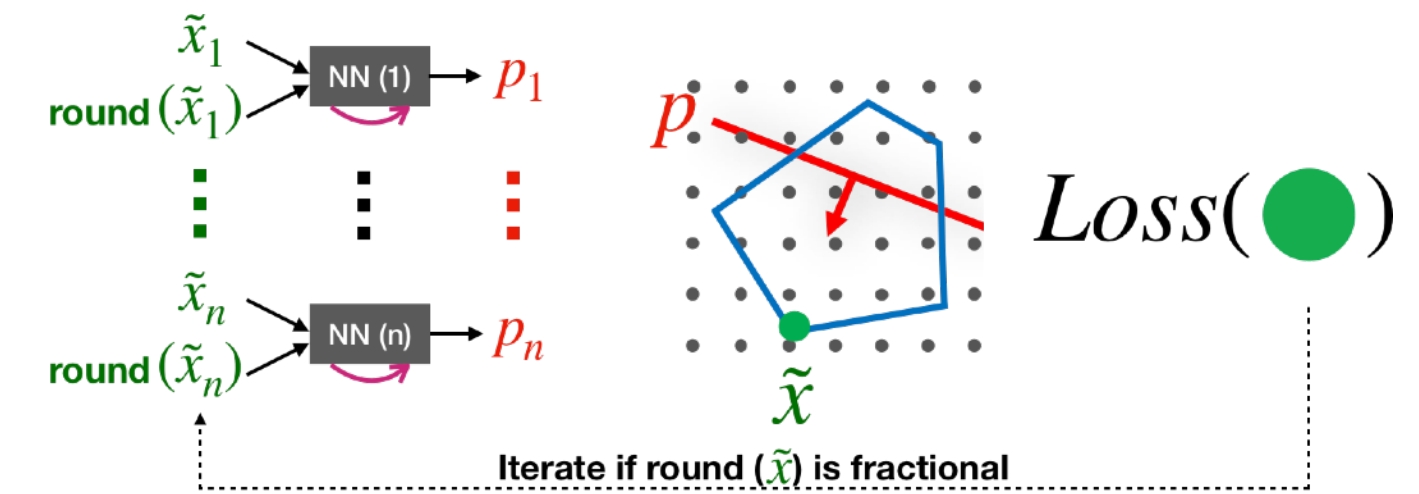
Greedy Heuristic



Graph Optimization

NeurIPS-19, hopefully?

General Integer Programming Heuristic



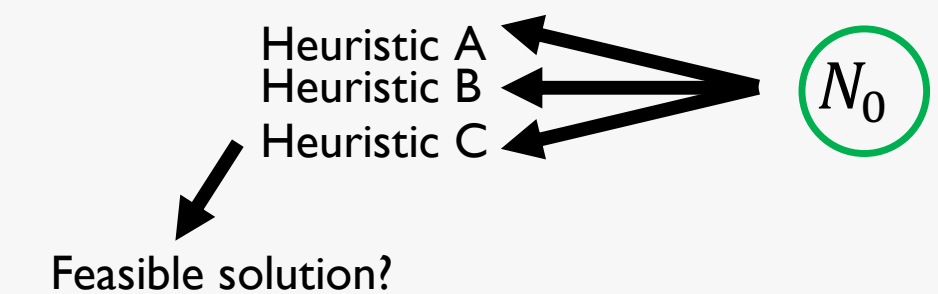
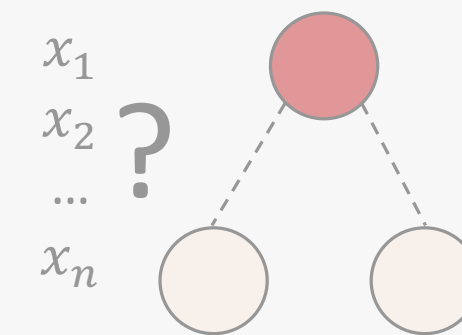
AAAI-16

Exact Solving

IJCAI-17

Branching

Heuristic Selection

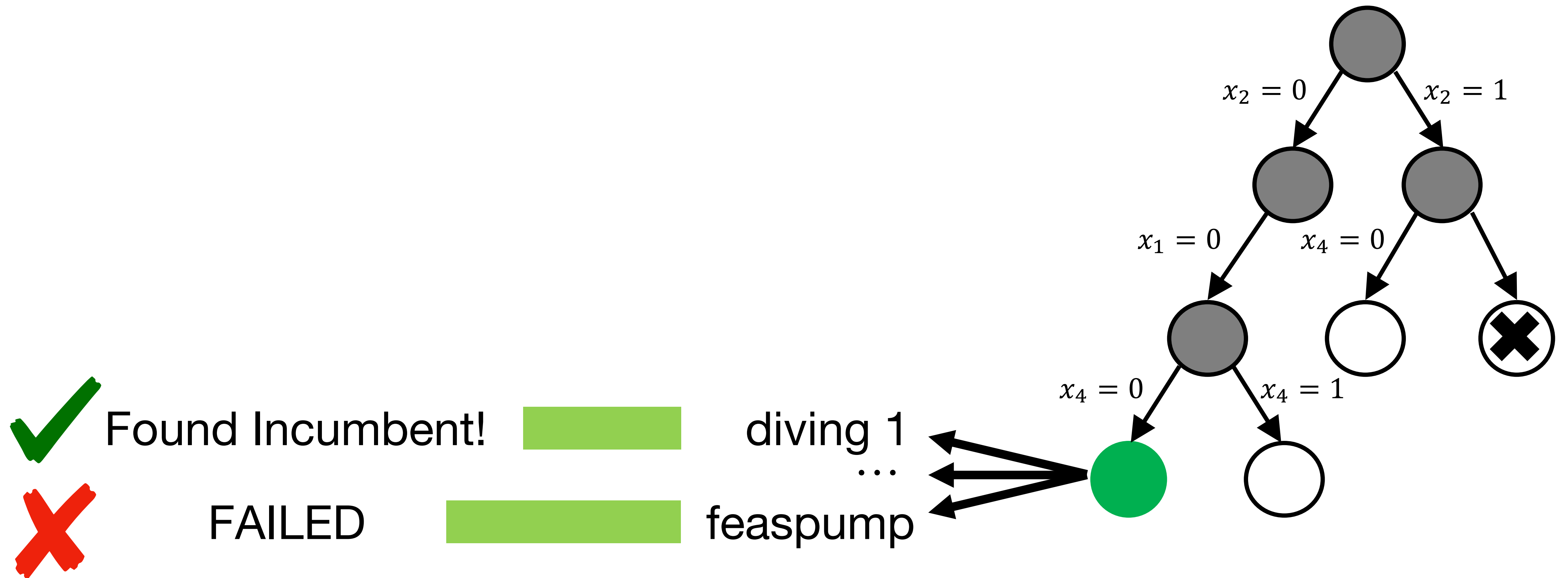


Integer Programming

Problem Type

The Heuristic Selection Problem

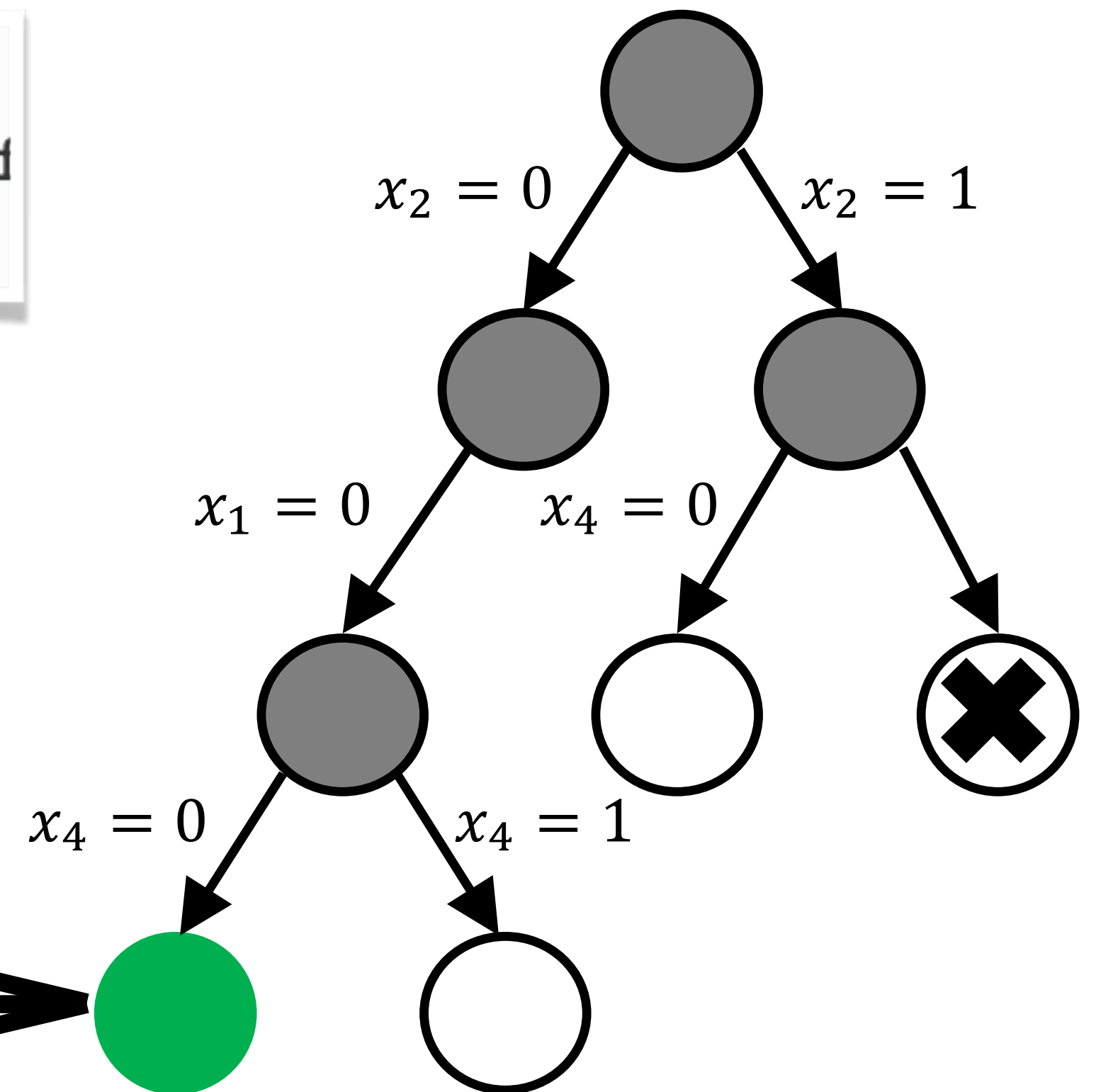
MIP solvers implement **many** primal **heuristics**: 54 in SCIP (2019)



The Heuristic Selection Problem

MIP solvers implement **many** primal **heuristics**: 54 in SCIP (2019)

```
# frequency for calling primal heuristic <nlpdiving>  
# [type: int, advanced: FALSE, range: [-1,65534], def  
heuristics/nlpdiving/freq = 10
```



Found Incumbent!



diving 1

...



FAILED



feaspump

The Heuristic Selection Problem

MIP solvers implement **many** primal **heuristics**: 54 in SCIP (2019)

```
# frequency for calling primal heuristic <nlpdiving>  
# [type: int, advanced: FALSE, range: [-1,65534], def  
heuristics/nlpdiving/freq = 10
```

```
# frequency for calling primal heuristic <feaspump>  
# [type: int, advanced: FALSE, range: [-1,65534], de  
heuristics/feaspump/freq = 20
```



Found Incumbent!



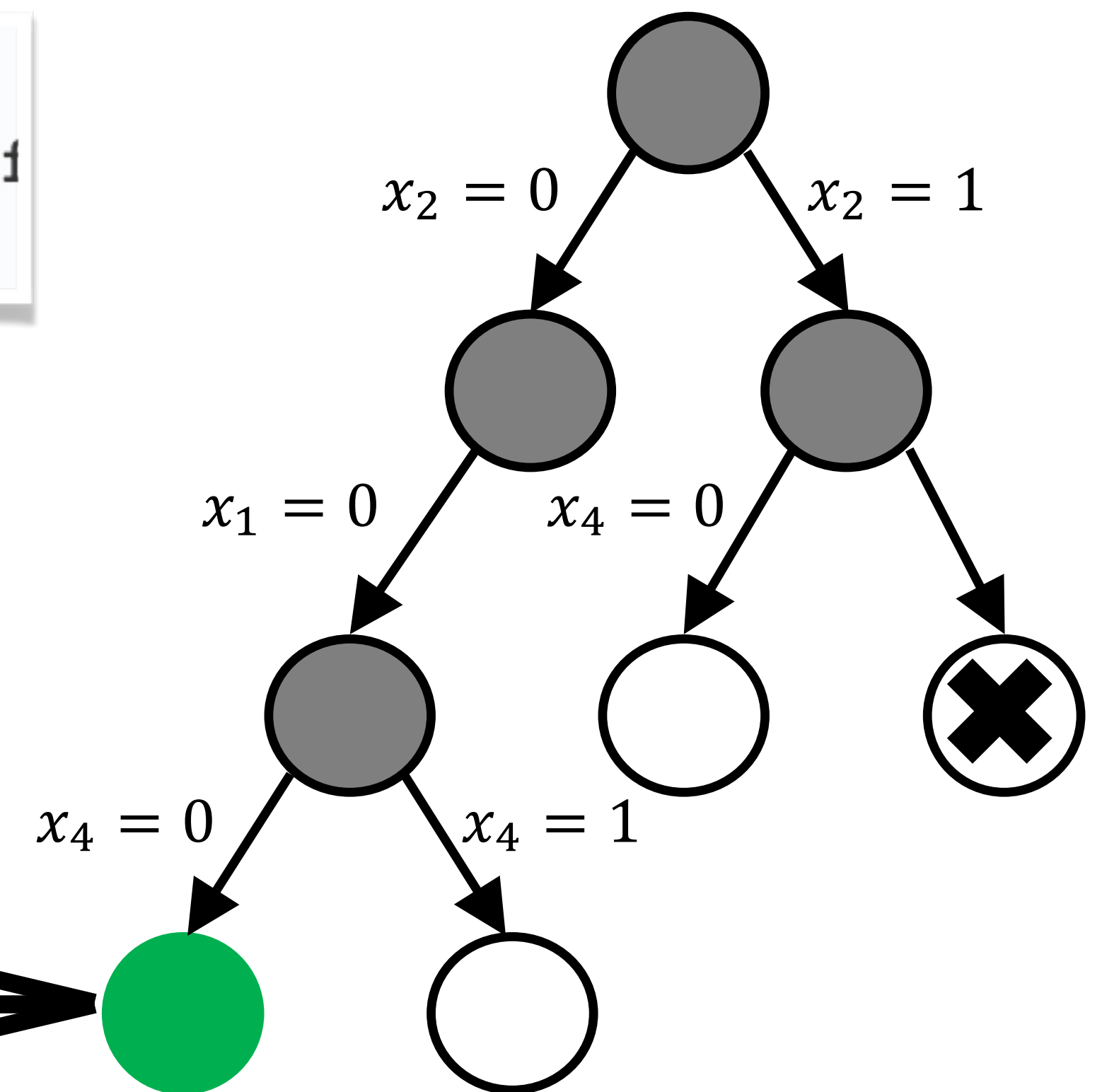
diving 1
...



FAILED



feaspump



The Heuristic Selection Problem

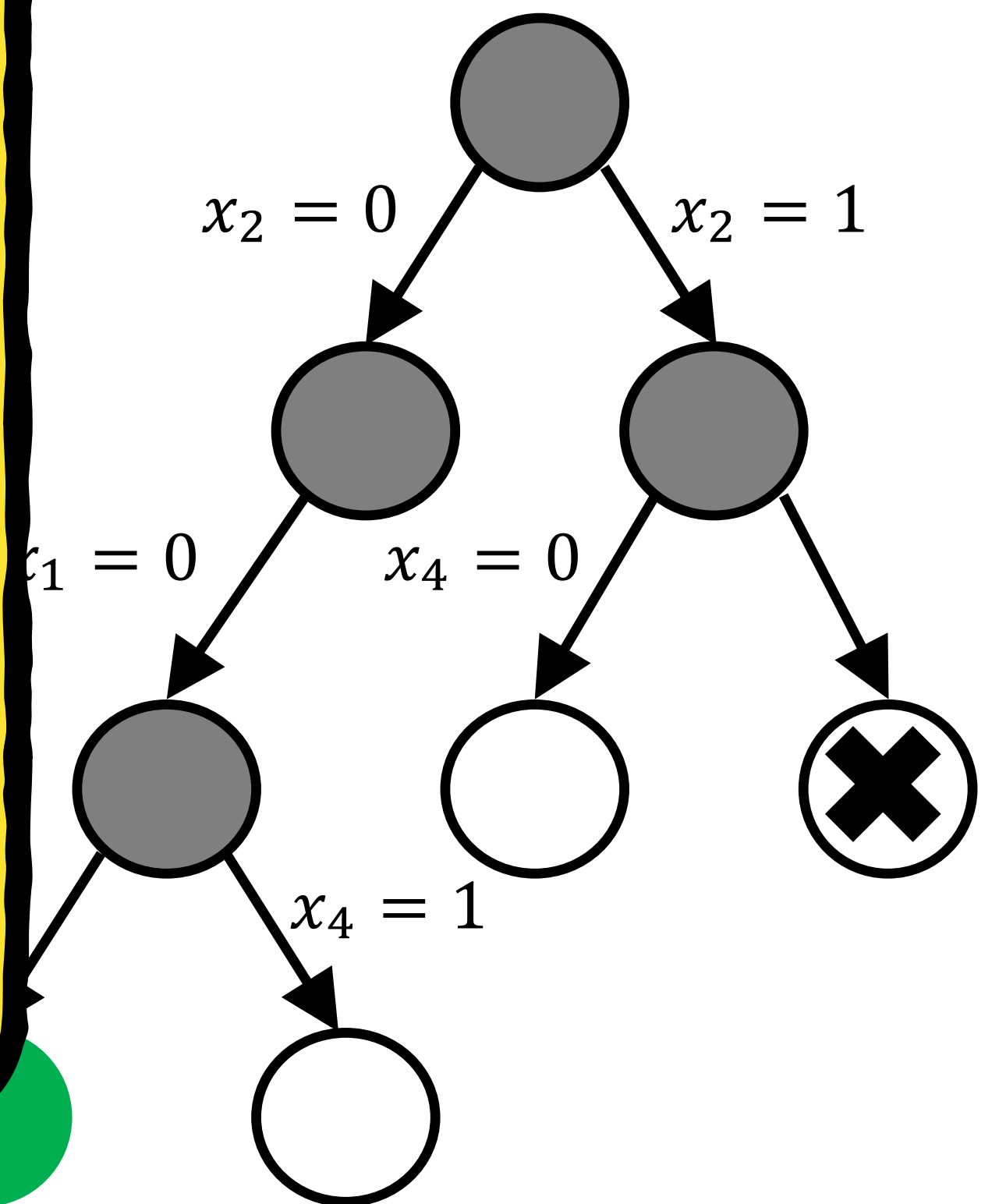
Learning to Run Heuristics

[Khalil, Dilkina, Nemhauser, Ahmed, Shao, 2017]

Given: dataset of
(node features, 0/1 success flag)

Learn: a classifier of heuristic success

IP (2019)



FAILED

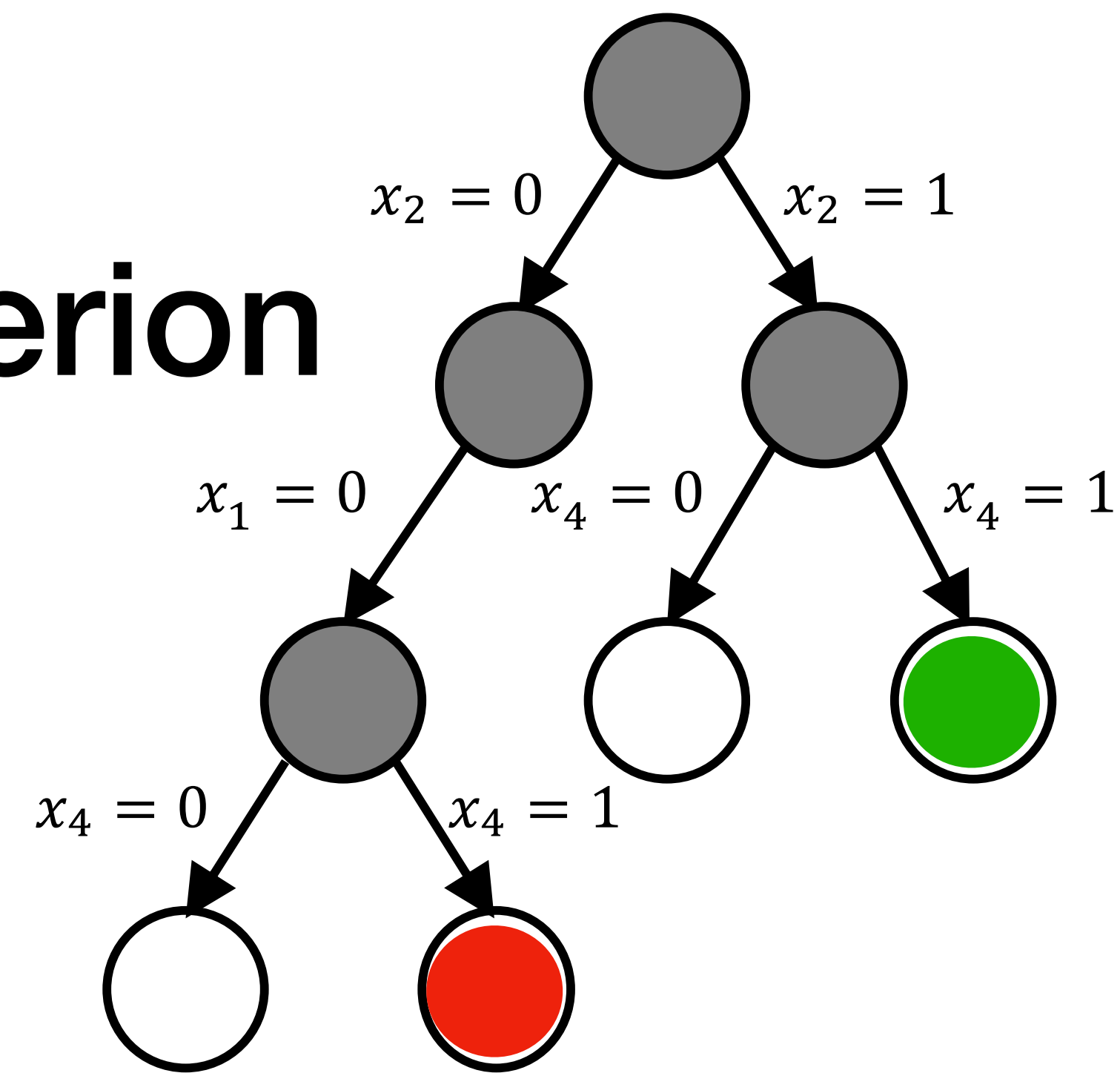
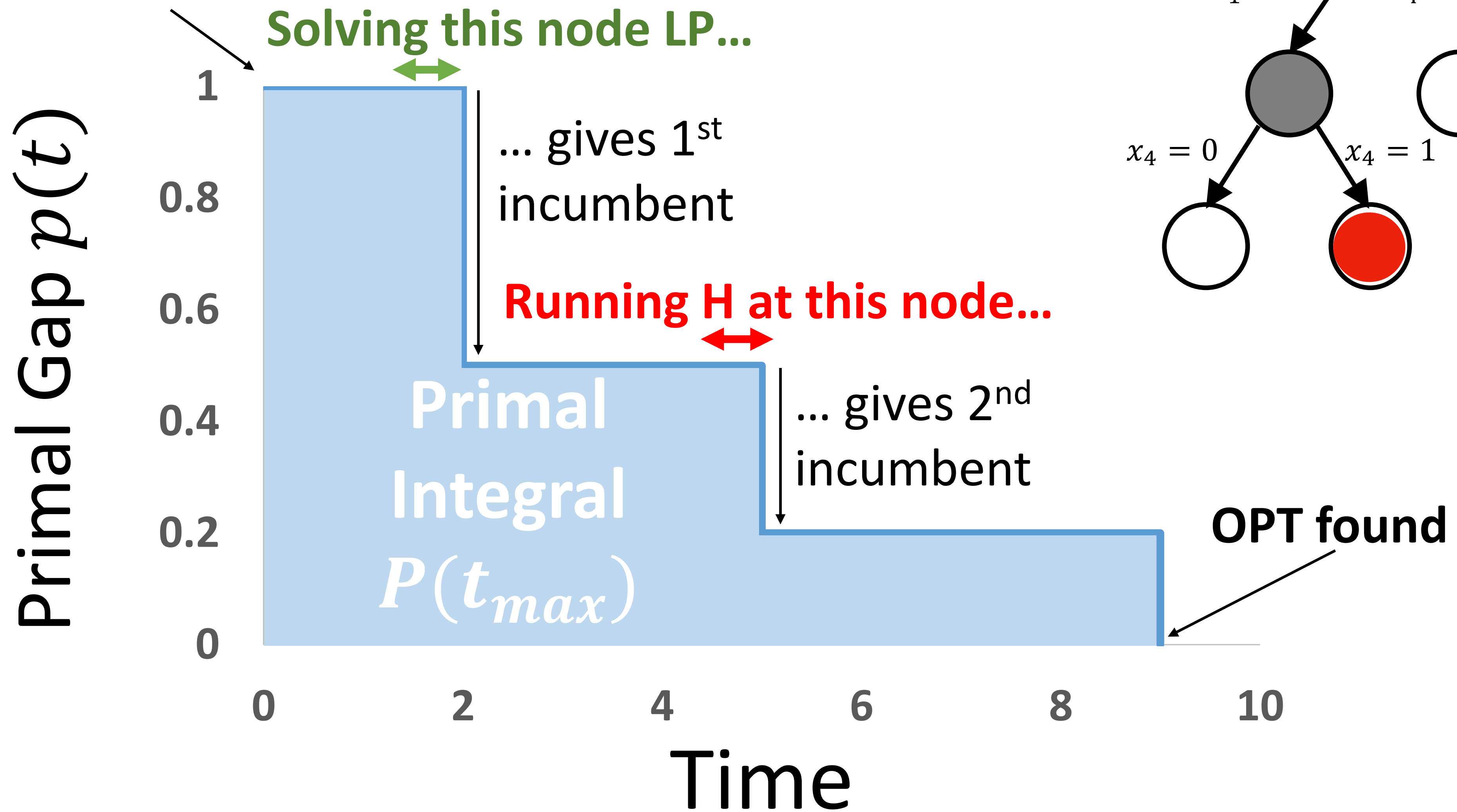


feaspump

Primal Integral

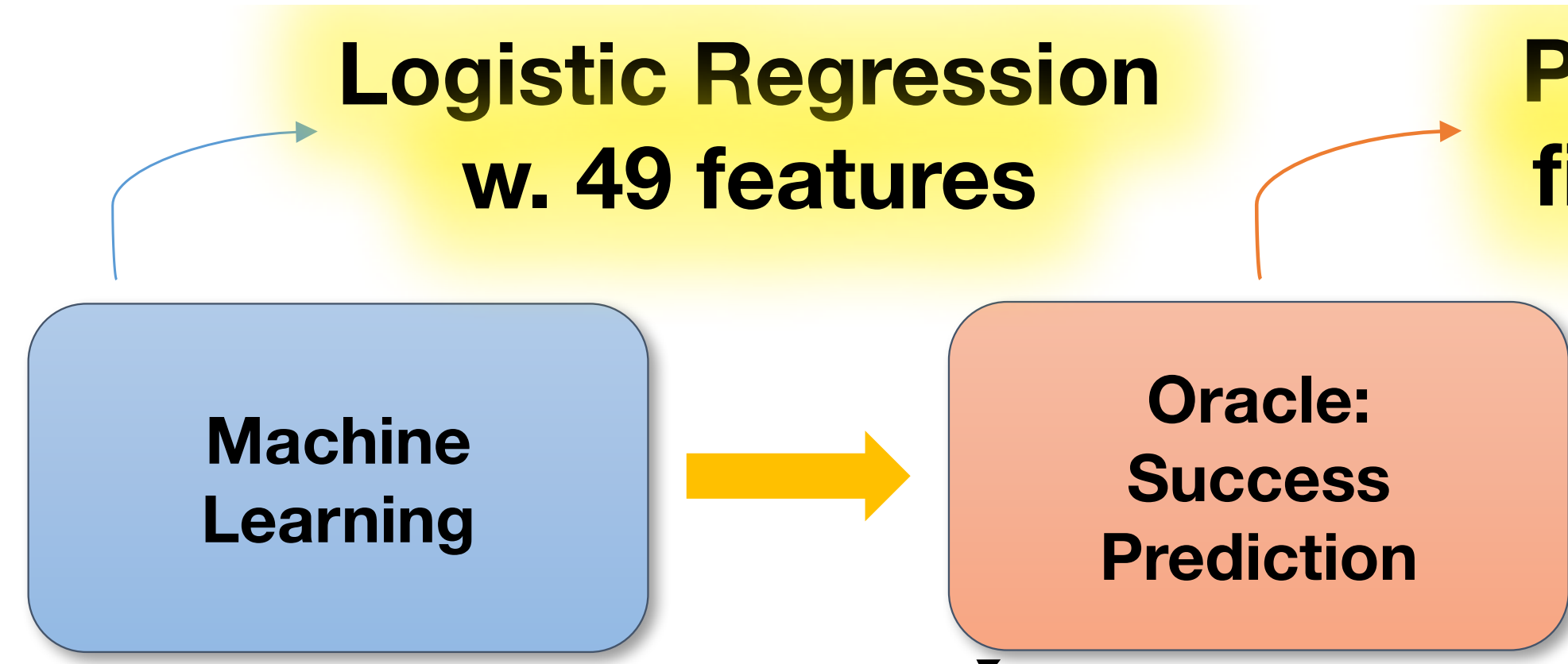
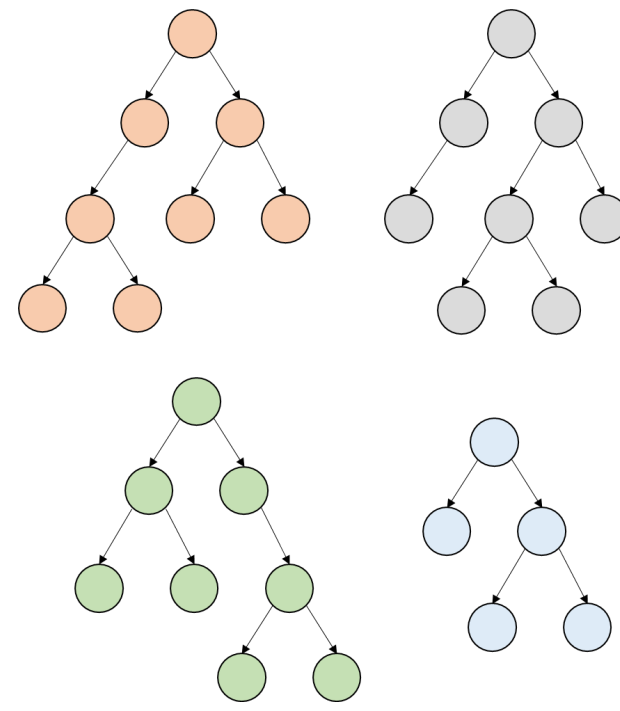
A Good Performance Criterion

No incumbent at first

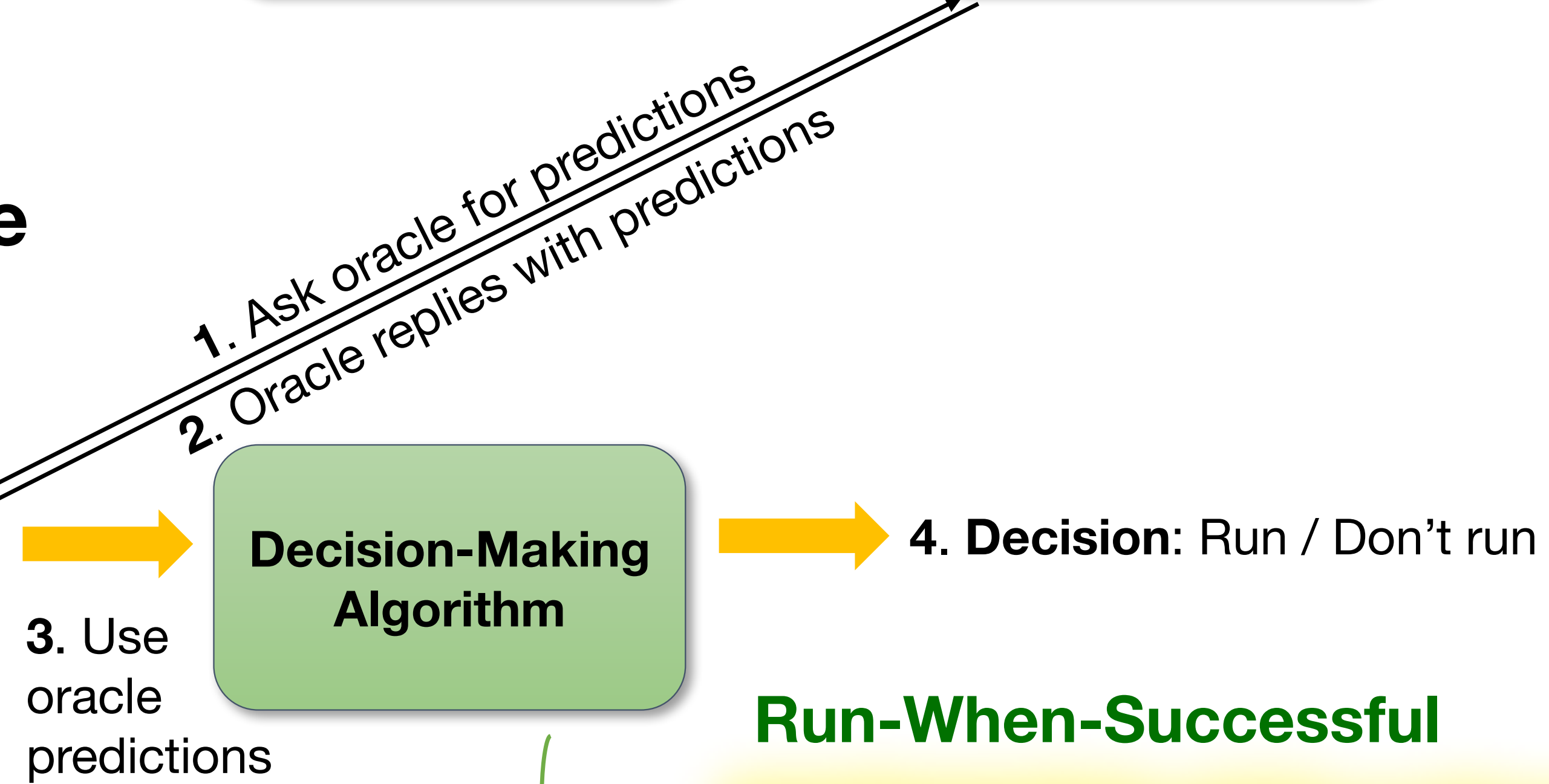
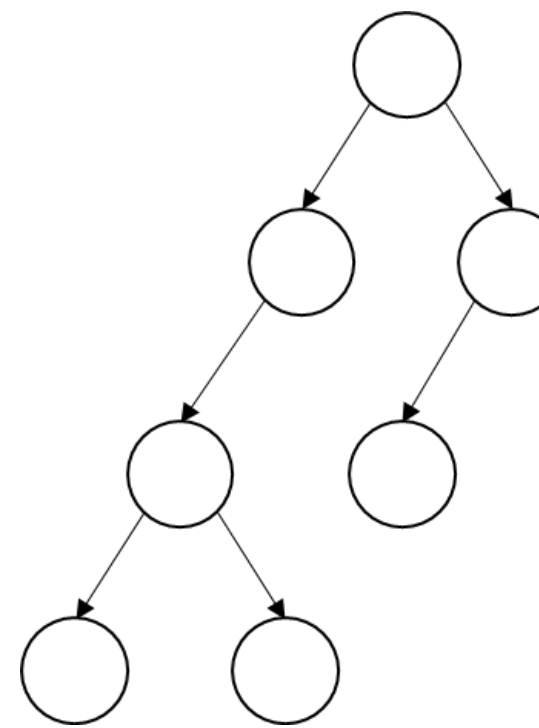


Learning to Run Heuristics

Data Collection



New Instance

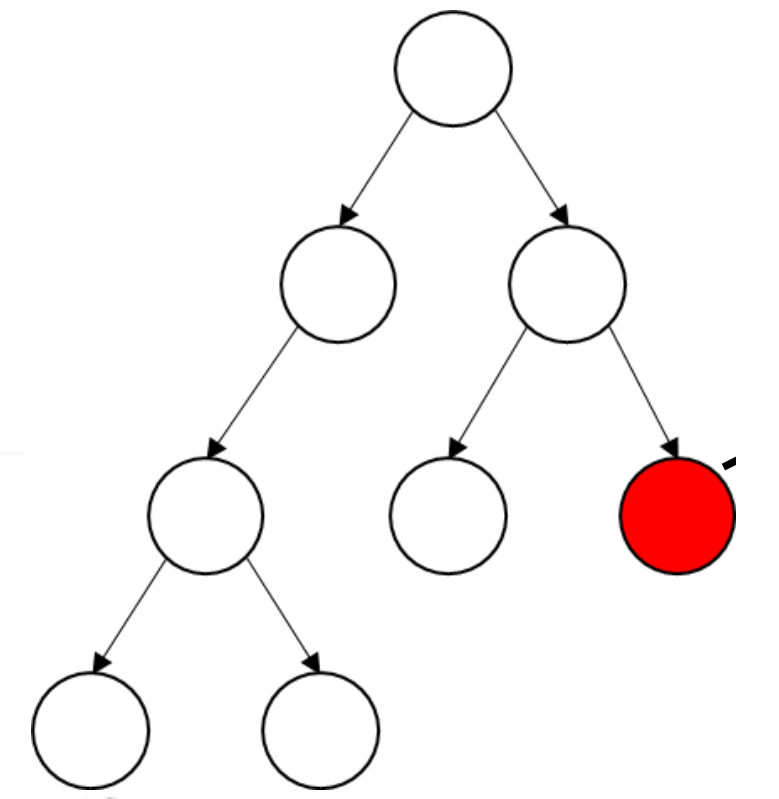


Run-When-Successful
RWS: if $P(N) > 0.5$, run heuristic

Feature Engineering

- ▶ **Global Features (4):**
 - ▶ optimality gap, root LP value / global lower (upper) bound
- ▶ **Depth Features (2):**
 - ▶ node depth / max. depth in tree (max. possible depth)
- ▶ **Node LP Features (8):**
 - ▶ sum of variables' LP sol. fractionalities / #fractional variables
 - ▶ num. of fractional variables / #integer variables
 - ▶ num. variables roundable up (down) / #integer variables
- ▶ **Scoring Features for Fractional Variables (35):**
 - ▶ number of up (down) locks
 - ▶ normalized objective coefficient
 - ▶ pseudocost score

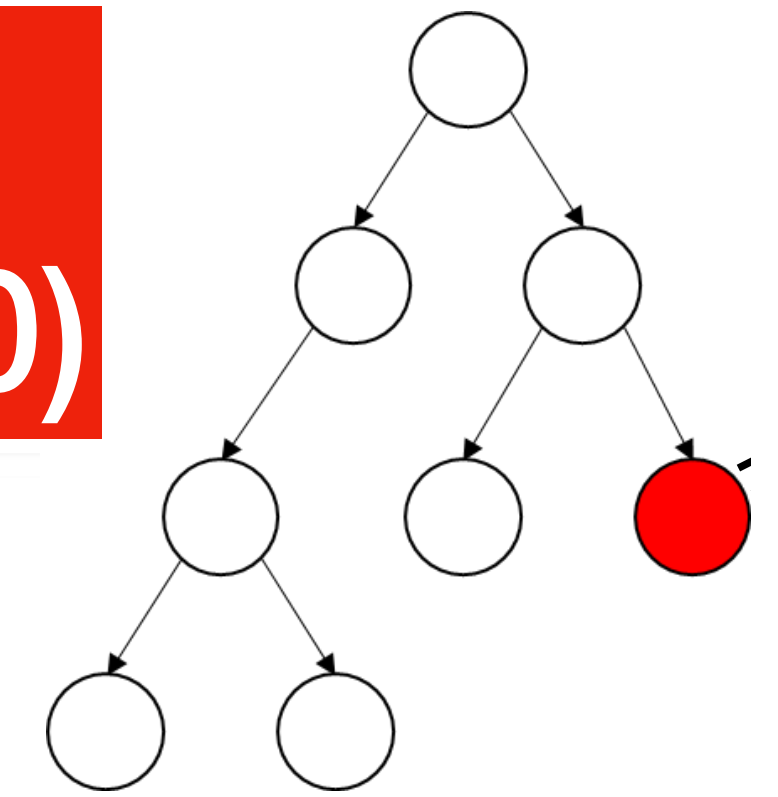
Five statistics (mean, min., max., median, standard deviation) for each metric over fractional variables in LP solution.



Feature Engi

Binary Label

found incumbent (1), o.w. (0)



- ▶ **Global Features (4):**
 - ▶ optimality gap, root LP value / global lower (upper) bound
- ▶ **Depth Features (2):**
 - ▶ node depth / max. depth in tree (max. possible depth)
- ▶ **Node LP Features (8):**
 - ▶ sum of variables' LP sol. fractionalities / #fractional variables
 - ▶ num. of fractional variables / #integer variables
 - ▶ num. variables roundable up (down) / #integer variables
- ▶ **Scoring Features for Fractional Variables (35):**
 - ▶ number of up (down) locks
 - ▶ normalized objective coefficient
 - ▶ pseudocost score

Five statistics (mean, min., max., median, standard deviation) for each metric over fractional variables in LP solution.

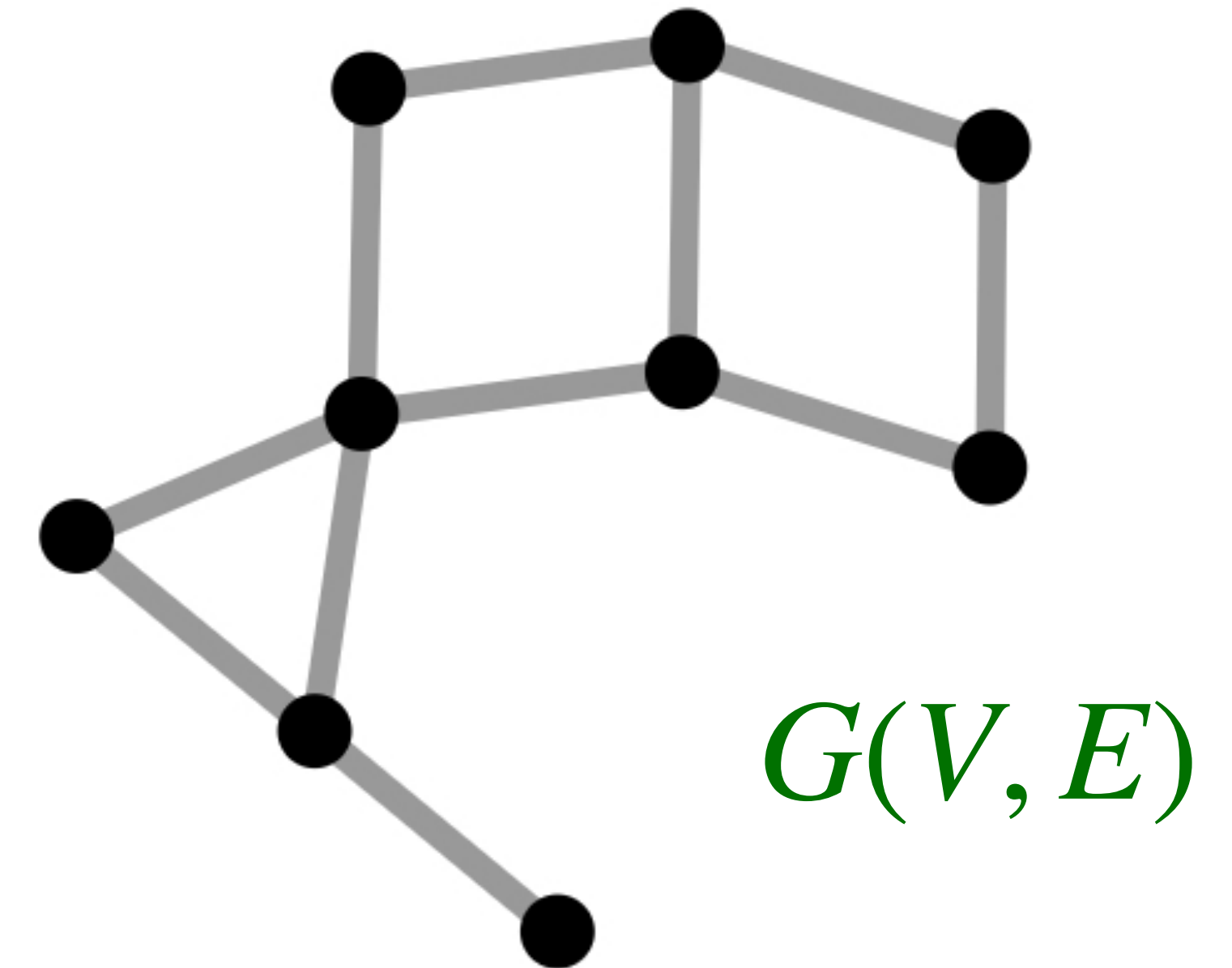
Forest Harvesting



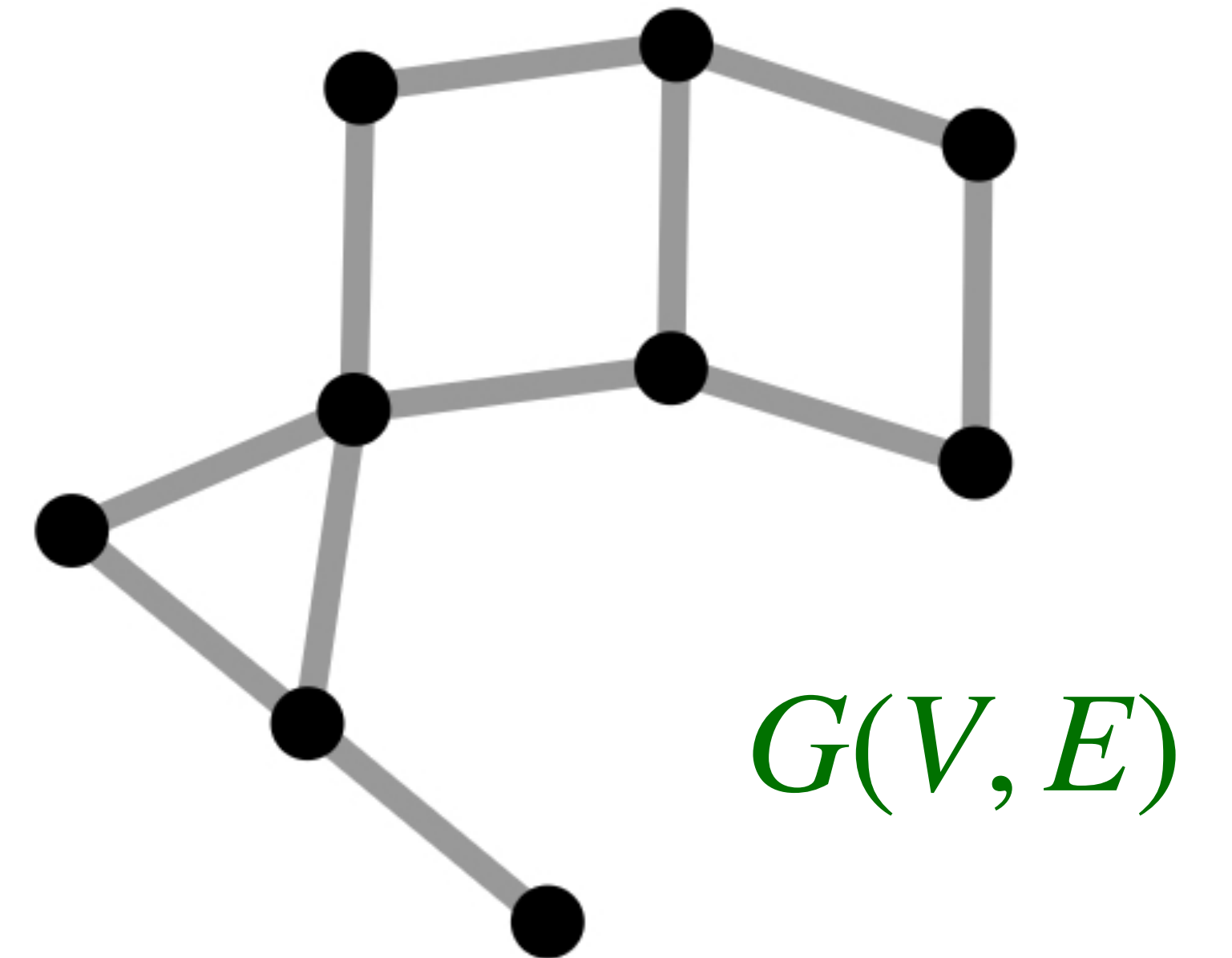
Forest Harvesting



Forest Harvesting

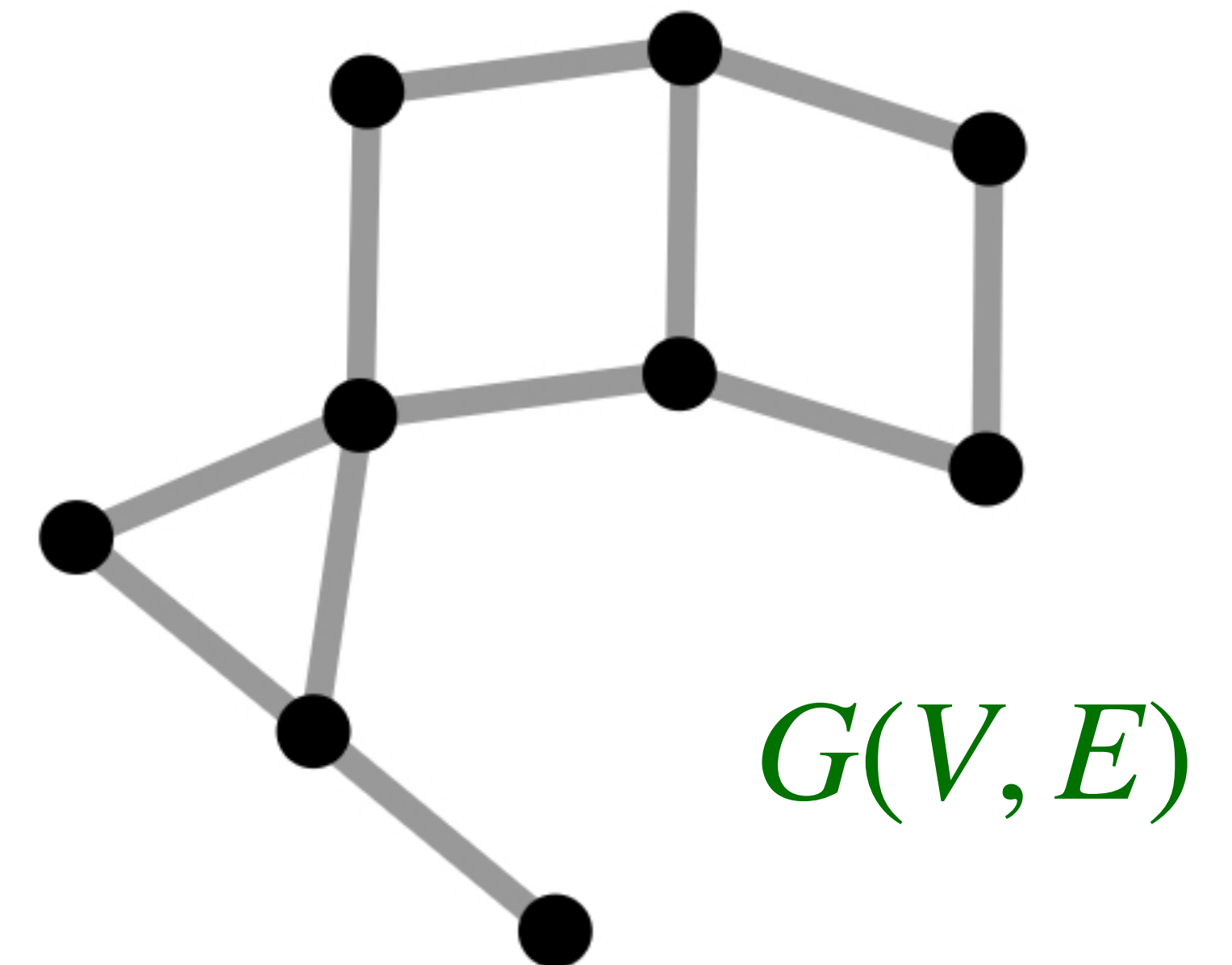


Forest Harvesting



Forest Harvesting

●
Goal: Harvest subset of parcels to maximize **revenue**; pay **cost** for harvesting adjacent parcels



Forest Harvesting

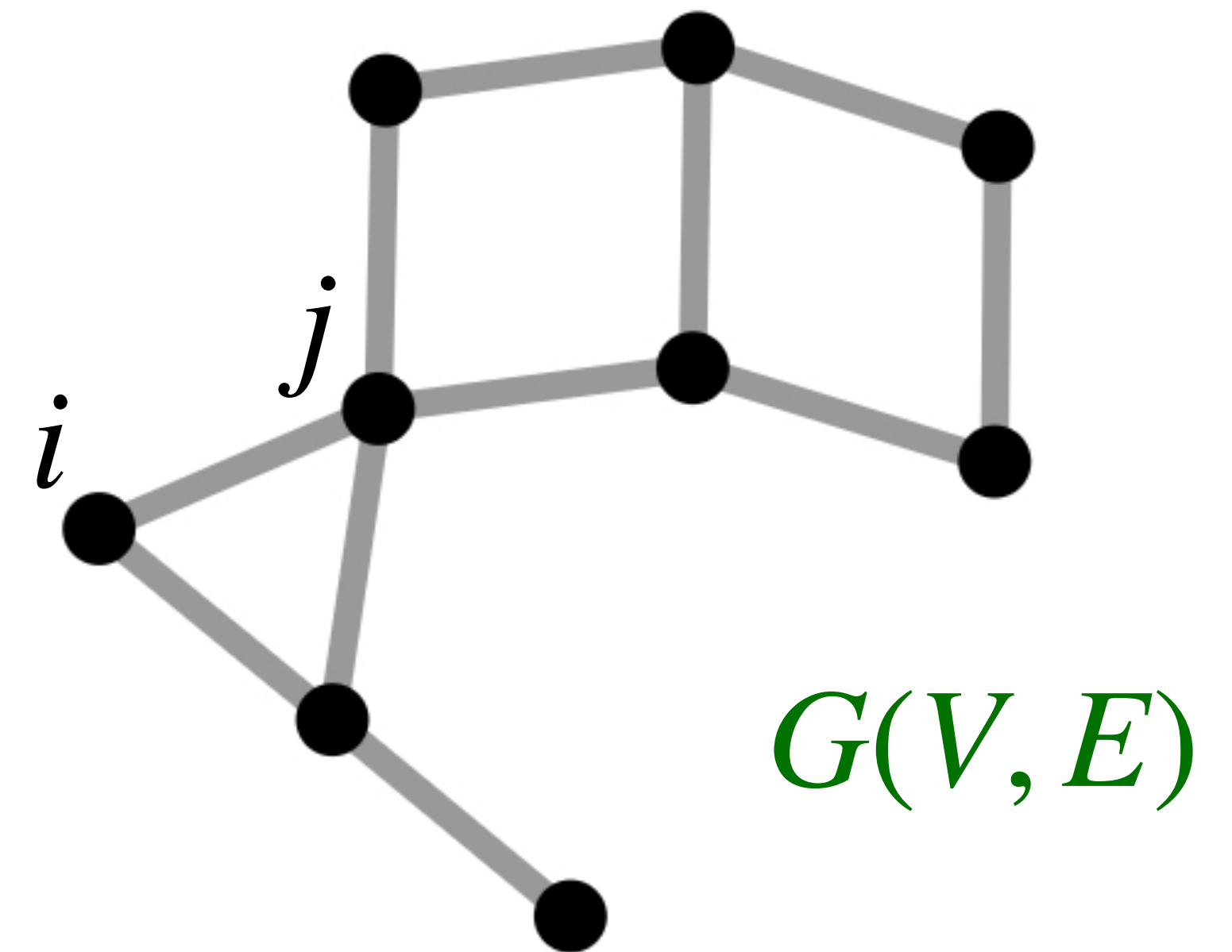
Goal: Harvest subset of parcels to maximize **revenue**; pay **cost** for harvesting adjacent parcels



maximize $\sum_{i \in V} r_i x_i - \sum_{(i,j) \in E} c_{ij} y_{ij}$

subject to $x_i + x_j - y_{ij} \leq 1$

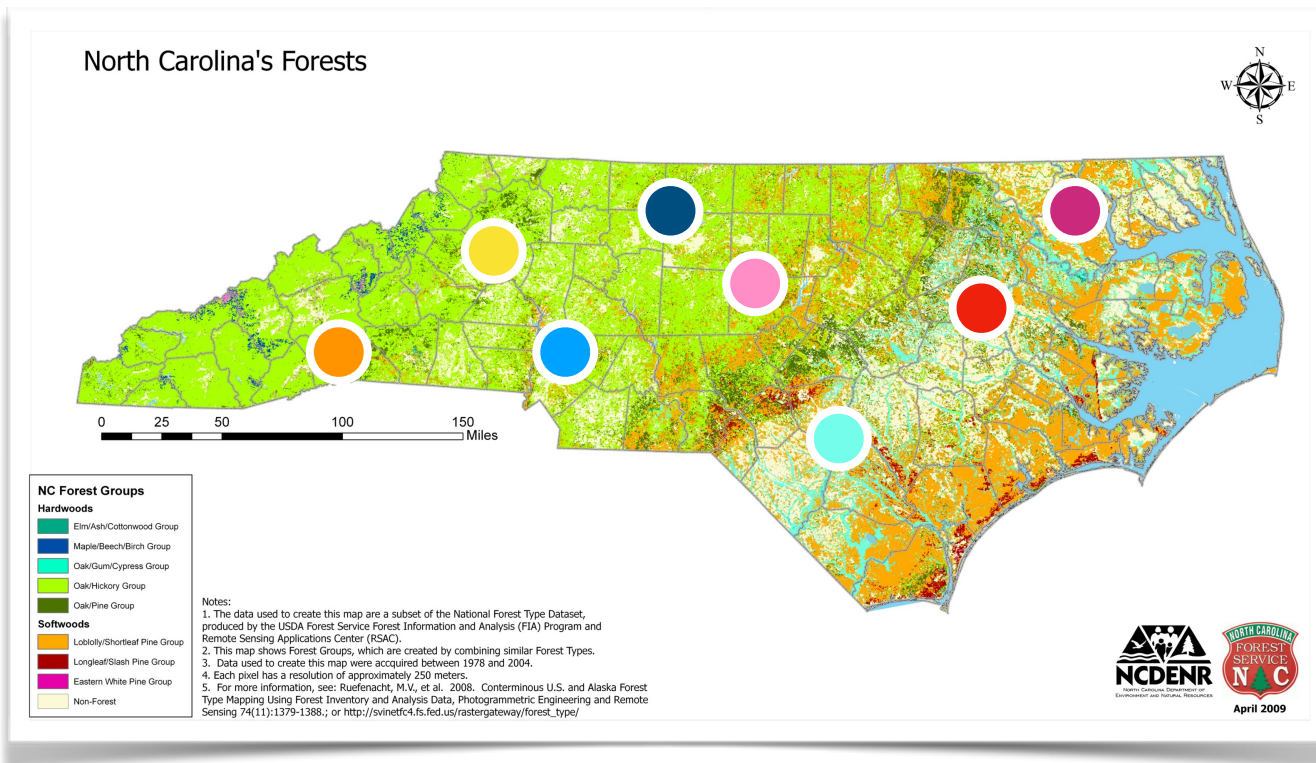
$x \in \{0,1\}^n, y \in \{0,1\}^m$



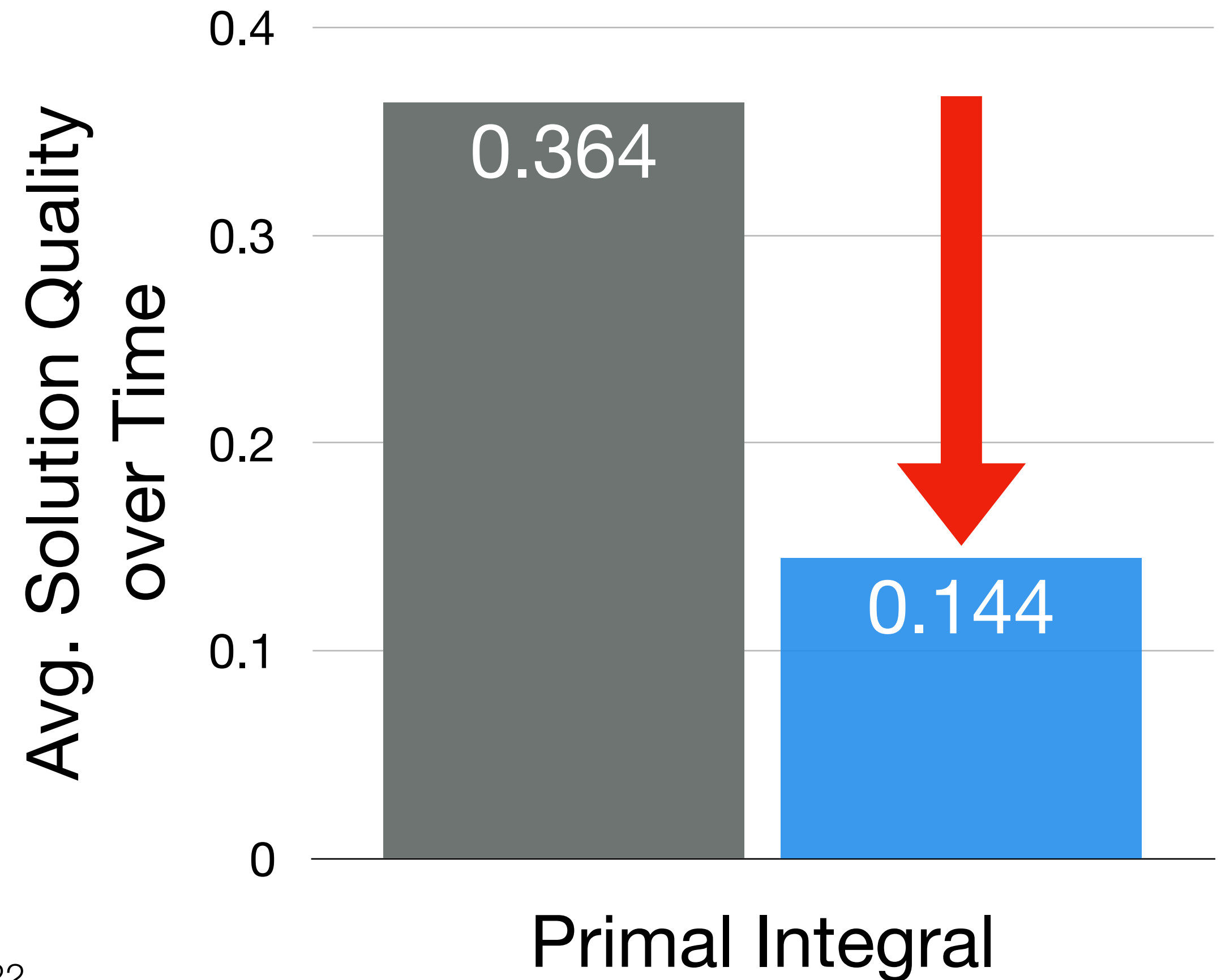
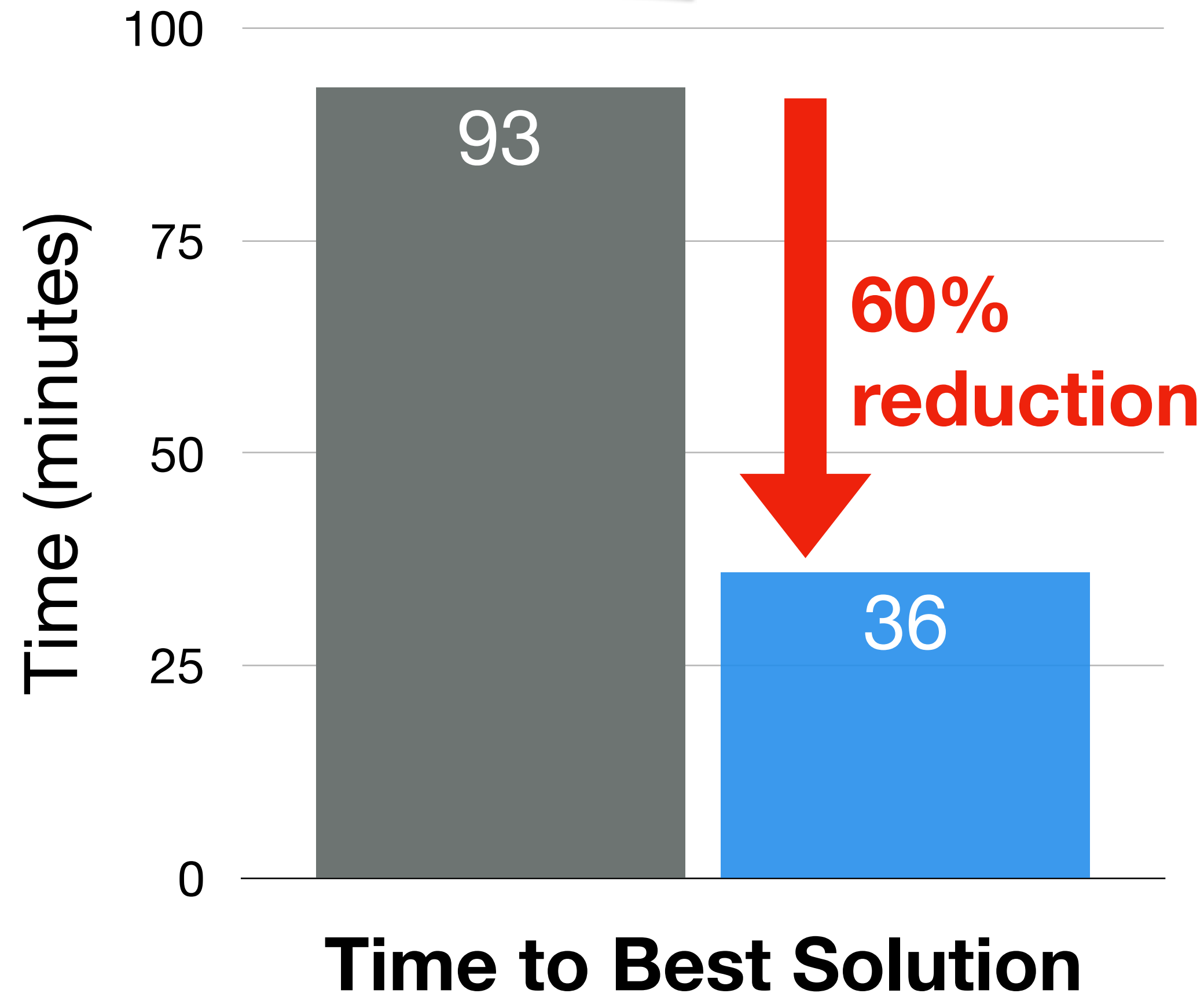
Heuristic Selection in Practice

Generalized Independent Set

$$\begin{aligned} &\text{maximize} \sum_{i \in V} r_i x_i - \sum_{(i,j) \in E} c_{ij} y_{ij} \\ &\text{subject to } x_i + x_j - y_{ij} \leq 1 \\ &\quad x \in \{0,1\}^n, y \in \{0,1\}^m \end{aligned}$$



■ Default SCIP ■ Learned



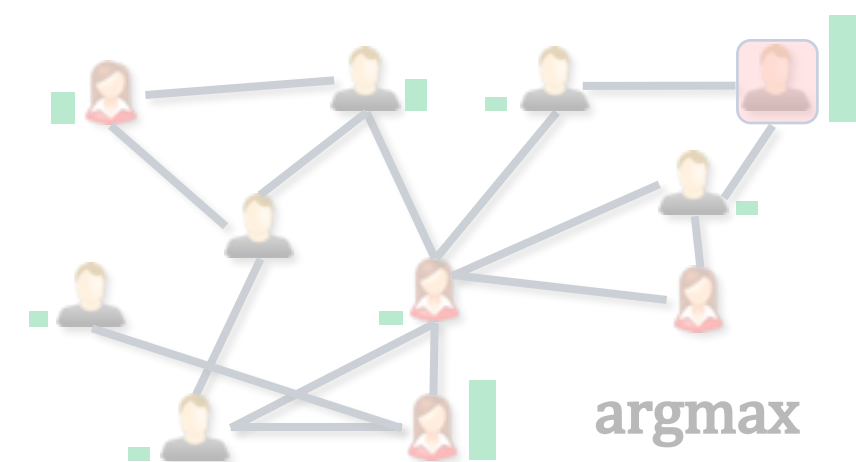
ML Paradigm

Self-Supervised Learning ■

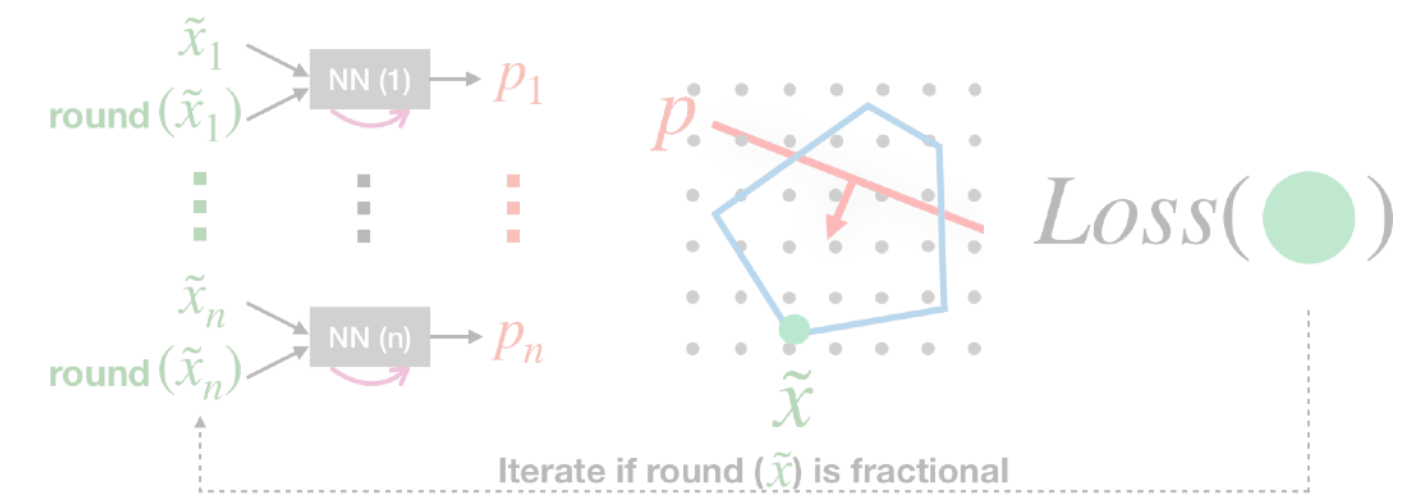
Reinforcement Learning ■

Supervised Learning ■

Greedy Heuristic

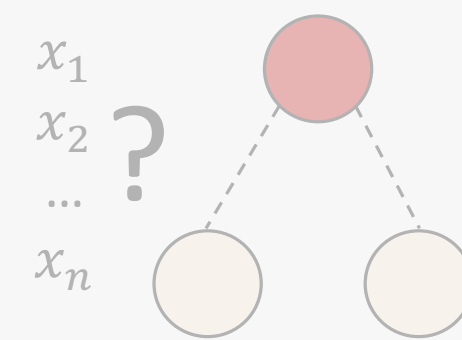


General IP Heuristic

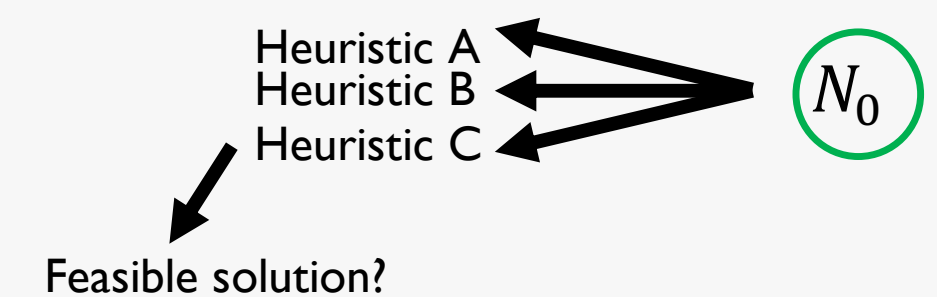


Exact Solving

Branching



Heuristic Selection



Graph Optimization

Integer Programming

Problem Type

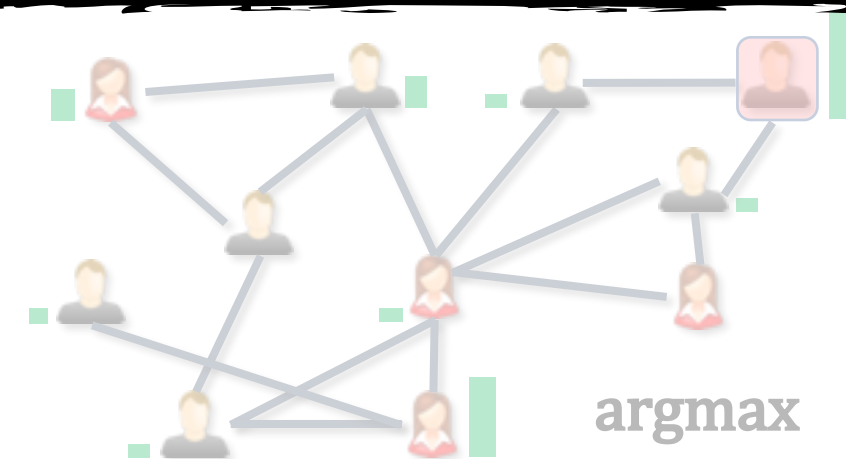
Takeaways

- ▶ **First ML framework for heuristic selection in B&B**
- ▶ **Dynamic, node-dependent decision-making**
- ▶ **Forest Harvesting: 60% reduction** in Primal Integral
- ▶ Even on the heterogeneous **MIPLIB2010** Benchmark:
6% reduction in Primal Integral

Self-S

Reinforcement Learning

Supervised Learning

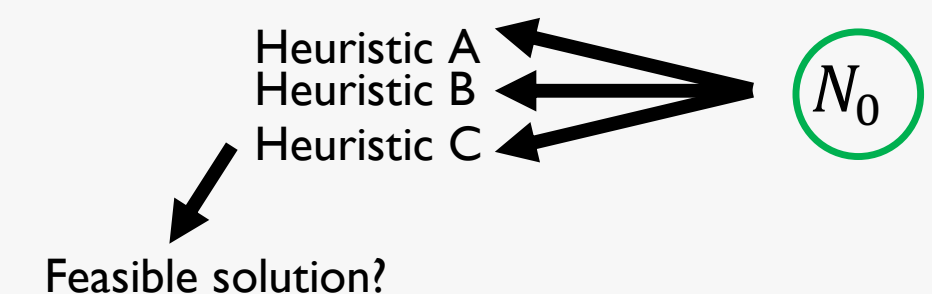
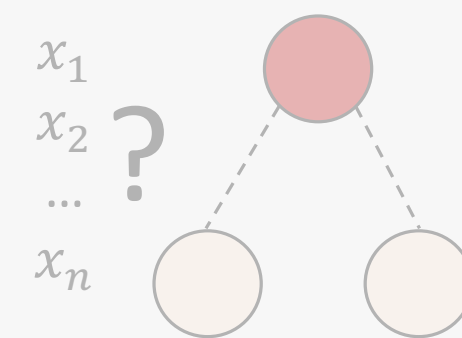


Graph Optimization

Exact Solving

Branching

Heuristic Selection



Integer Programming

Problem Type

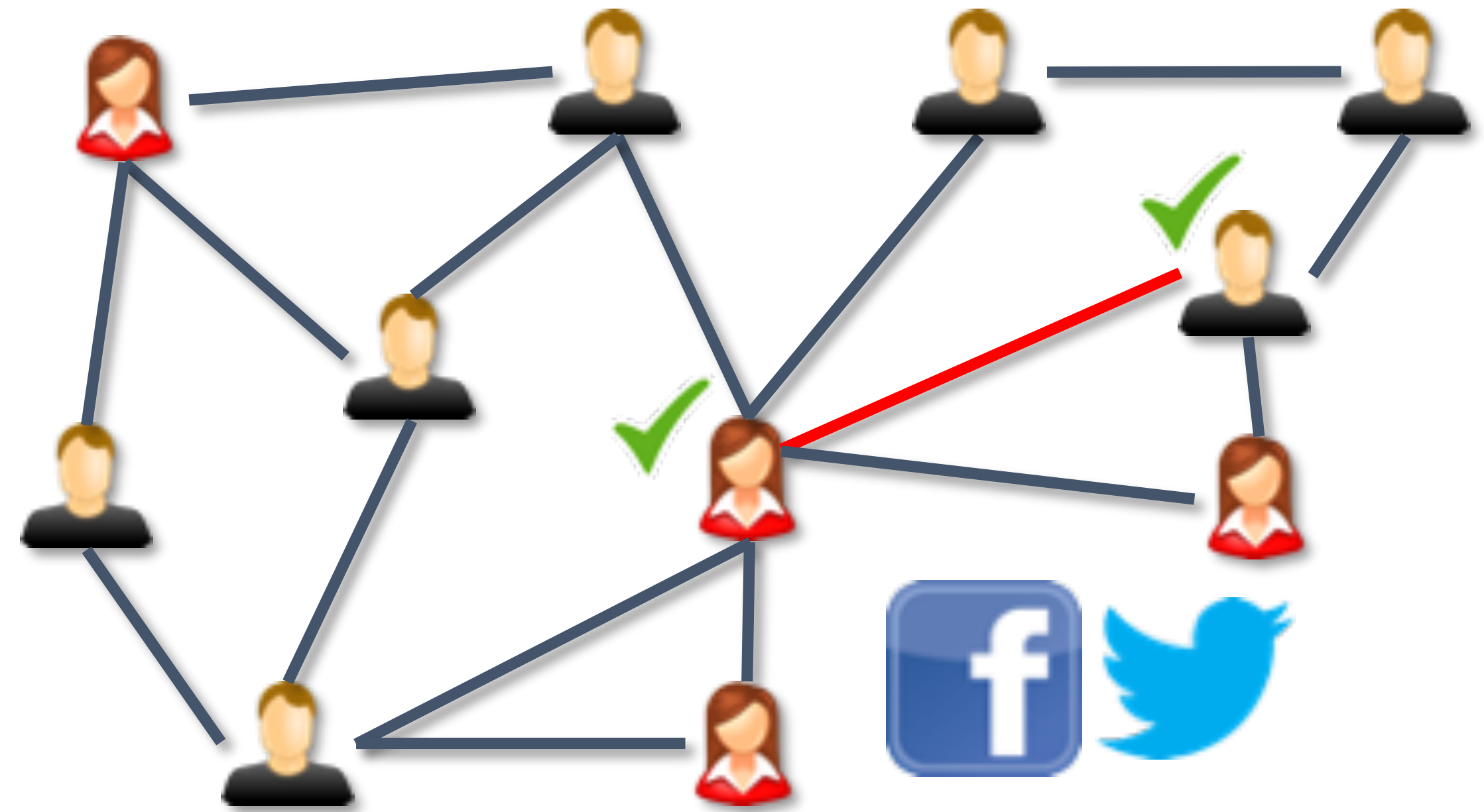
Greedy Graph Optimization

Minimum Vertex Cover

Find smallest vertex subset such that each edge is covered

2-Approximation:

Greedy add vertices of edge with **max degree sum**



Greedy Graph Optimization

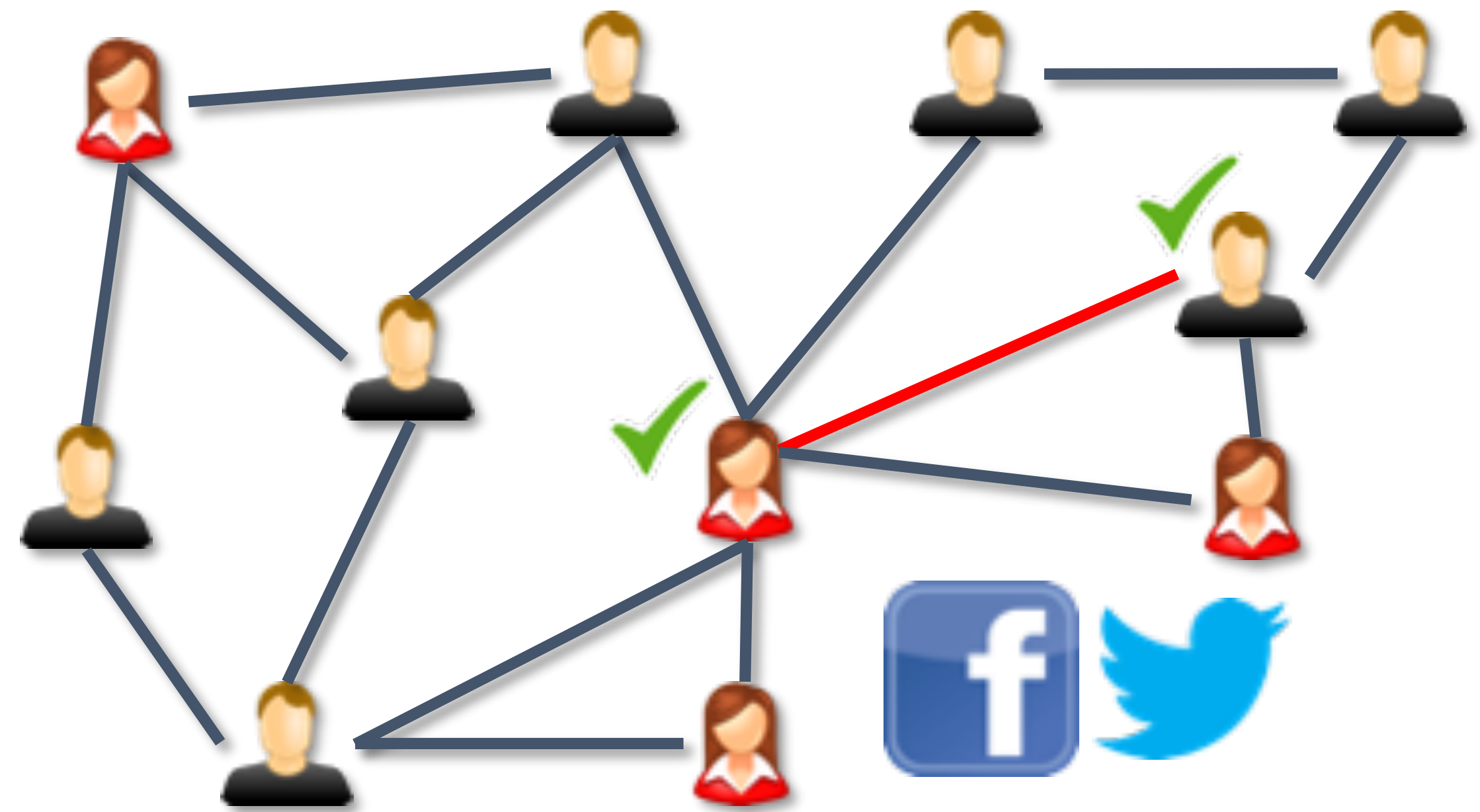
Minimum Vertex Cover

Find smallest vertex subset such that each edge is covered

Learning Greedy Graph Heuristics
[Dai*, Khalil*, Zhang, Dilkina, Song, 2017]

Given: graph problem, family of graphs

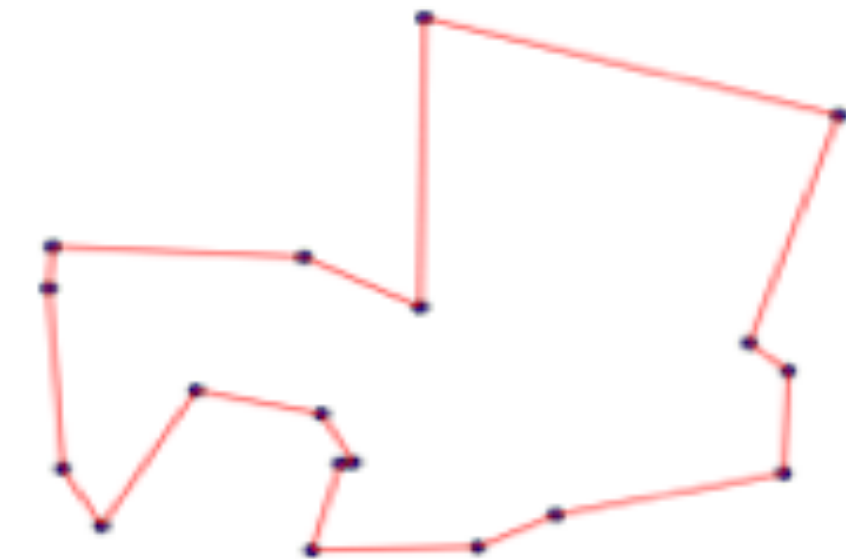
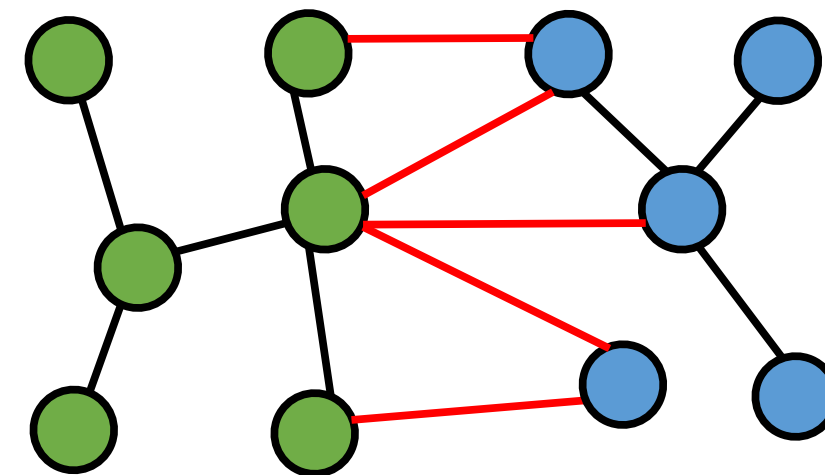
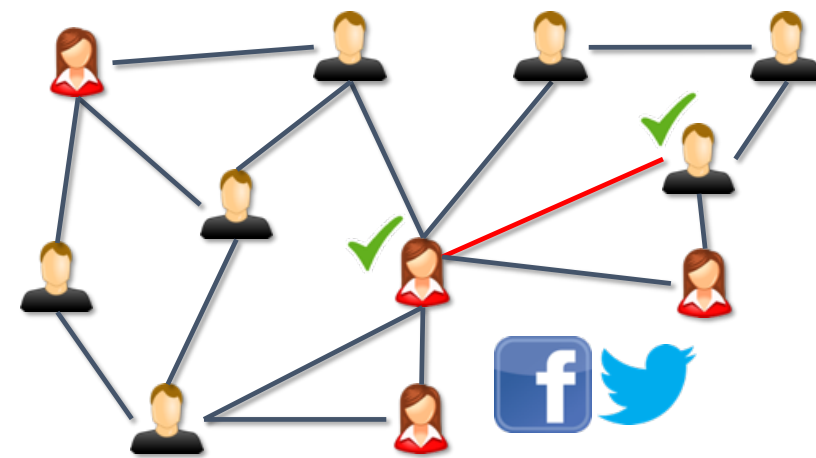
Learn: a **scoring function** to **guide** a **greedy** algorithm



Learning Greedy Heuristics

Given: graph problem, family of graphs
Learn: a **scoring function** to **guide** a **greedy** algorithm

Problem	Minimum Vertex Cover	Maximum Cut	Traveling Salesman Problem
Domain	Social network snapshots	Spin glass models	Package delivery
Greedy operation	Insert nodes into cover	Insert nodes into subset	Insert nodes into sub-tour



Reinforcement Learning

Greedy Algorithm Reinforcement Learning

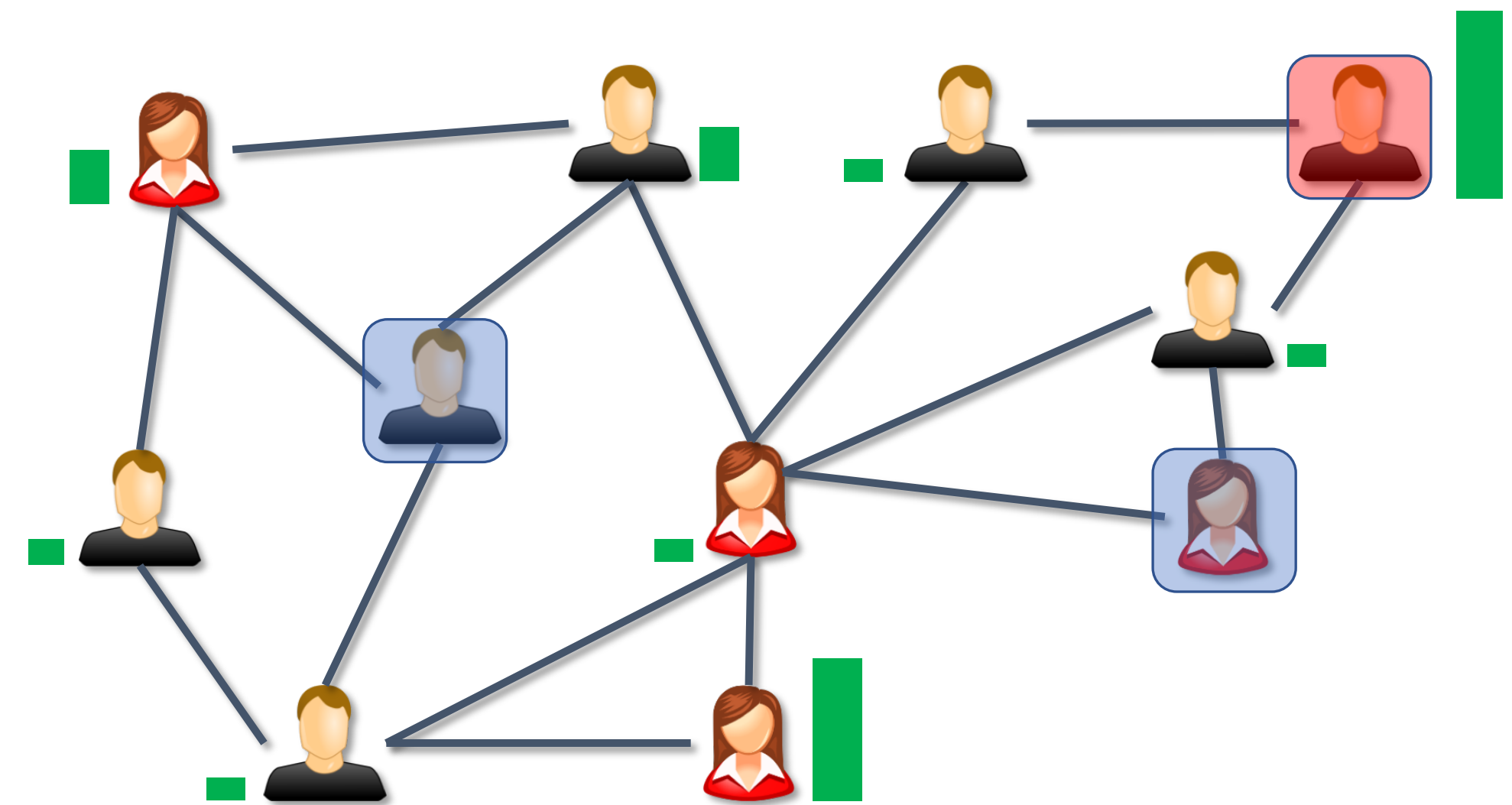
Partial solution \equiv State

Scoring function \equiv Q-function

Select **best node** \equiv Greedy Policy

Repeat until all edges are covered:

1. Compute node **scores**
2. Select **best node** w.r.t. **score**
3. Add **best node** to **partial sol.**

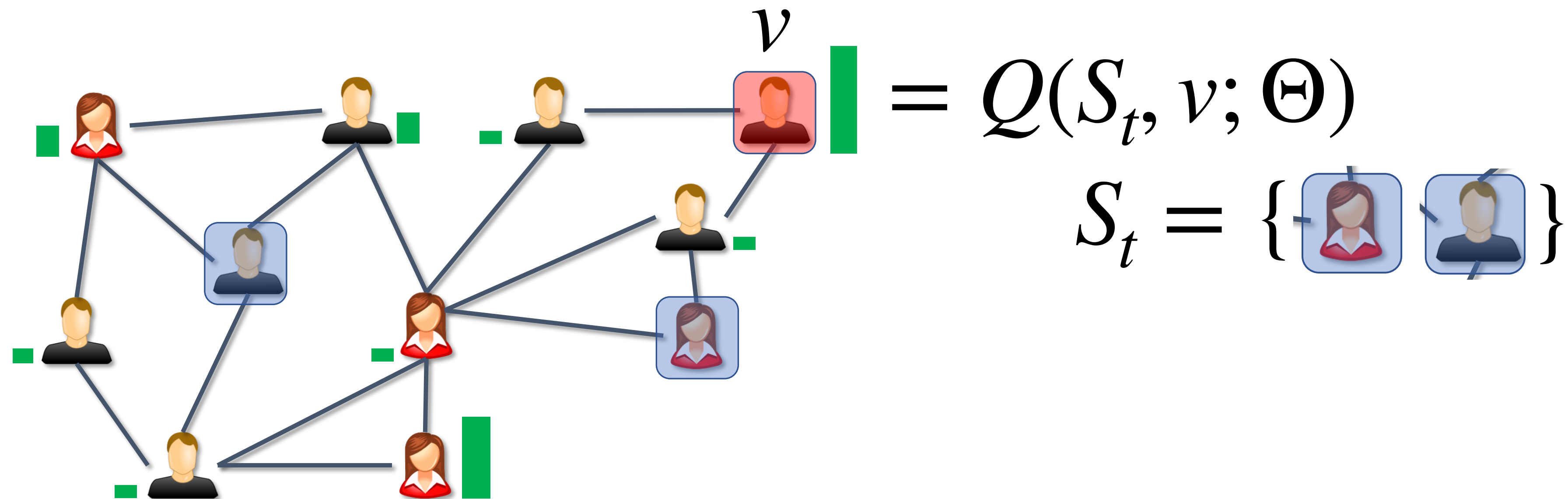


Partial Solution



Learning Node Features

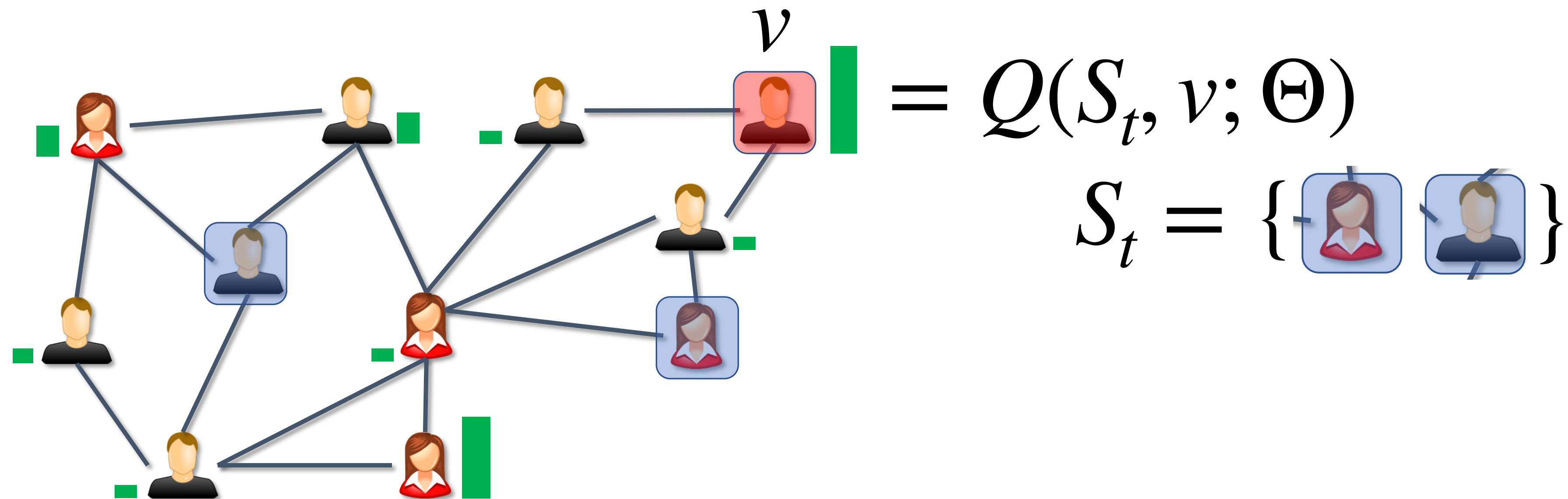
Scoring Function: Need to represent node with a **feature vector** first



Learning Node Features

Scoring Function: Need to represent node with a **feature vector** first

Problem: Not clear what good node features are!

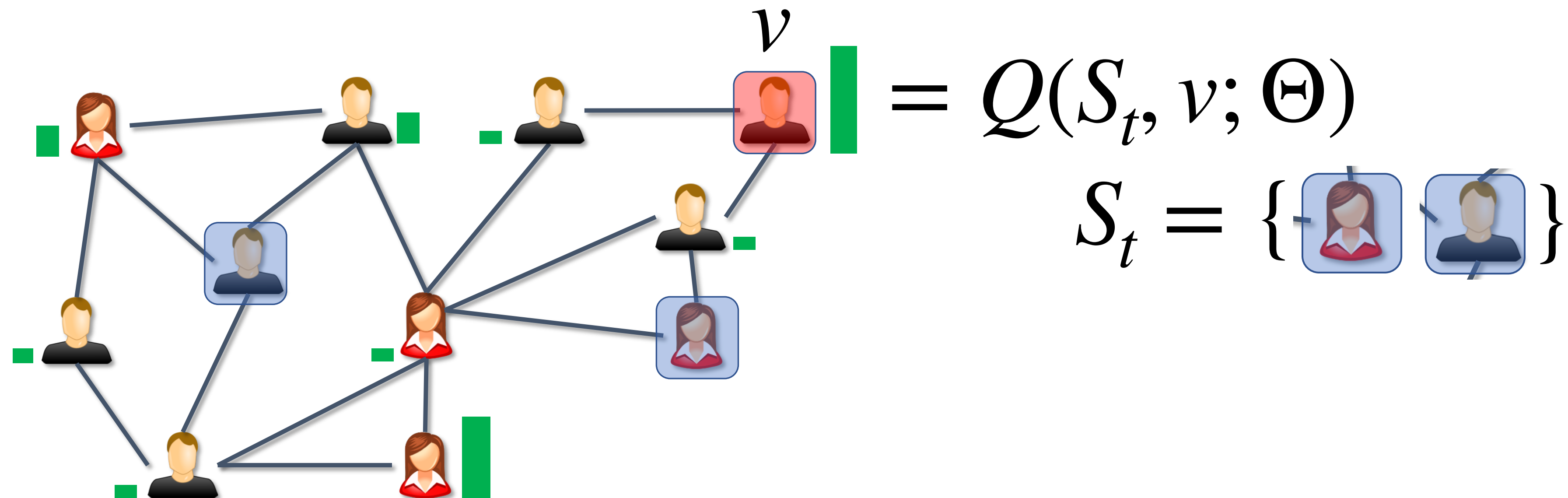


Learning Node Features

Scoring Function: Need to represent node with a **feature vector** first

Problem: Not clear what good node features are!

Solution: Parametrize a **Graph Neural Network** with parameters Θ



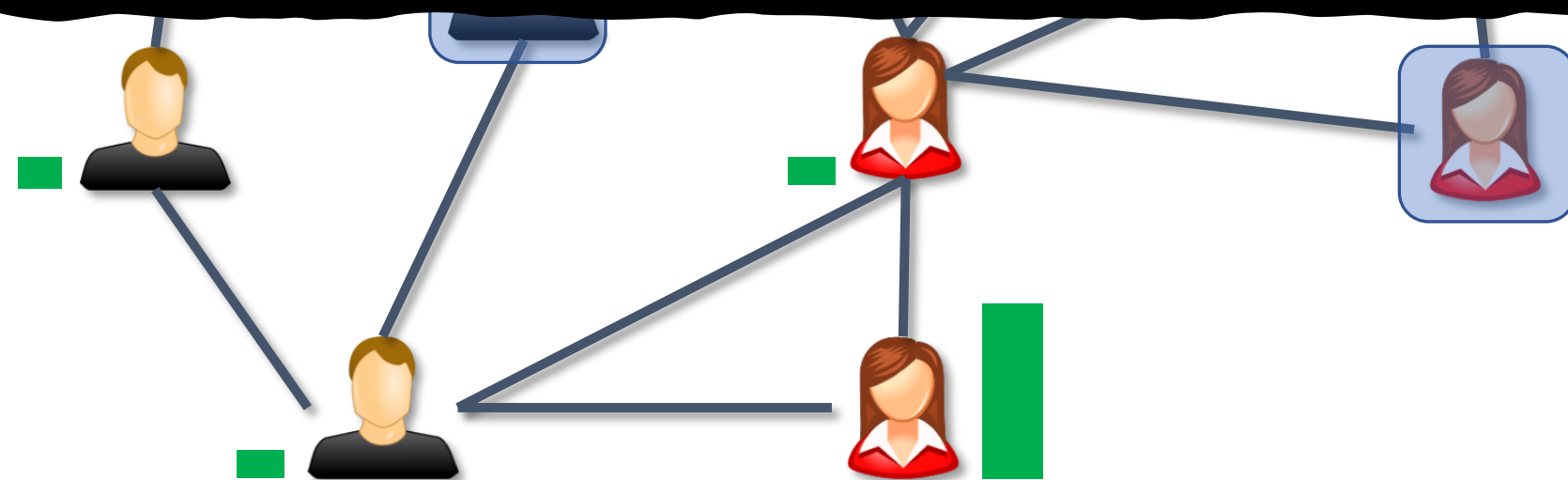
Learning Node Features

Scoring Function: Need to represent node with a **feature vector** first

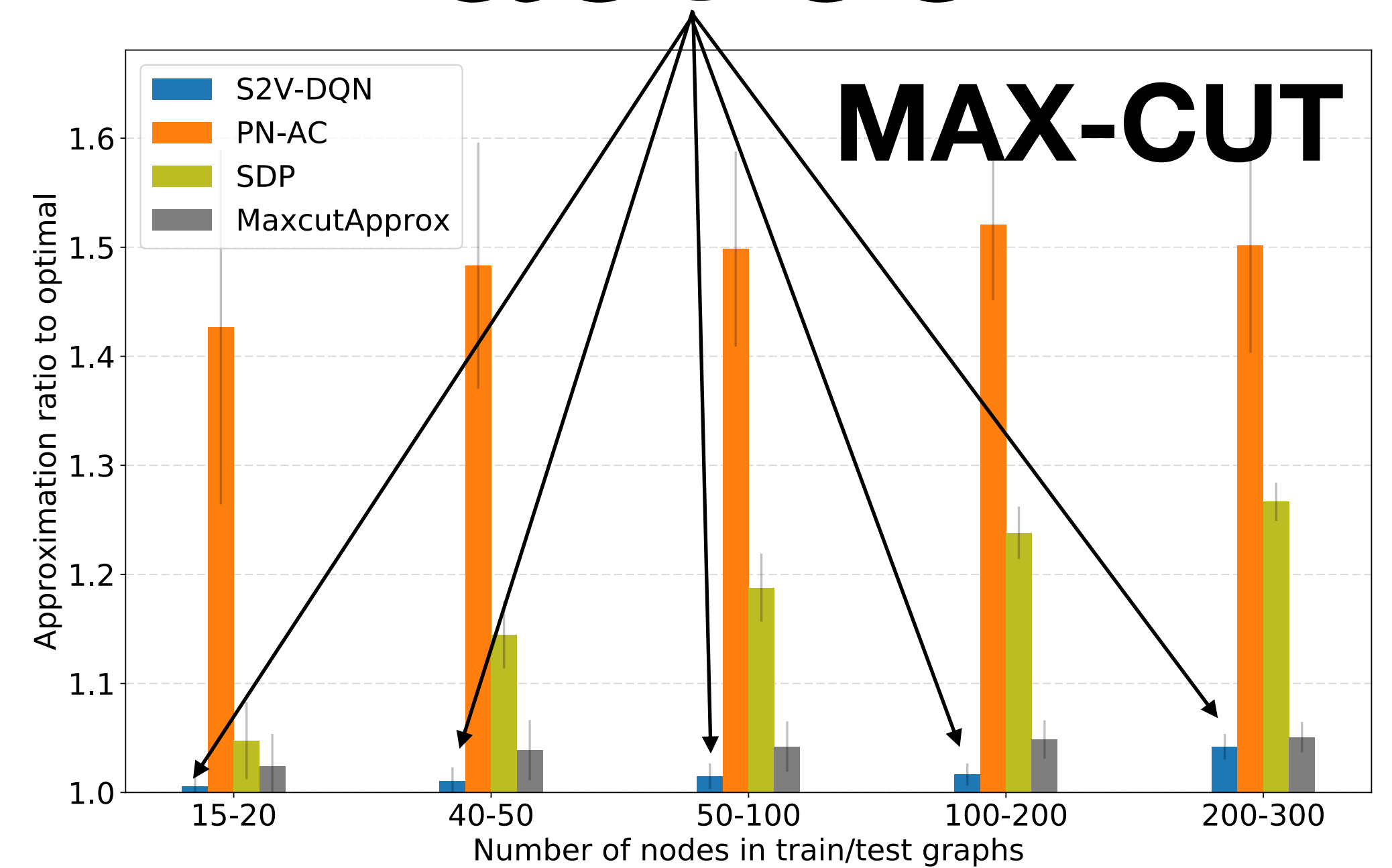
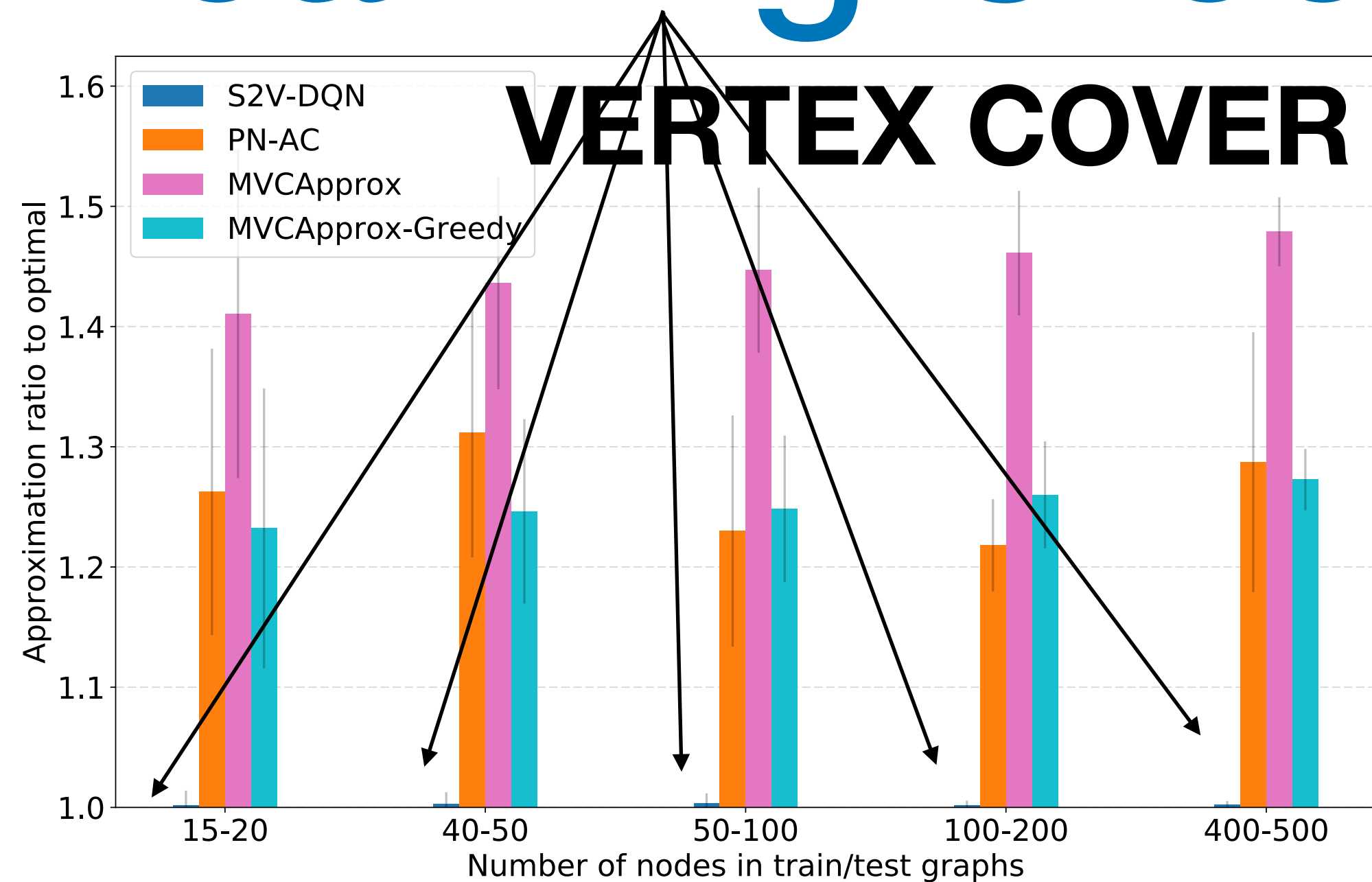
Problem: Not clear what good node features are!

Solution: Parametrize a **Graph Neural Network** with parameters Θ

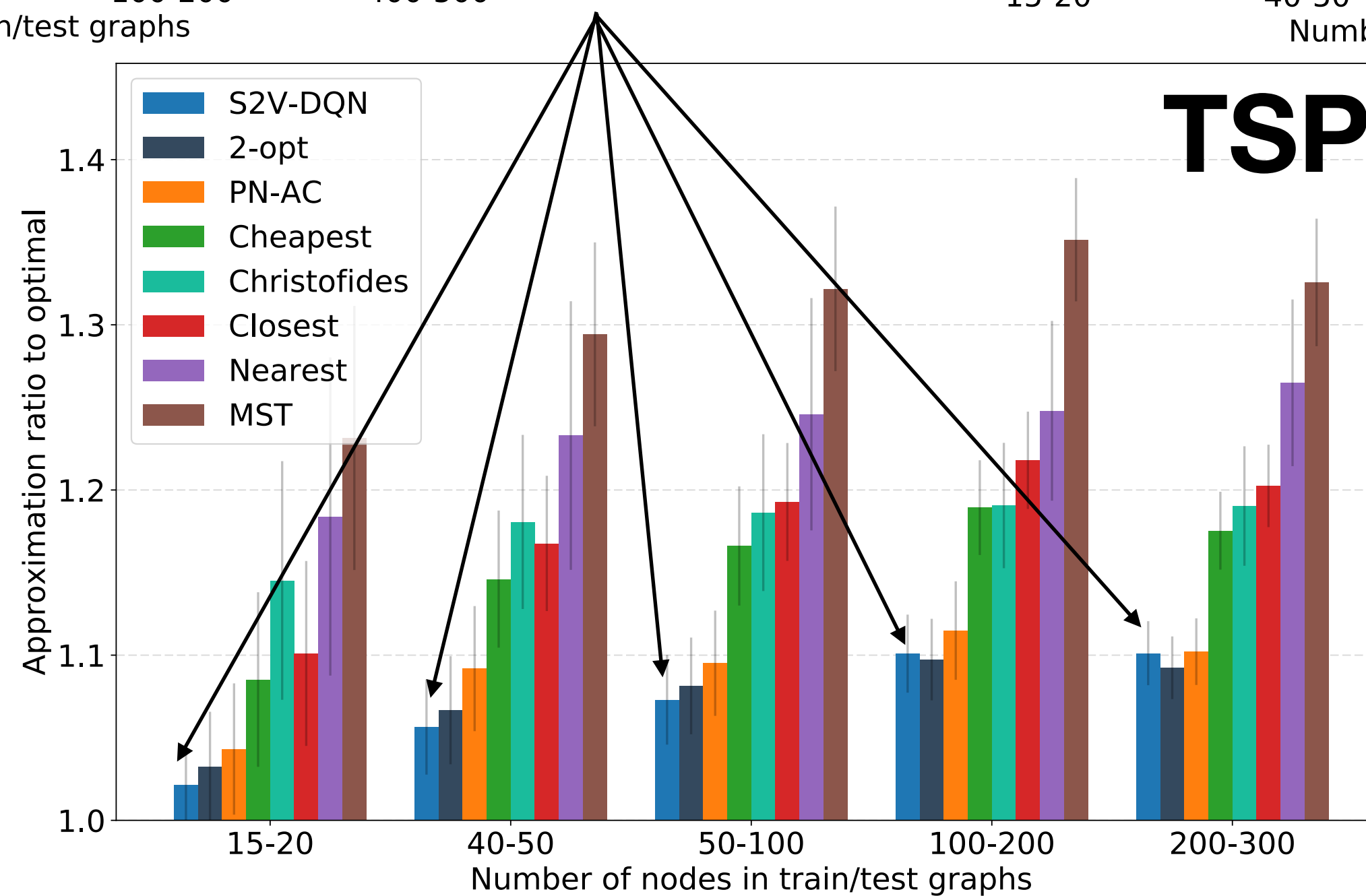
Run RL algorithm (e.g. Q-Learning)
Use gradient of solution cost to update Θ



Learning Greedy in Practice



**Approximation
Ratio**



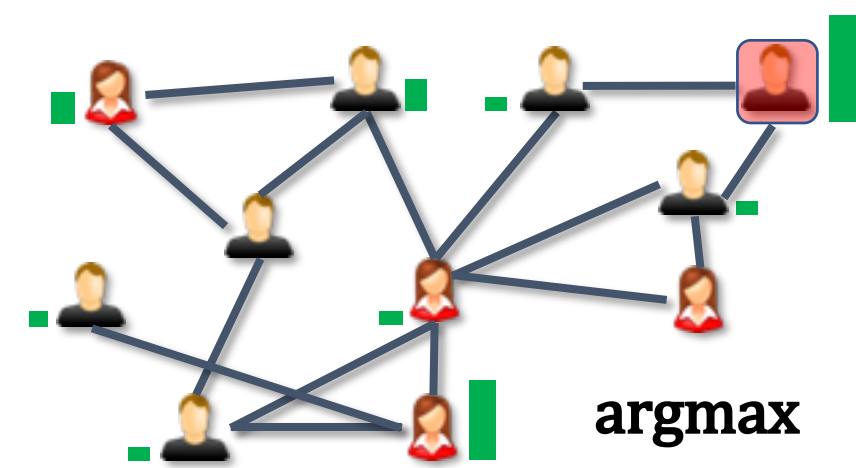
ML Paradigm

Self-Supervised Learning ■

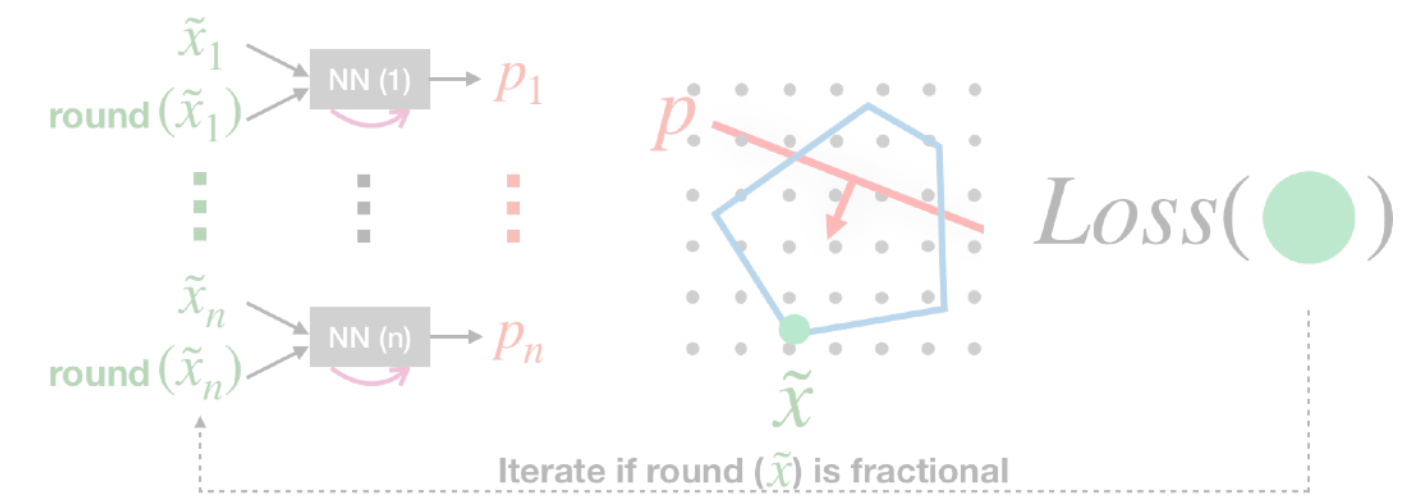
Reinforcement Learning ■

Supervised Learning ■

Greedy Heuristic

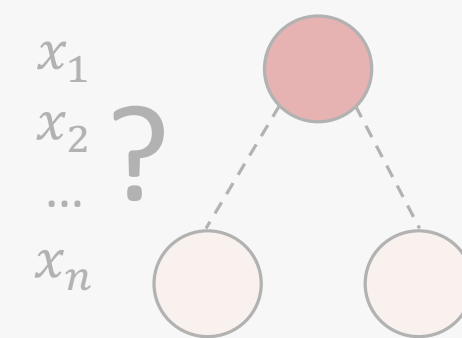


General IP Heuristic

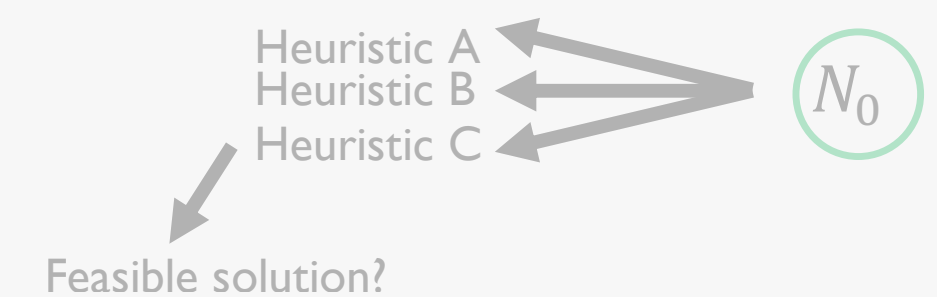


Exact Solving

Branching



Heuristic Selection



Graph Optimization

Integer Programming

Problem Type

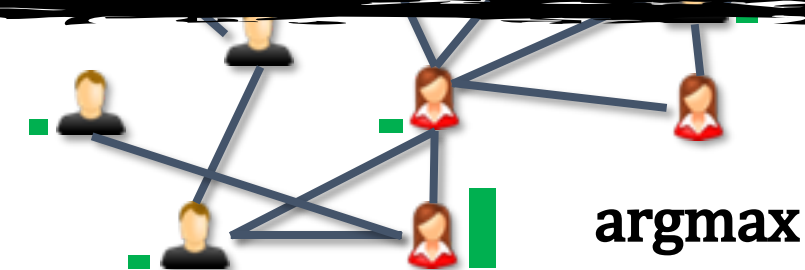
Takeaways

- ▶ **Reinforcement Learning** tailors **greedy** search to your instances
- ▶ Learn **features jointly with greedy policy**
- ▶ **Human priors** encoded via (greedy) **meta-algorithm**
- ▶ **Interesting, novel strategies** emerge

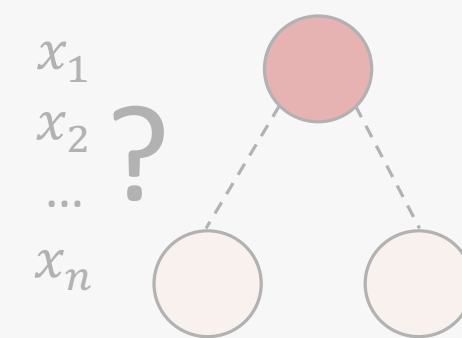
Self-S

Reint

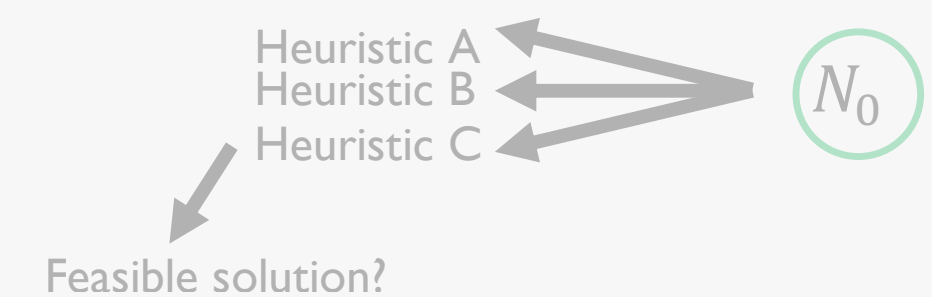
Supervised Learning



Branching



Heuristic Selection



Graph Optimization

Integer Programming

Problem Type



Power Systems

...



**Data Center
Resource Management**

...



Airline Scheduling

$$\min_x c^T x \quad \mathbf{s.t.} \quad Ax \leq b, x \in \{0,1\}^n$$

General Heuristic

Feasible Solution

General IP Heuristics



Power Systems

...

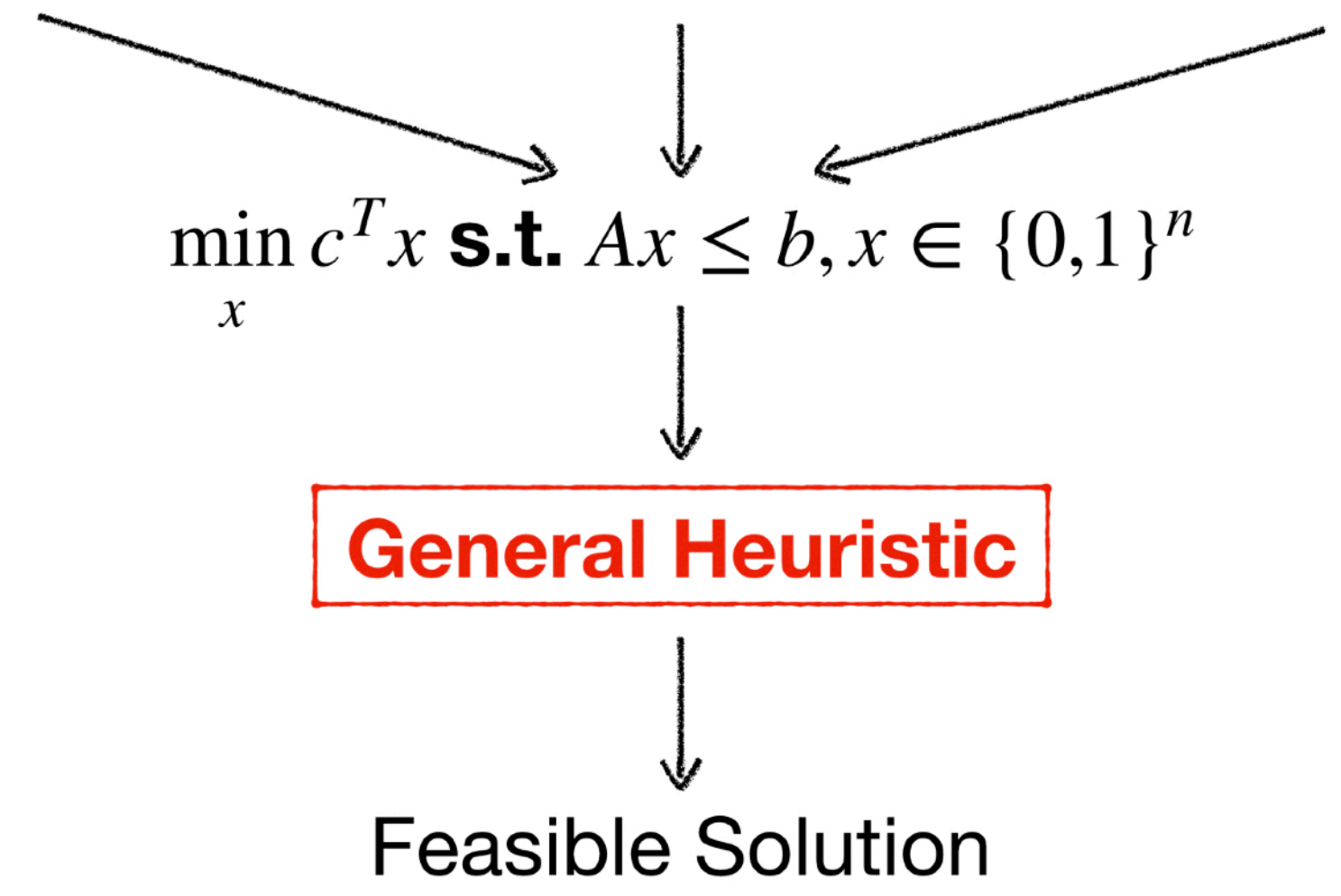


Data Center
Resource Management

...



Airline Scheduling



General IP Heuristics

Strengths



Power Systems

...

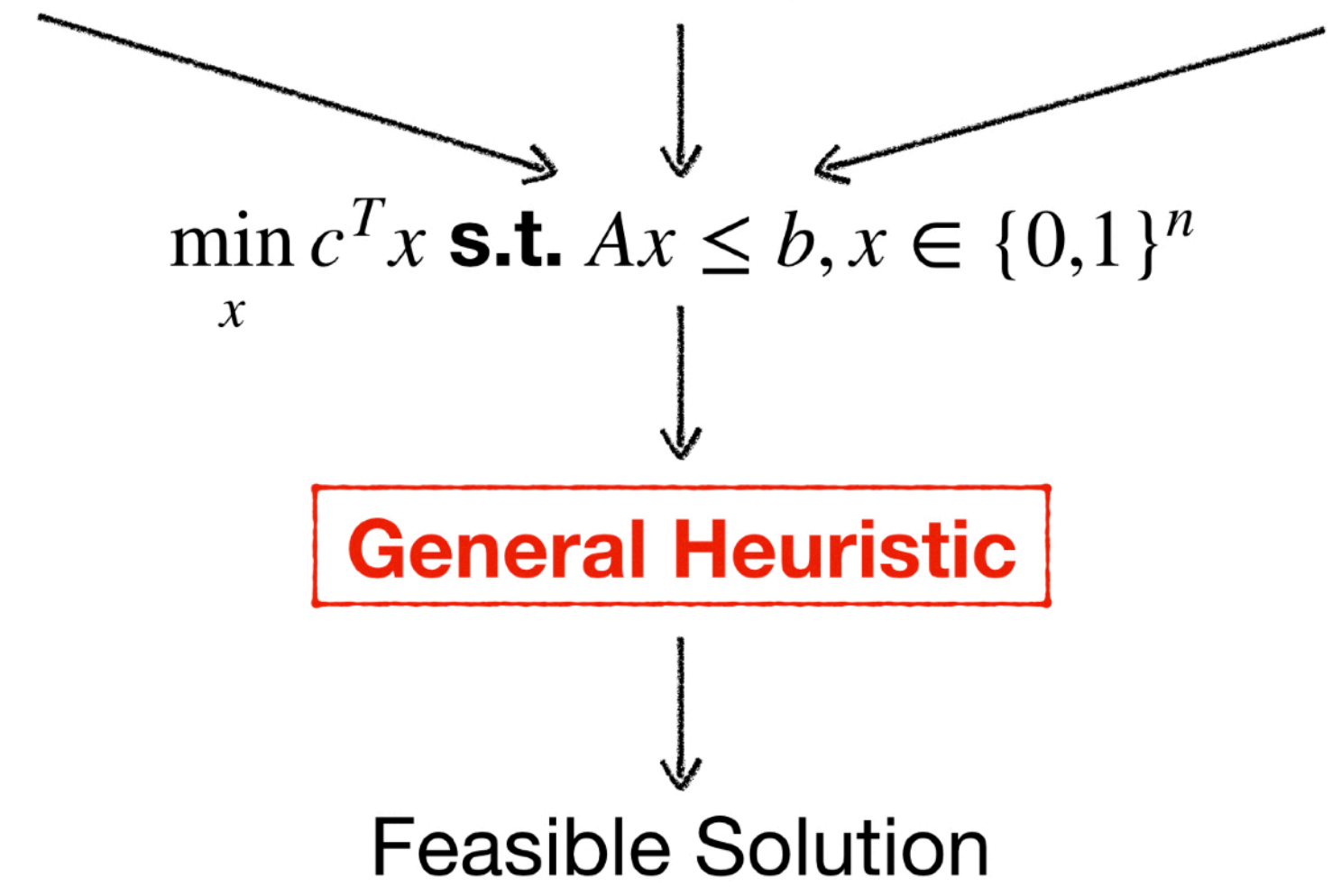


Data Center
Resource Management

...



Airline Scheduling



General IP Heuristics

Strengths

- Applicable to many problems
- Usable inside Branch-and-Bound



Power Systems

...

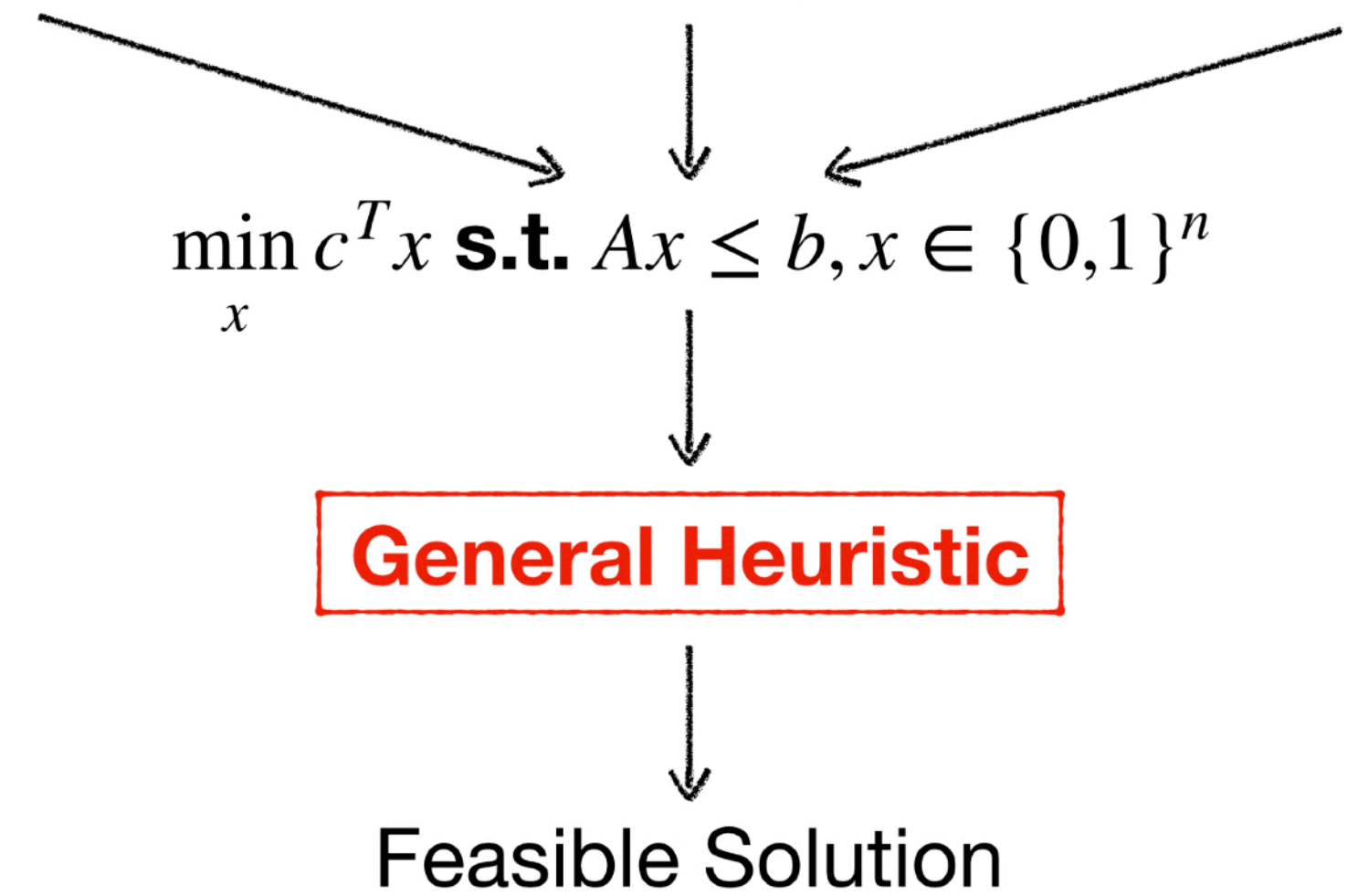


Data Center
Resource Management

...

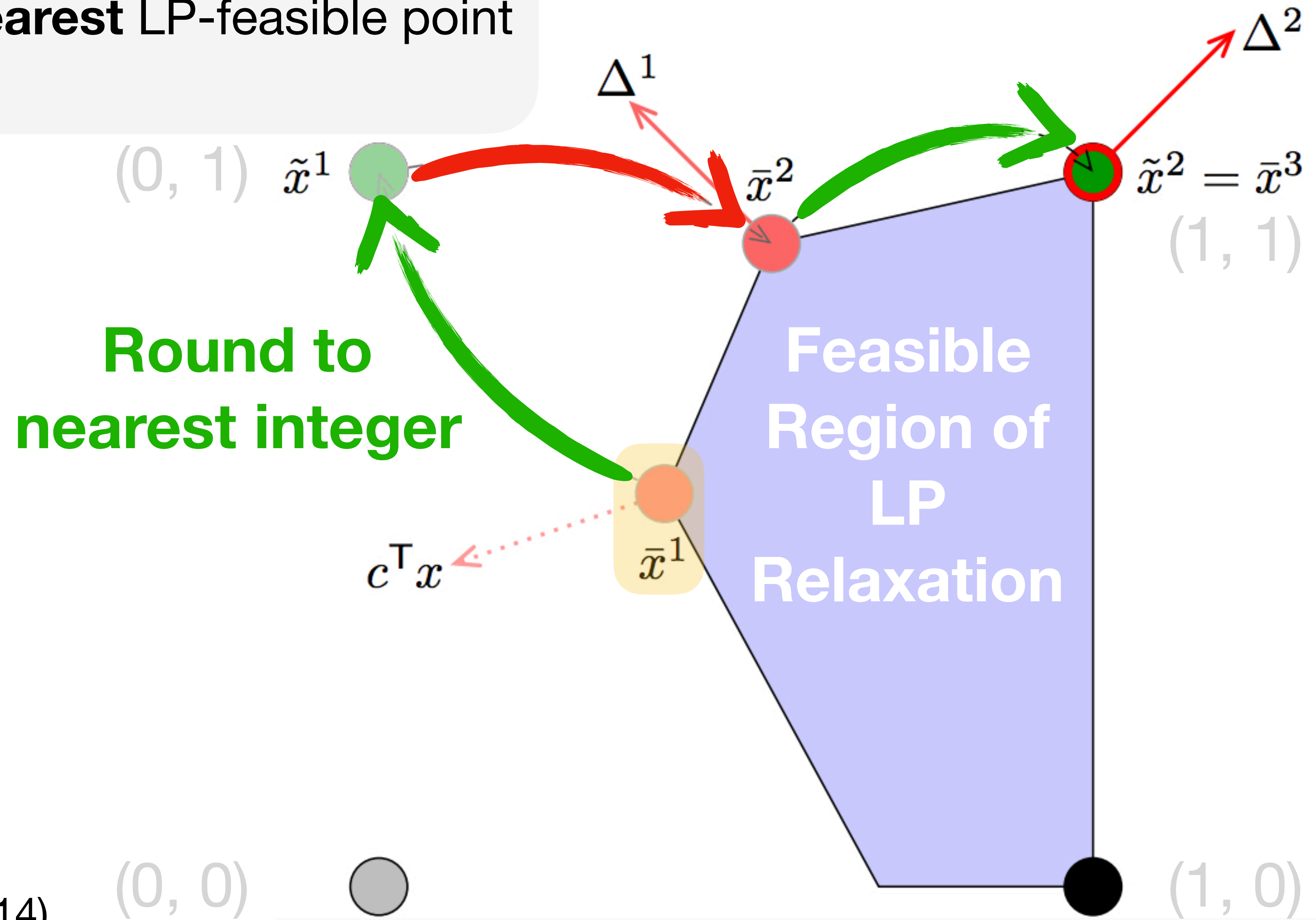


Airline Scheduling



Feasibility Pump

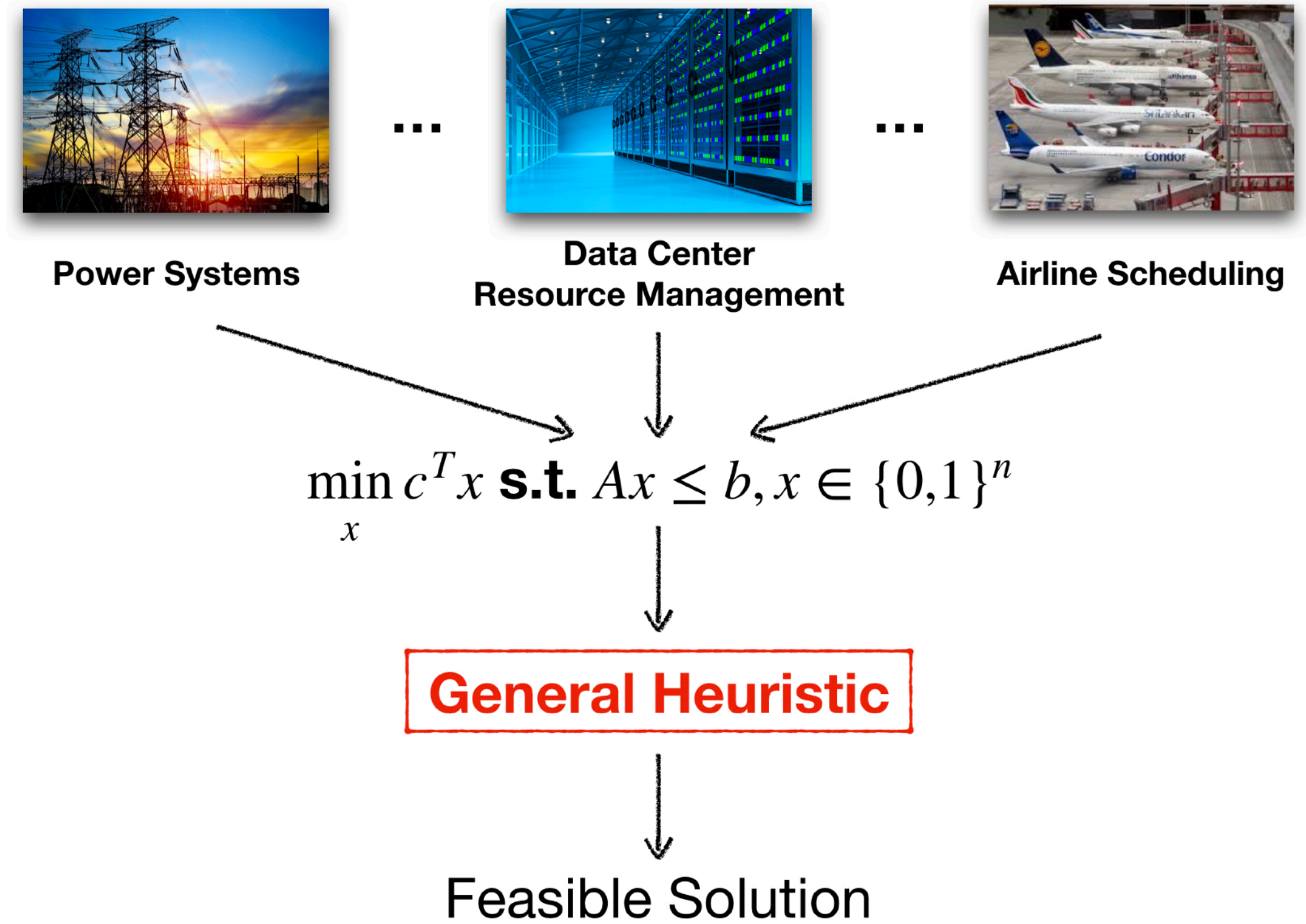
- 0 Start with LP-feasible (fractional) solution
- 1 **Round** to nearest integer, **return** if LP-feasible
- 2 **Project** integer point to **nearest** LP-feasible point
- 3 Go back to step 1



General IP Heuristics

Strengths

- Applicable to many problems
- Usable inside Branch-and-Bound

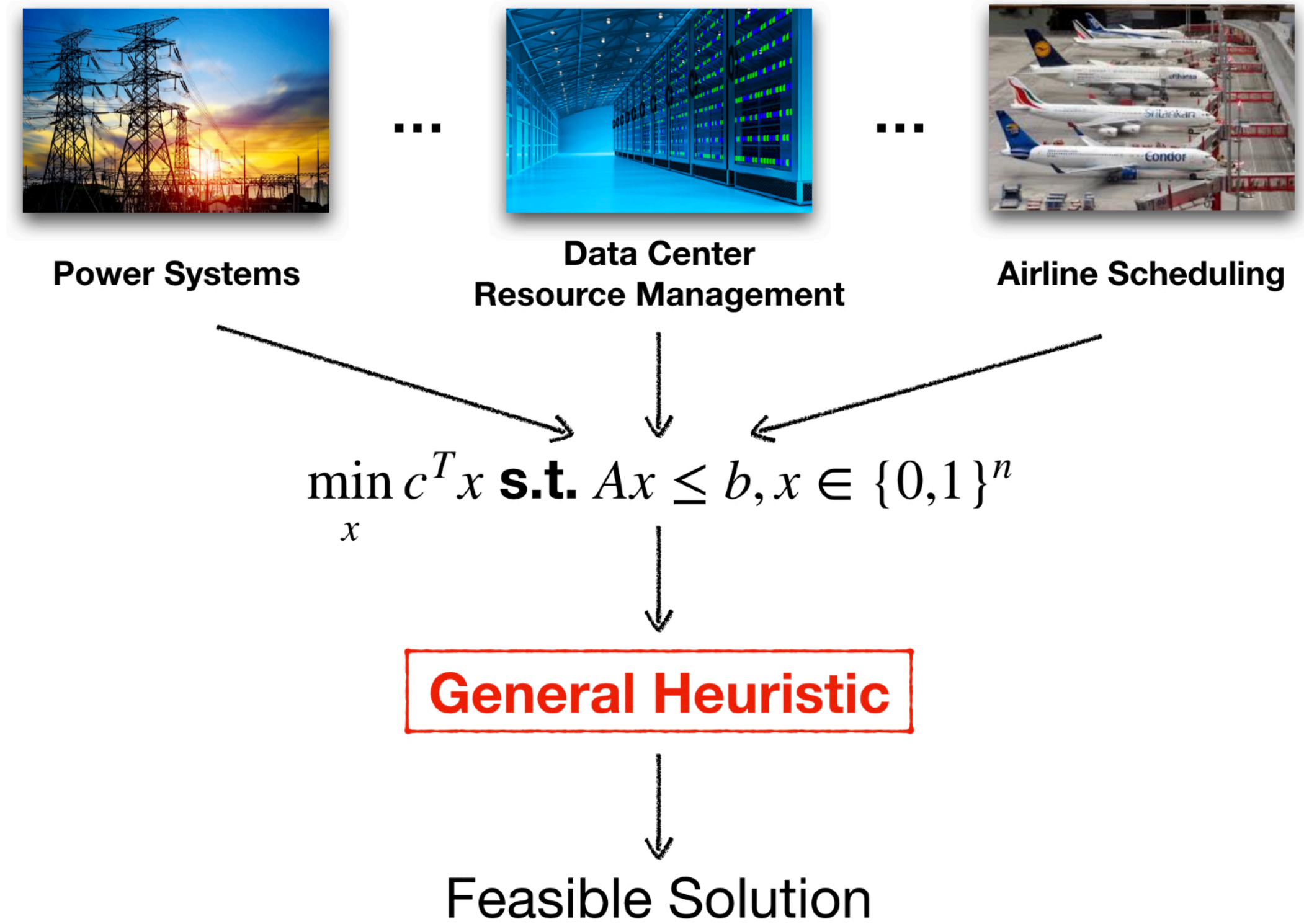


General IP Heuristics

Strengths

- Applicable to many problems
- Usable inside Branch-and-Bound

Weaknesses



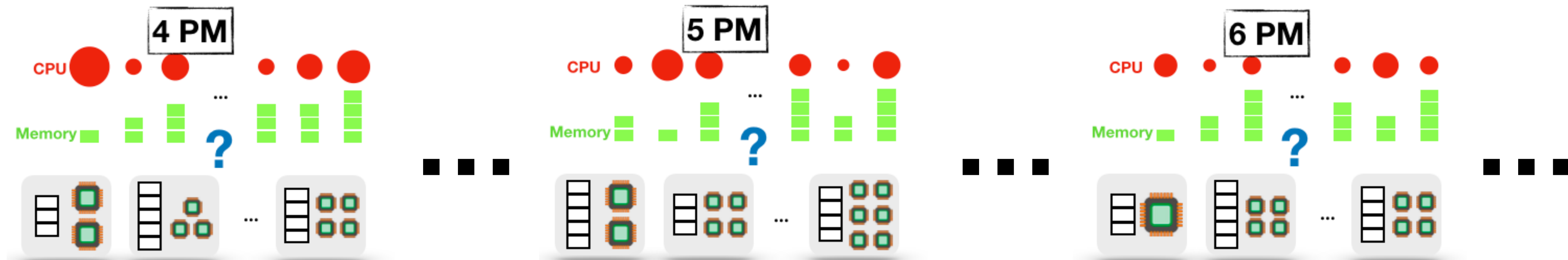
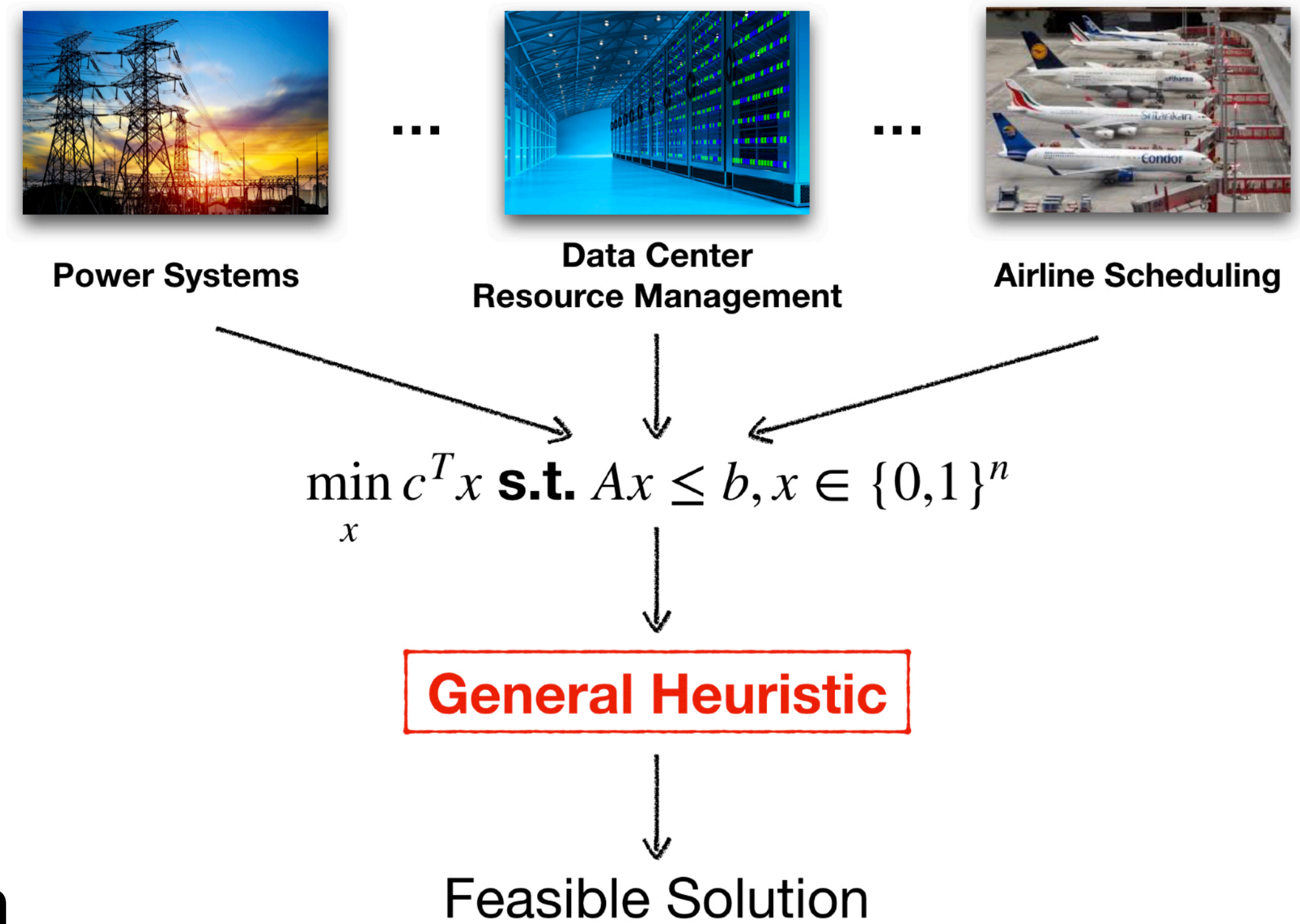
General IP Heuristics

Strengths

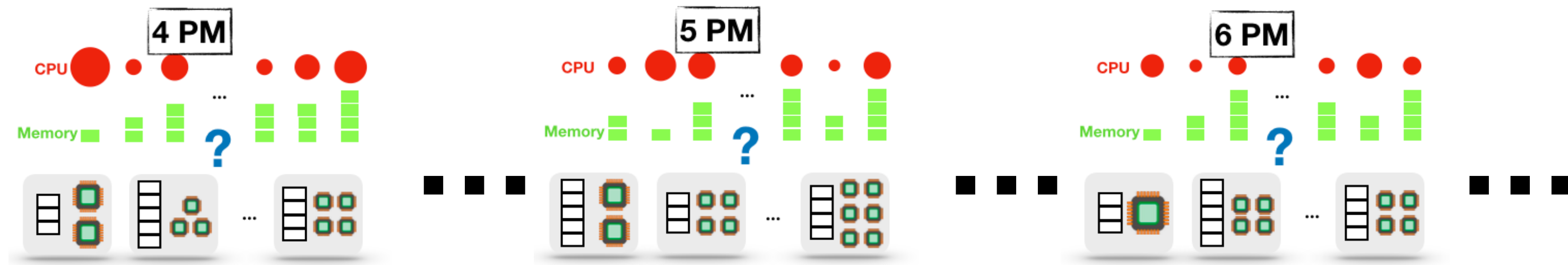
- Applicable to many problems
- Usable inside Branch-and-Bound

Weaknesses

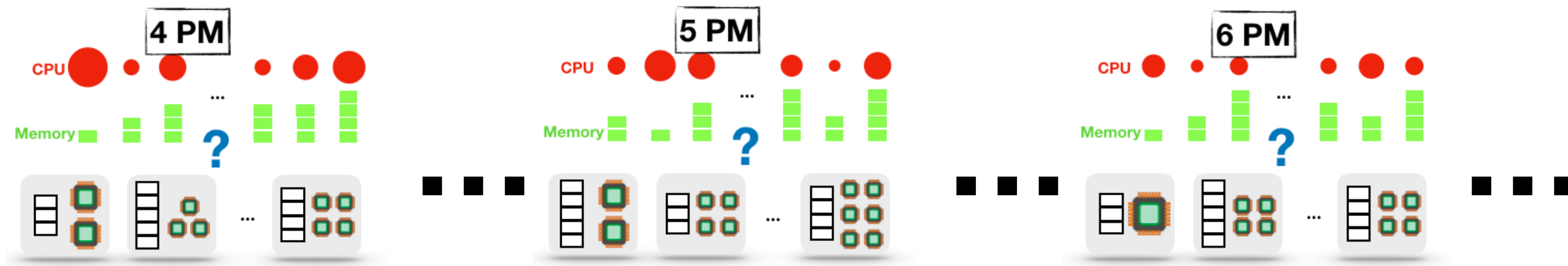
- May not work well for **your** problem
- Cannot exploit **distribution of instances**



Problem Statement

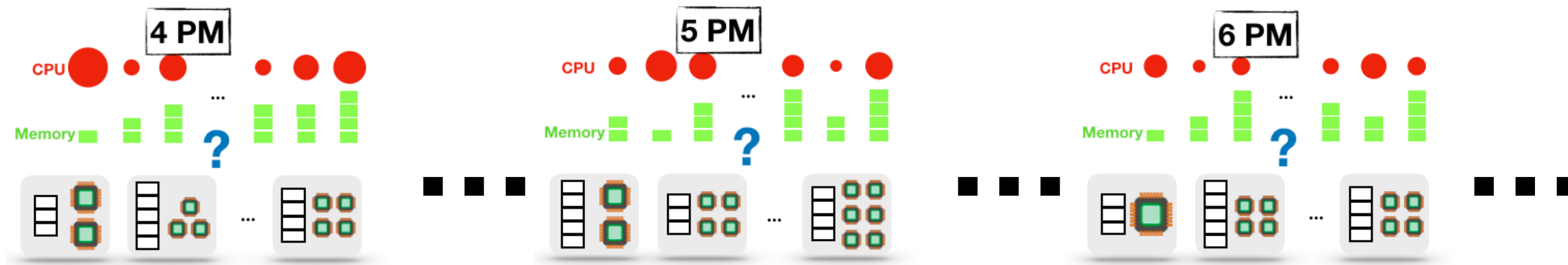


Problem Statement



$$\begin{aligned} &\underset{x}{\text{maximize}} && \sum_{i=1}^m \sum_{j=1}^n p_{ij} x_{ij} \\ &\text{subject to} && \sum_{j=1}^n w_{ij} x_{ij} \leq c_i, \quad i = 1, \dots, m, \\ &&& \sum_{i=1}^m x_{ij} = 1, \quad j = 1, \dots, n, \\ &&& x_{ij} \in \{0, 1\}, \quad i = 1, \dots, m, j = 1, \dots, n. \end{aligned}$$

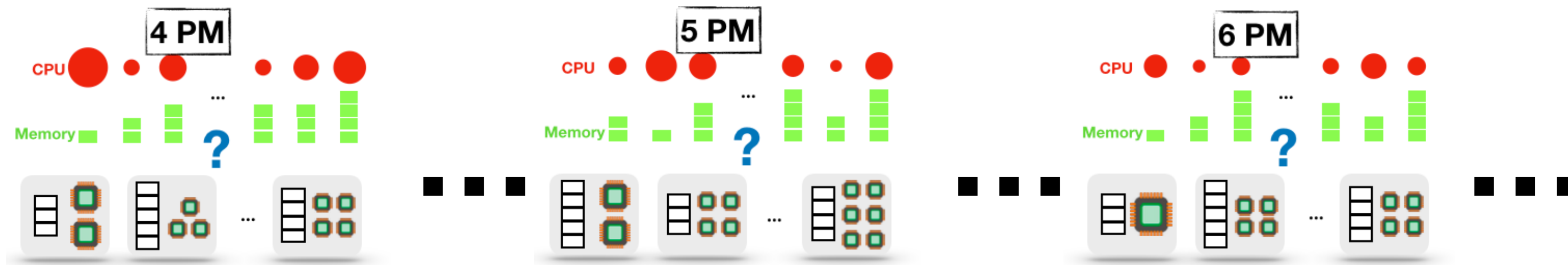
Problem Statement



\mathcal{I} : set of training IP instances

$$\begin{aligned} & \underset{x}{\text{maximize}} && \sum_{i=1}^m \sum_{j=1}^n p_{ij} x_{ij} \\ & \text{subject to} && \sum_{j=1}^n w_{ij} x_{ij} \leq c_i, \quad i = 1, \dots, m, \\ & && \sum_{i=1}^m x_{ij} = 1, \quad j = 1, \dots, n, \\ & && x_{ij} \in \{0, 1\}, \quad i = 1, \dots, m, j = 1, \dots, n. \end{aligned}$$

Problem Statement

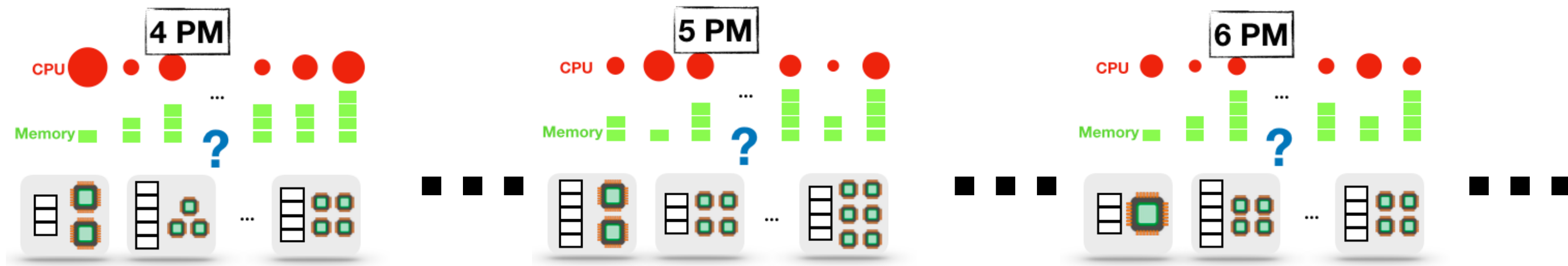


\mathcal{I} : set of **training IP instances**

$$\begin{aligned}
 &\underset{x}{\text{maximize}} && \sum_{i=1}^m \sum_{j=1}^n p_{ij} x_{ij} \\
 &\text{subject to} && \sum_{j=1}^n w_{ij} x_{ij} \leq c_i, \quad i = 1, \dots, m, \\
 &&& \sum_{i=1}^m x_{ij} = 1, \quad j = 1, \dots, n, \\
 &&& x_{ij} \in \{0, 1\}, \quad i = 1, \dots, m, j = 1, \dots, n.
 \end{aligned}$$

A : a **parametric algorithm**; outputs Θ $\begin{cases} 1 & \text{if feasible solution is found} \\ 0 & \text{otherwise} \end{cases}$

Problem Statement



\mathcal{I} : set of training IP instances

$$\begin{aligned}
 &\underset{x}{\text{maximize}} && \sum_{i=1}^m \sum_{j=1}^n p_{ij} x_{ij} \\
 &\text{subject to} && \sum_{j=1}^n w_{ij} x_{ij} \leq c_i, \quad i = 1, \dots, m, \\
 &&& \sum_{i=1}^m x_{ij} = 1, \quad j = 1, \dots, n, \\
 &&& x_{ij} \in \{0, 1\}, \quad i = 1, \dots, m, j = 1, \dots, n.
 \end{aligned}$$

$$\text{Find } \Theta^* = \underset{\Theta \in \mathbb{R}^p}{\text{arg max}} \frac{1}{|\mathcal{I}|} \sum_{I \in \mathcal{I}} \mathcal{A}(I; \Theta)$$

\mathcal{A} : a **parametric algorithm**; outputs Θ $\begin{cases} 1 & \text{if feasible solution is found} \\ 0 & \text{otherwise} \end{cases}$

Towards Learning General Heuristics

$$\text{Find } \Theta^* = \arg \max_{\Theta \in \mathbb{R}^p} \frac{1}{|\mathcal{I}|} \sum_{I \in \mathcal{I}} \mathcal{A}(I; \Theta)$$

Towards Learning General Heuristics

$$\text{Find } \Theta^* = \arg \max_{\Theta \in \mathbb{R}^p} \frac{1}{|\mathcal{I}|} \sum_{I \in \mathcal{I}} \mathcal{A}(I; \Theta)$$

1 *What type of algorithm is \mathcal{A} ?*

Towards Learning General Heuristics

$$\text{Find } \Theta^* = \arg \max_{\Theta \in \mathbb{R}^p} \frac{1}{|\mathcal{I}|} \sum_{I \in \mathcal{I}} \mathcal{A}(I; \Theta)$$

- 1 *What **type of algorithm** is \mathcal{A} ?*
- 2 *What is the **role of the ML model**, parameterized by Θ , in \mathcal{A} ?*

Towards Learning General Heuristics

$$\text{Find } \Theta^* = \arg \max_{\Theta \in \mathbb{R}^p} \frac{1}{|\mathcal{I}|} \sum_{I \in \mathcal{I}} \mathcal{A}(I; \Theta)$$

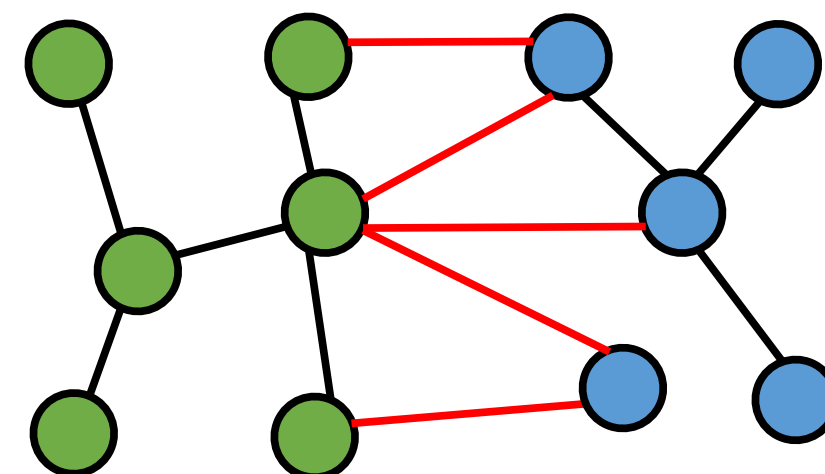
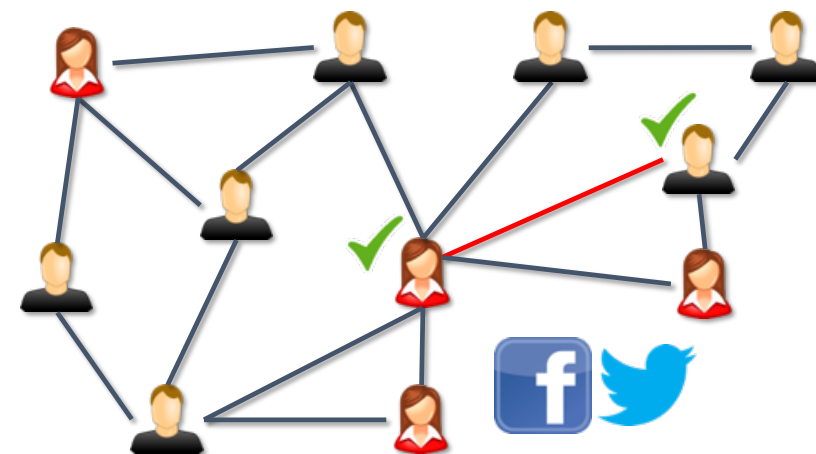
- 1 *What **type of algorithm** is \mathcal{A} ?*
- 2 *What is the **role of the ML model**, parameterized by Θ , in \mathcal{A} ?*
- 3 *How can we **train** the algorithm?*

1 What type of algorithm is \mathcal{A} ?

[Dai & Khalil, et al. (2017)]

Given: graph problem, family of graphs
Learn: a **scoring function** to **guide** a **greedy** algorithm

Problem	Minimum Vertex Cover	Maximum Cut	Traveling Salesman Problem
Domain	Social network snapshots	Spin glass models	Package delivery
Greedy operation	Insert nodes into cover	Insert nodes into subset	Insert nodes into sub-tour

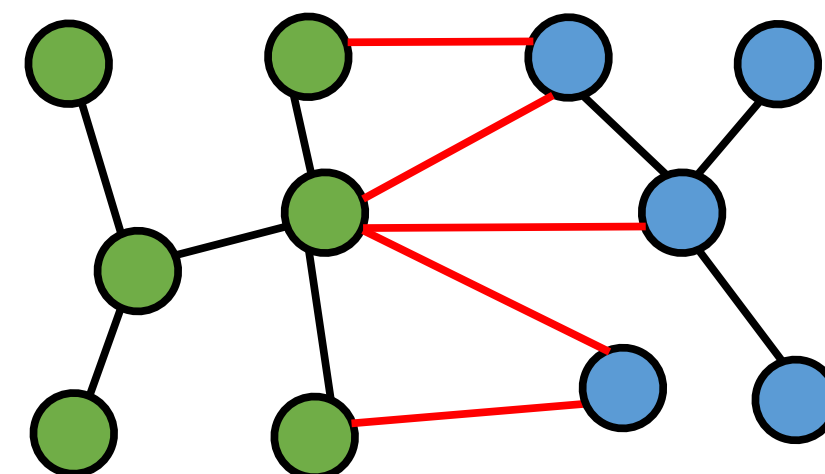
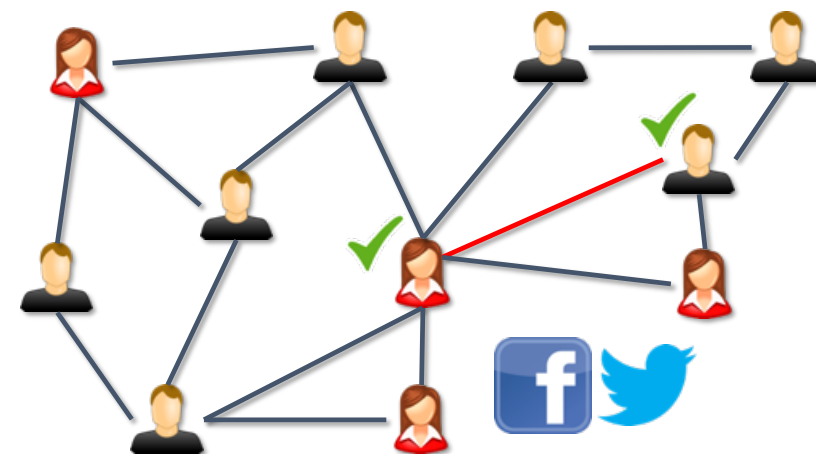


1 What type of algorithm is \mathcal{A} ?

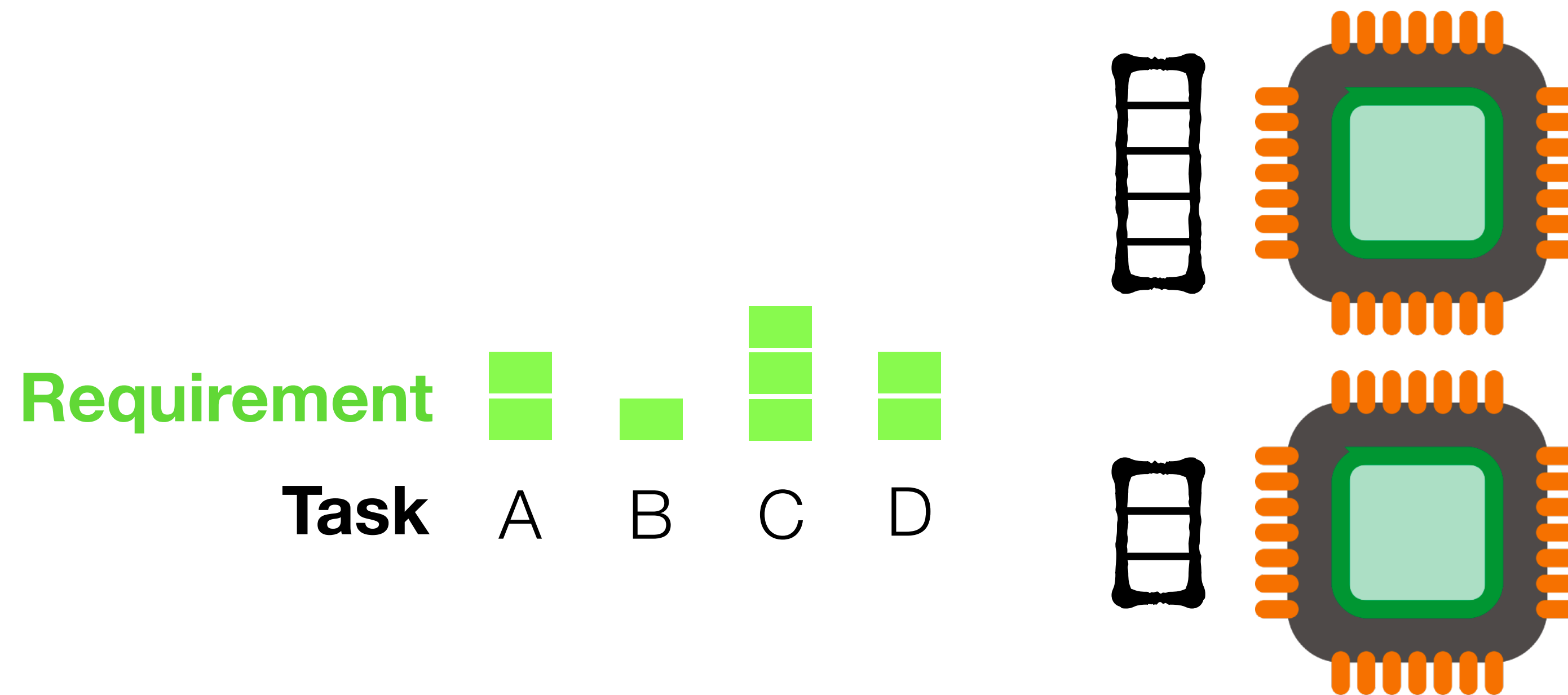
[Dai & Khalil, et al. (2017)]

Given: graph problem, family of graphs
Learn: a **scoring function** to **guide** a **greedy** algorithm

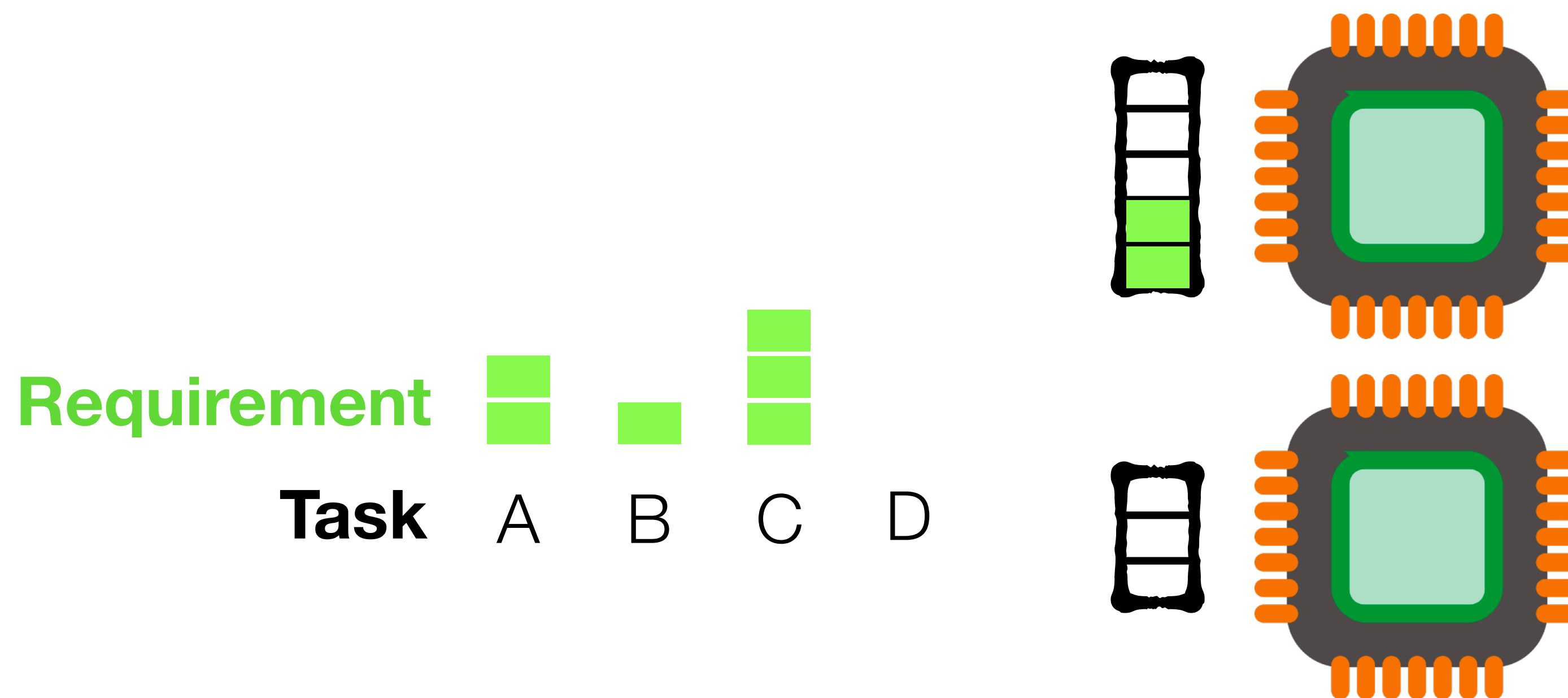
Problem	Minimum Vertex Cover	Maximum Cut	Traveling Salesman Problem
Domain	Social network snapshots	Spin glass models	Package delivery
Greedy operation	Insert nodes into cover	Insert nodes into subset	Insert nodes into sub-tour



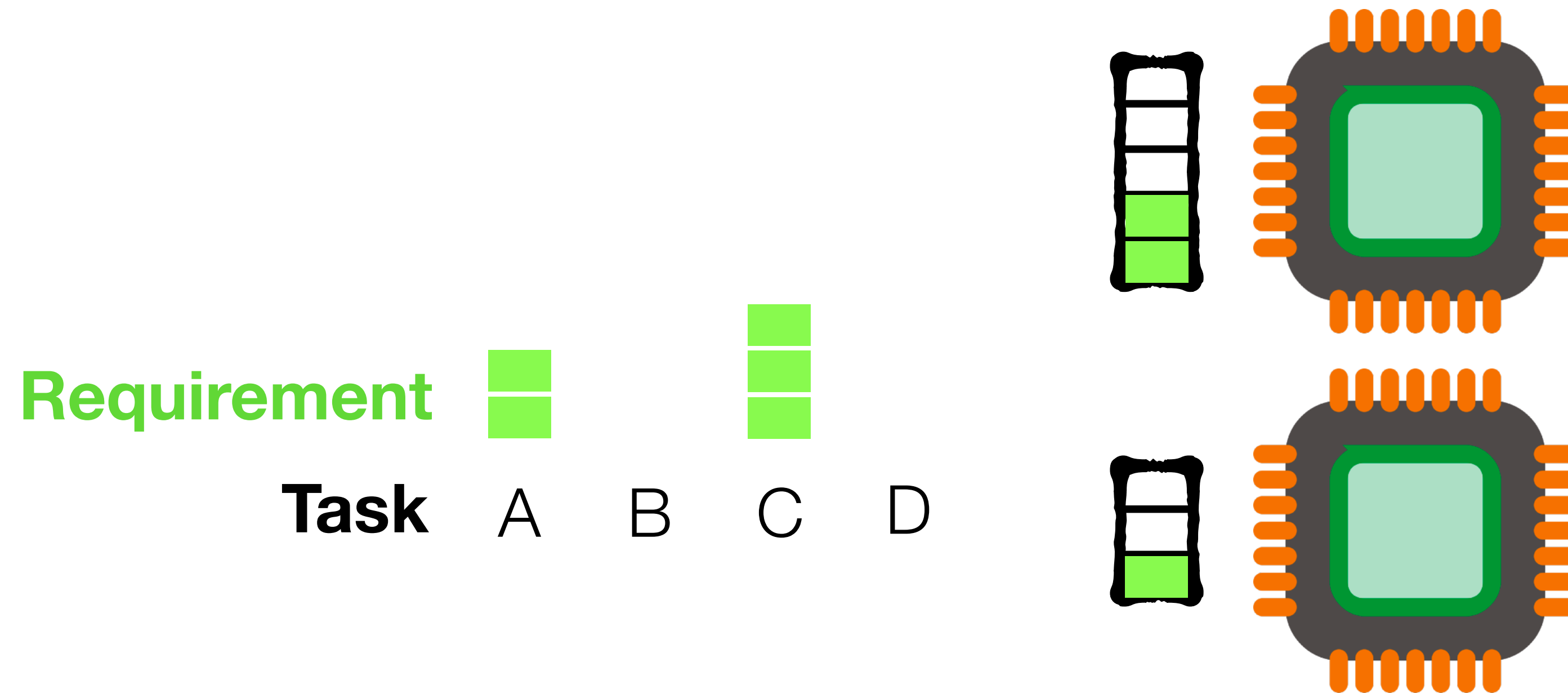
1 What type of algorithm is \mathcal{A} ?



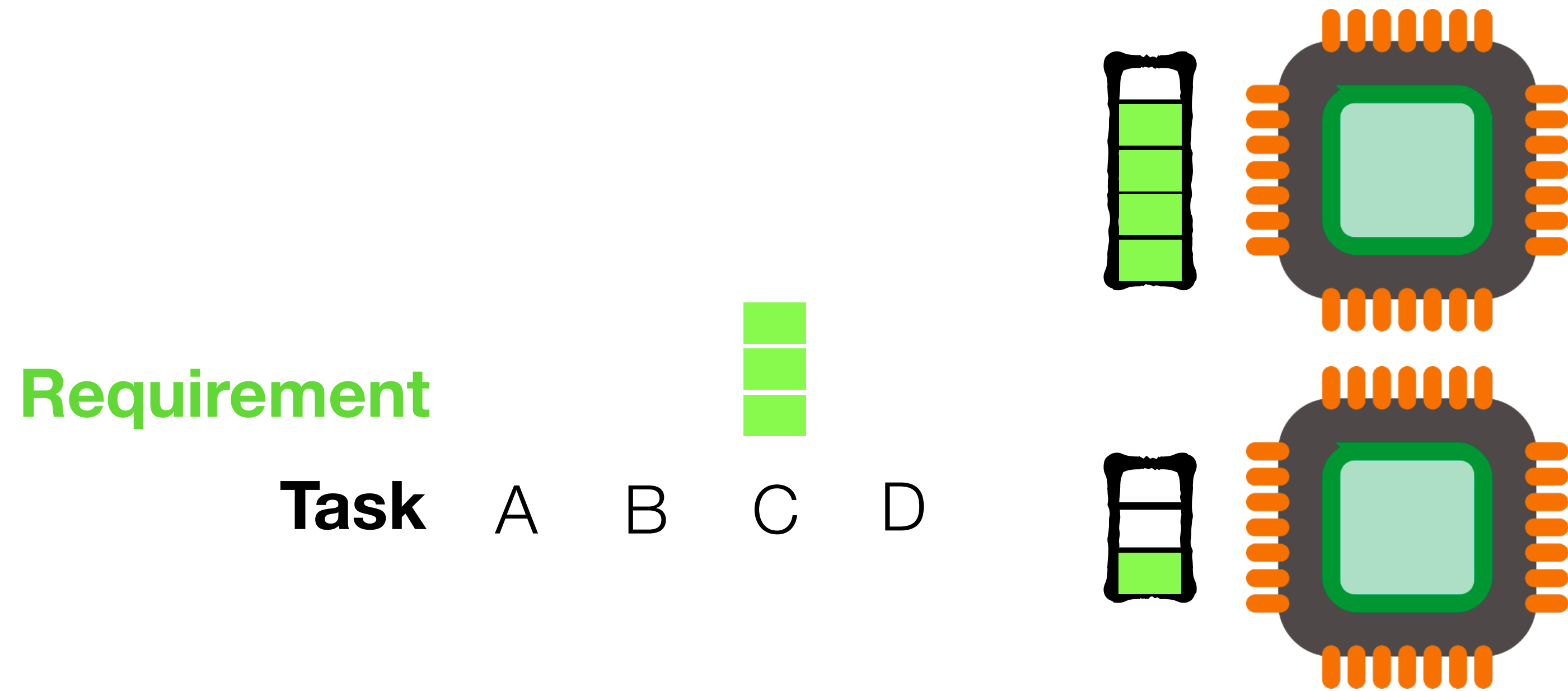
1 What type of algorithm is \mathcal{A} ?



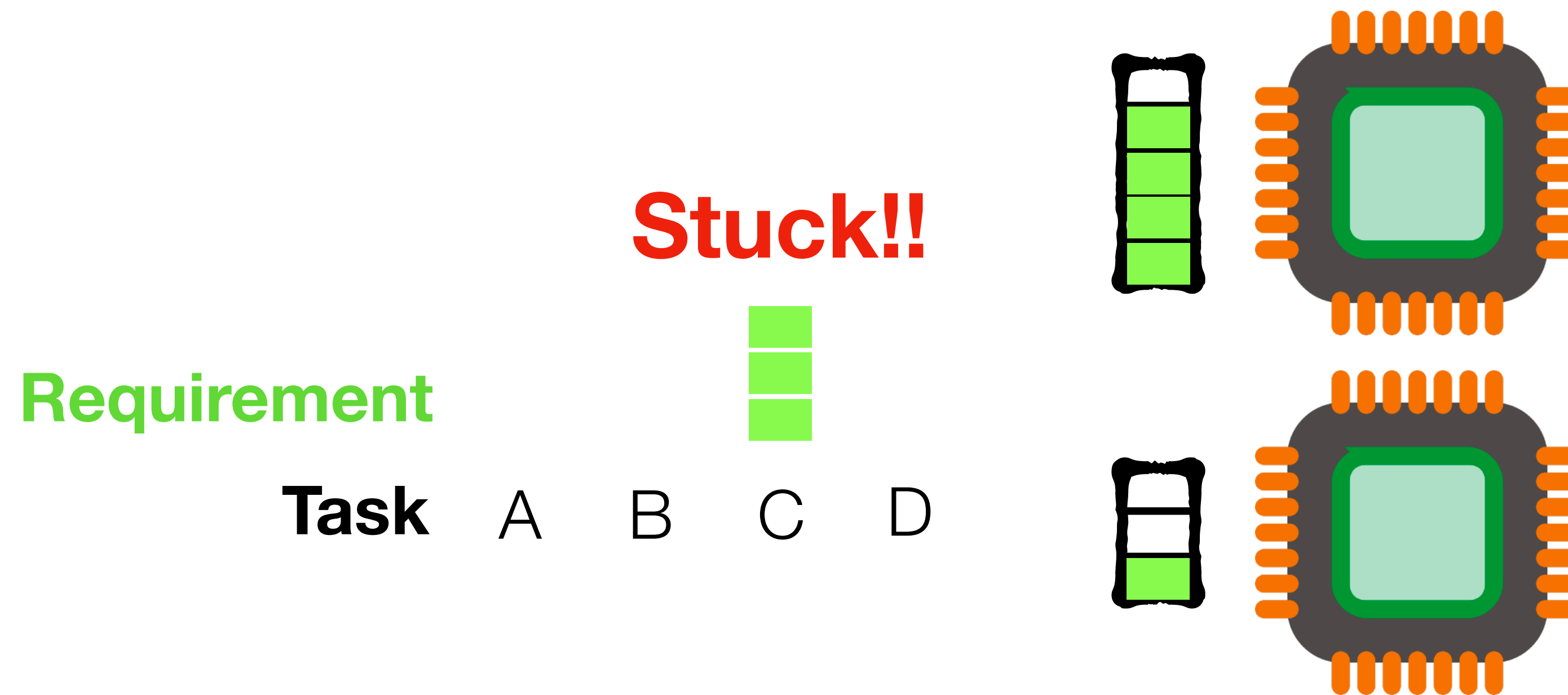
1 What type of algorithm is \mathcal{A} ?



1 What type of algorithm is \mathcal{A} ?

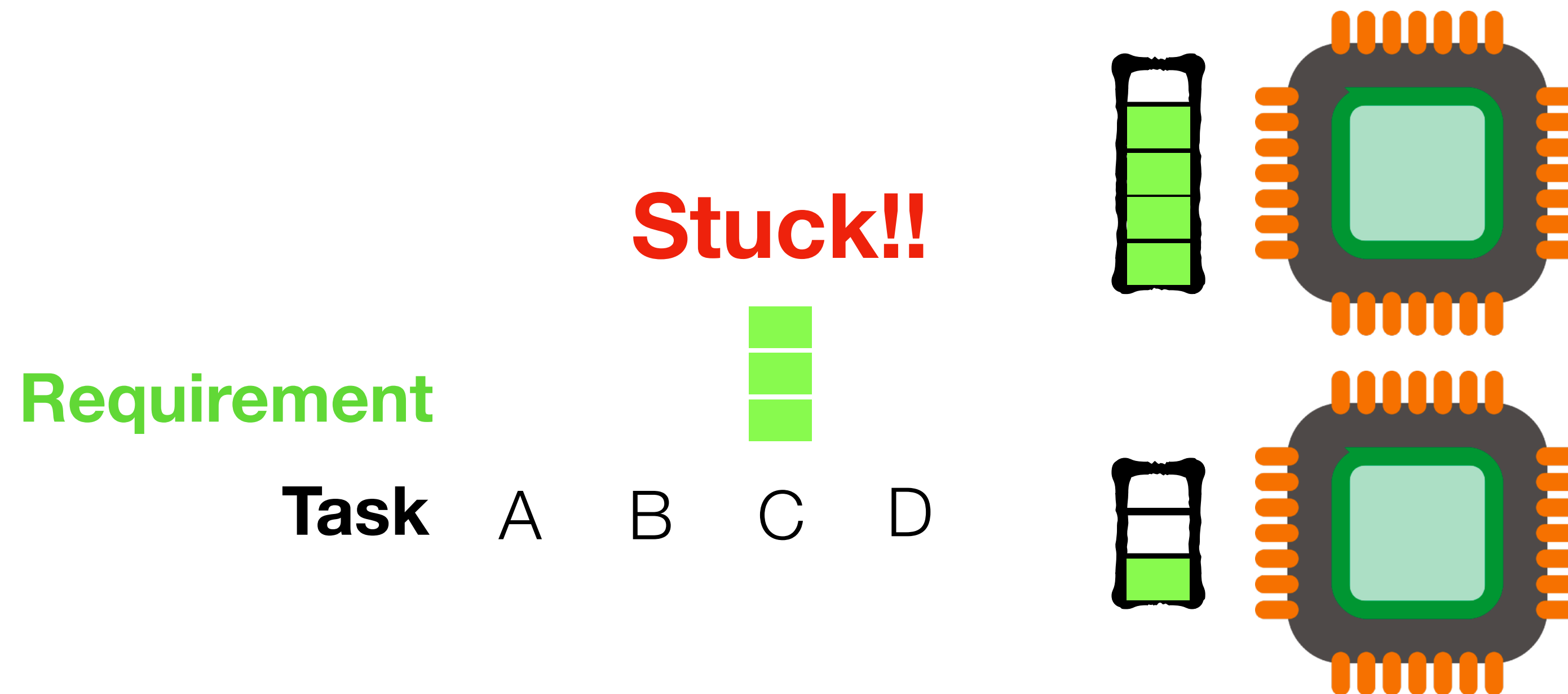


1 What type of algorithm is \mathcal{A} ?



1 What type of algorithm is \mathcal{A} ?

Local algorithms may fail in the presence of hard constraints



1 What type of algorithm is \mathcal{A} ?

Repeated Projections
maintain constraint
feasibility via LP solving

- 0 Start with LP-feasible (fractional) solution
- 1 **Round** to nearest integer, **return** if LP-feasible
- 2 **Project** integer point to **nearest** LP-feasible point
- 3 Go back to step 1

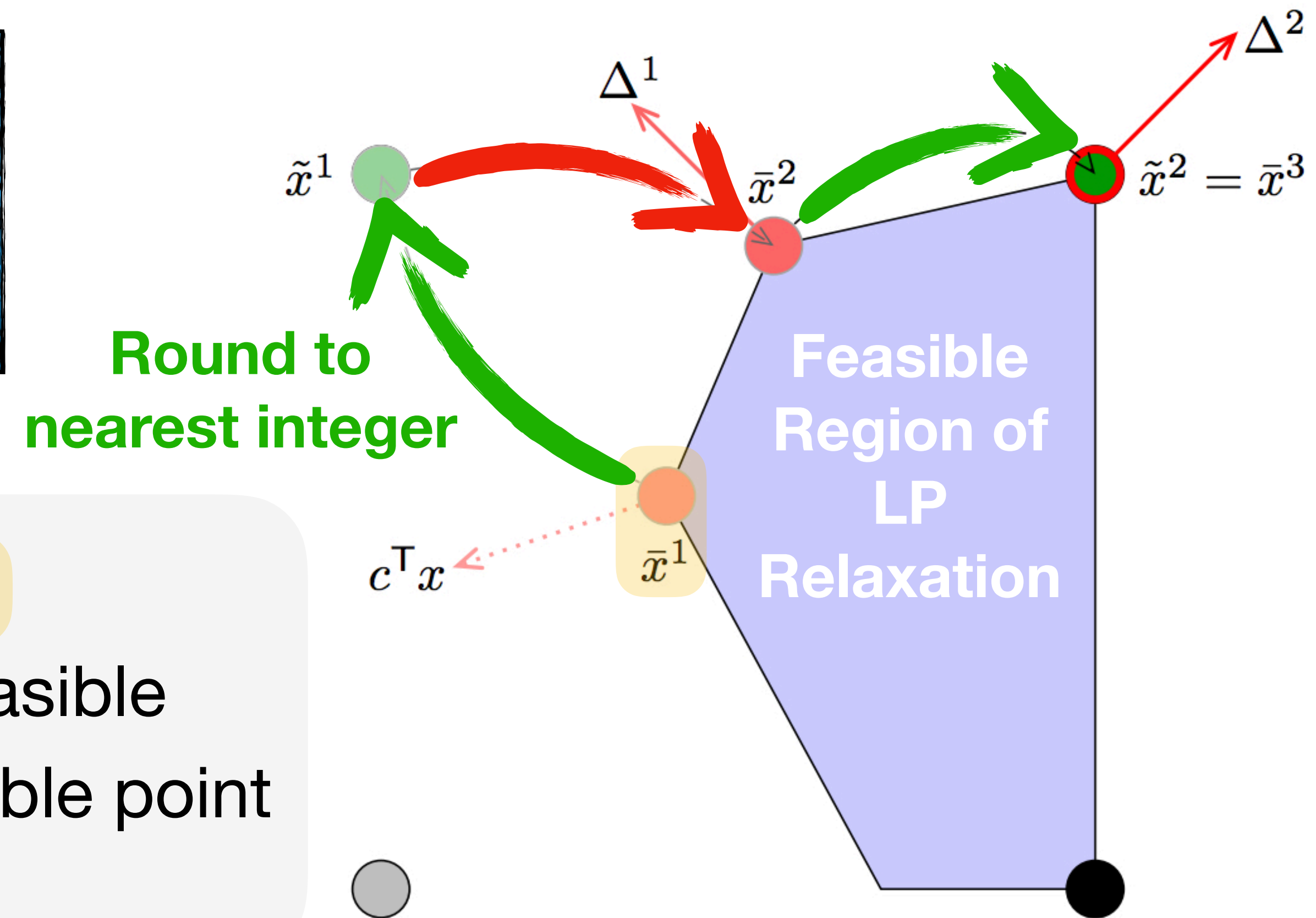
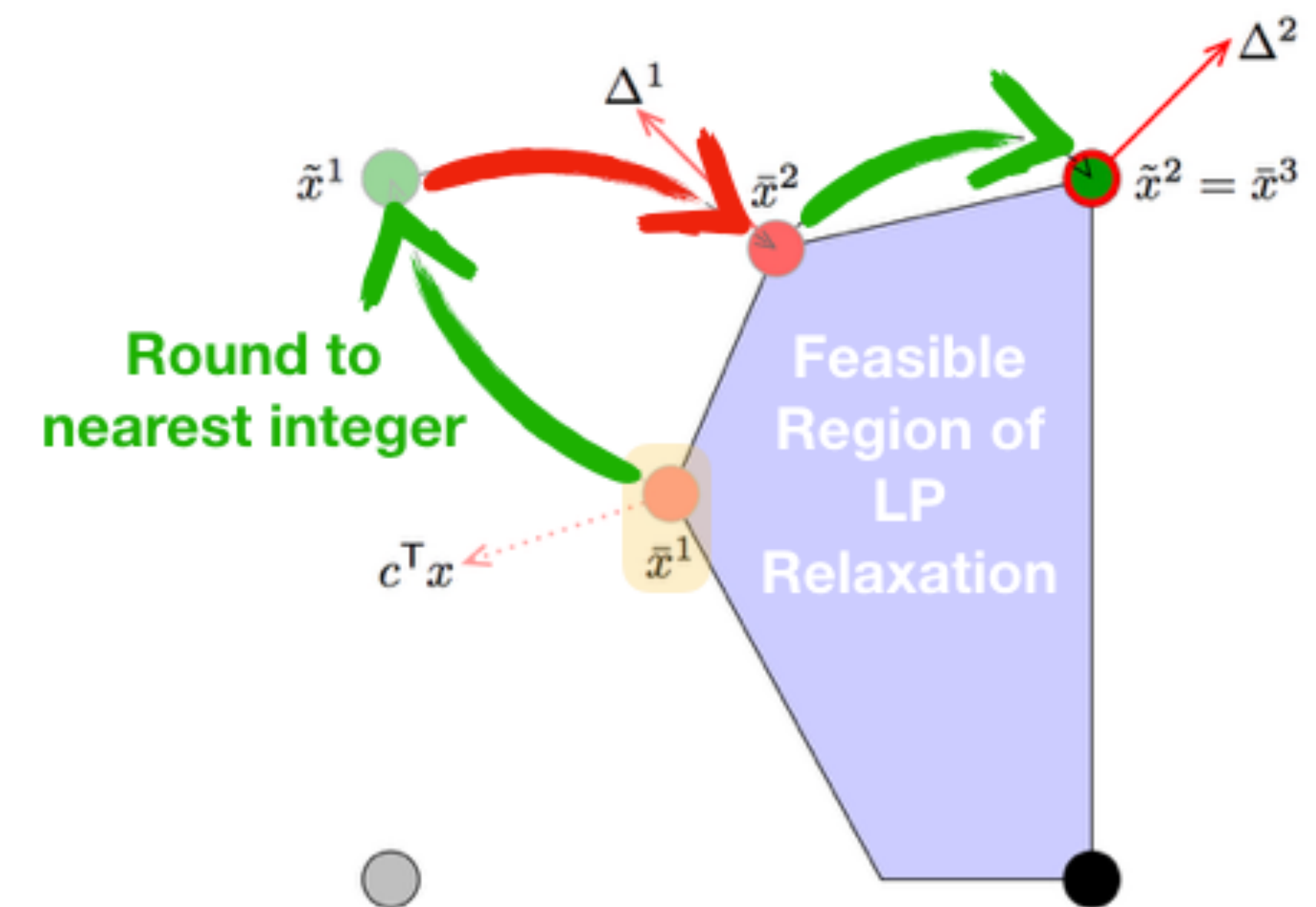


Figure in part from Berthold (2014)

2 What is the *role of ML* in the algorithm?

- 0 Start with LP-feasible (fractional) solution
- 1 **Round** to nearest integer, **return** if LP-feasible
- iterate ↻ 2 **Project** integer point to **nearest** LP-feasible point
- ↻ 3 Go back to step 1

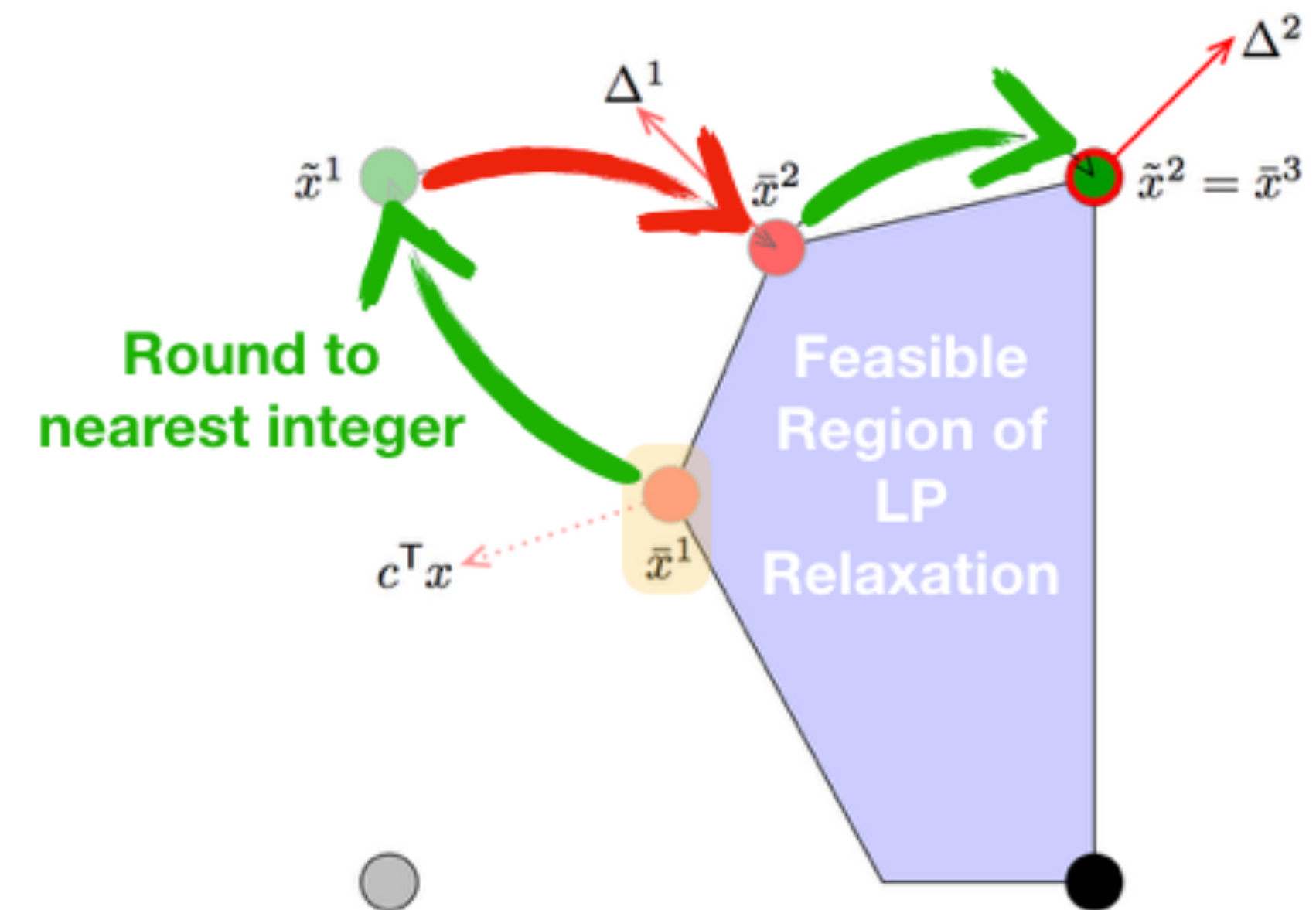


2

What is the role of *ML* in the algorithm?

- 0 Start with LP-feasible (fractional) solution
- 1 **Round** to nearest integer, **return** if LP-feasible
- iterate ↻ 2 **Project** integer point to **nearest** LP-feasible point
- ↻ 3 Go back to step 1

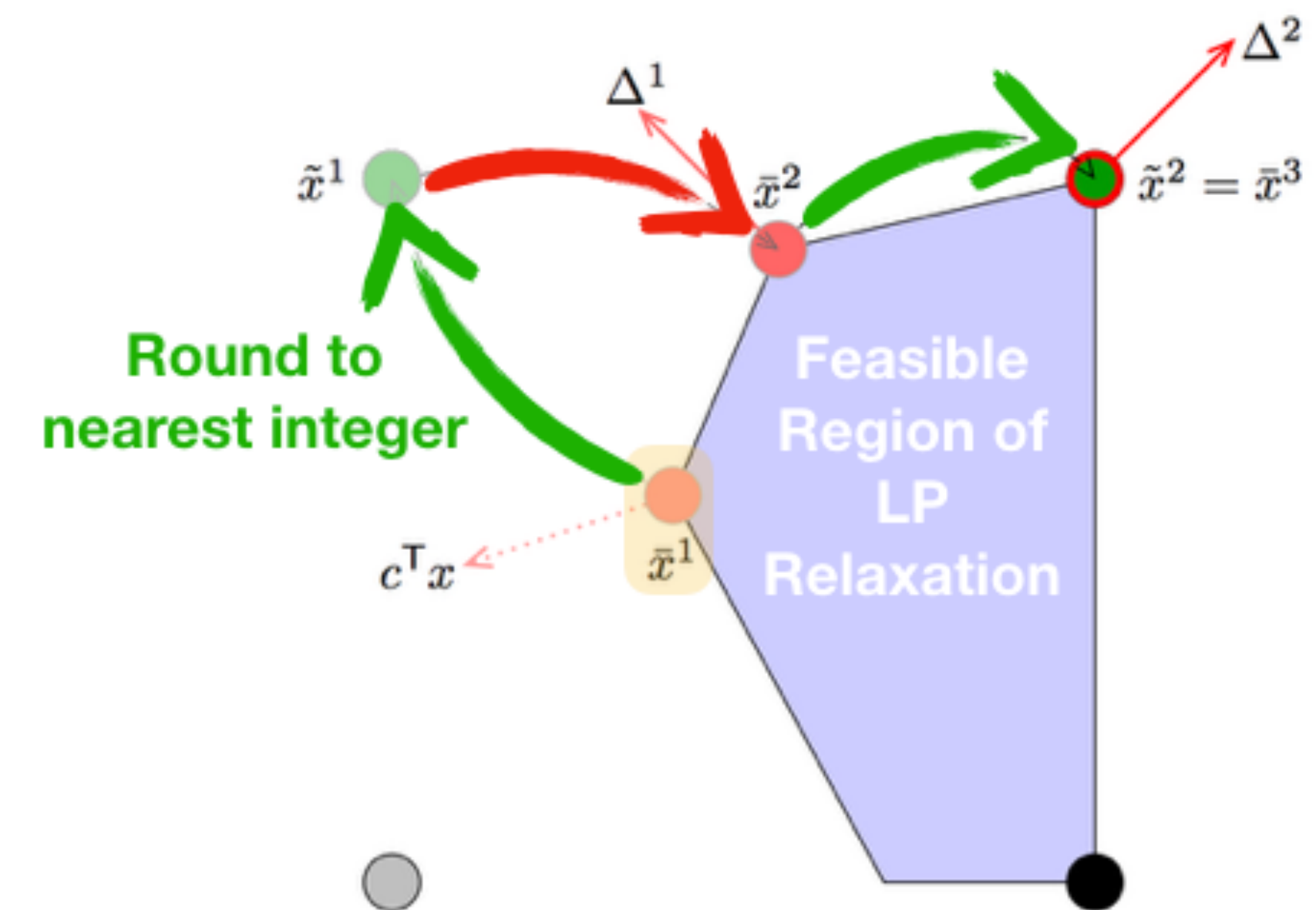
\bar{x}^1



2 What is the role of *ML* in the algorithm?

- 0 Start with LP-feasible (fractional) solution
- 1 **Round** to nearest integer, **return** if LP-feasible
- iterate ↻ 2 **Project** integer point to **nearest** LP-feasible point
- ↻ 3 Go back to step 1

$$\bar{x}^1 \quad \left[\bar{x}^1 \right]$$

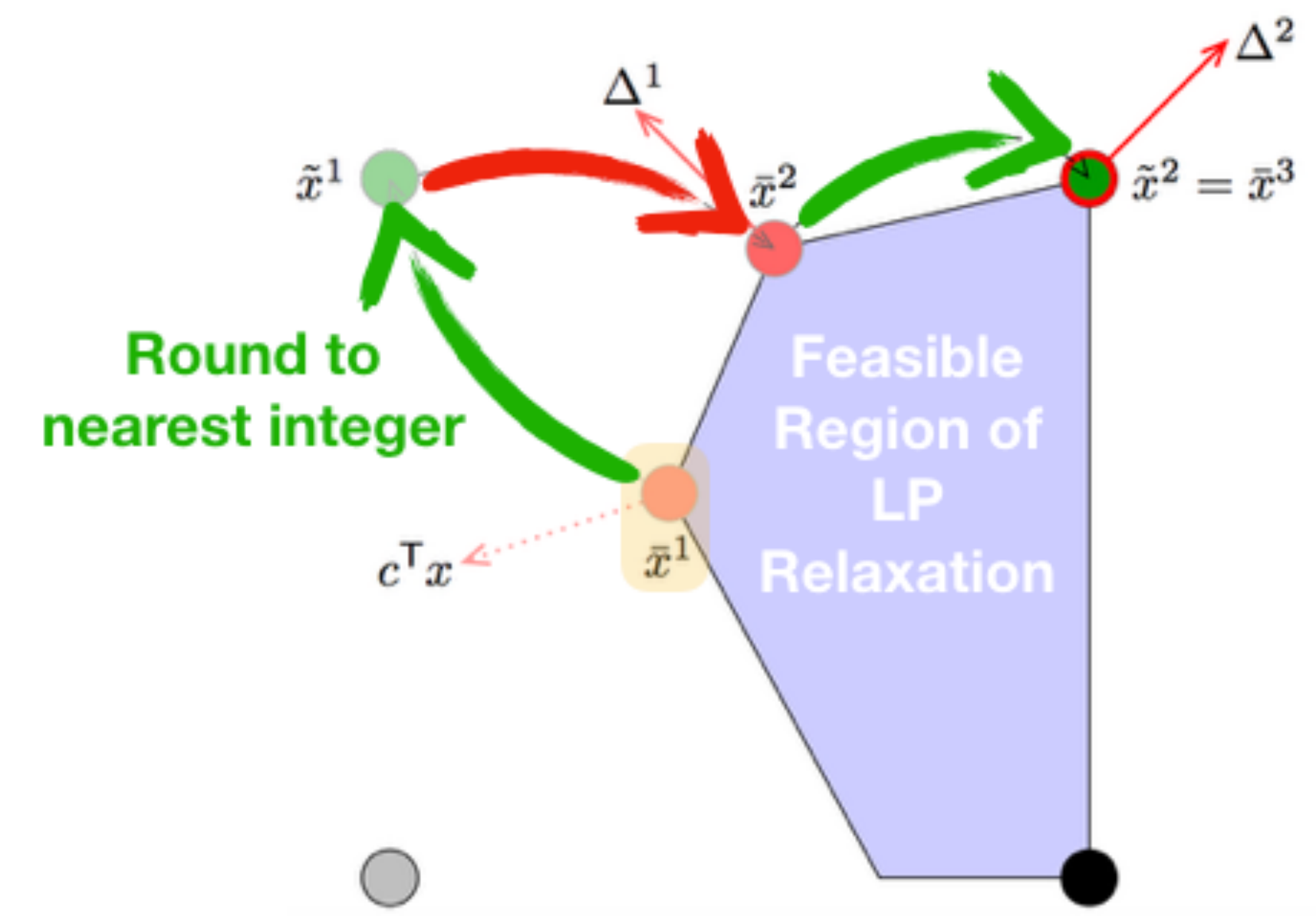


2 What is the *role of ML* in the algorithm?

- 0 Start with LP-feasible (fractional) solution
- 1 **Round** to nearest integer, **return** if LP-feasible
- iterate ↻ 2 **Project** integer point to **nearest** LP-feasible point
- 3 Go back to step 1

$$\bar{x}^1$$

$$\bar{x}^2 \quad \left[\bar{x}^1 \right]$$

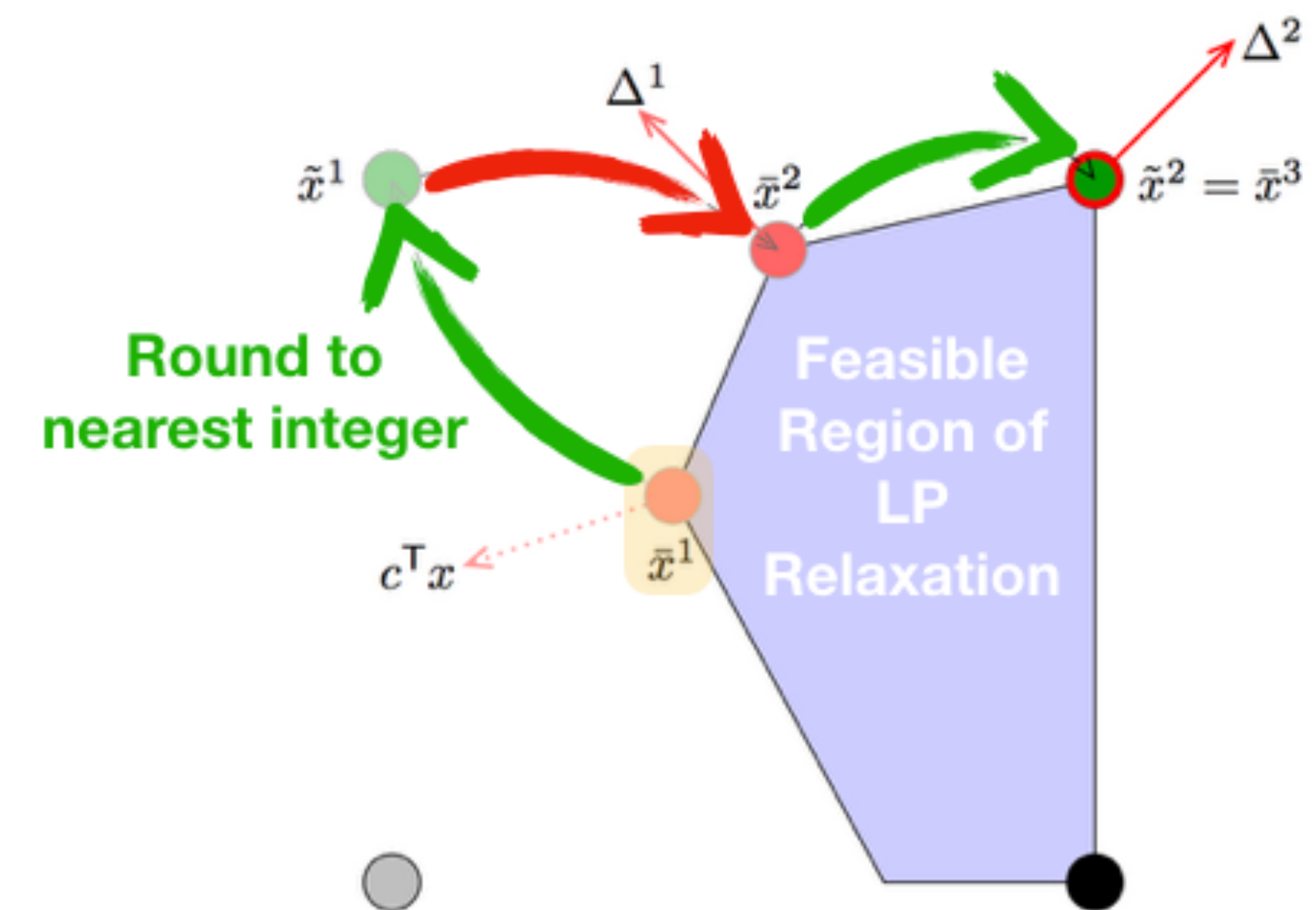


2 What is the role of *ML* in the algorithm?

- 0 Start with LP-feasible (fractional) solution
 - 1 **Round** to nearest integer, **return** if LP-feasible
 - 2 **Project** integer point to **nearest** LP-feasible point
 - 3 Go back to step 1
- iterate

$$\bar{x}^1$$

$$\bar{x}^2 \left[\bar{x}^1 \right]$$



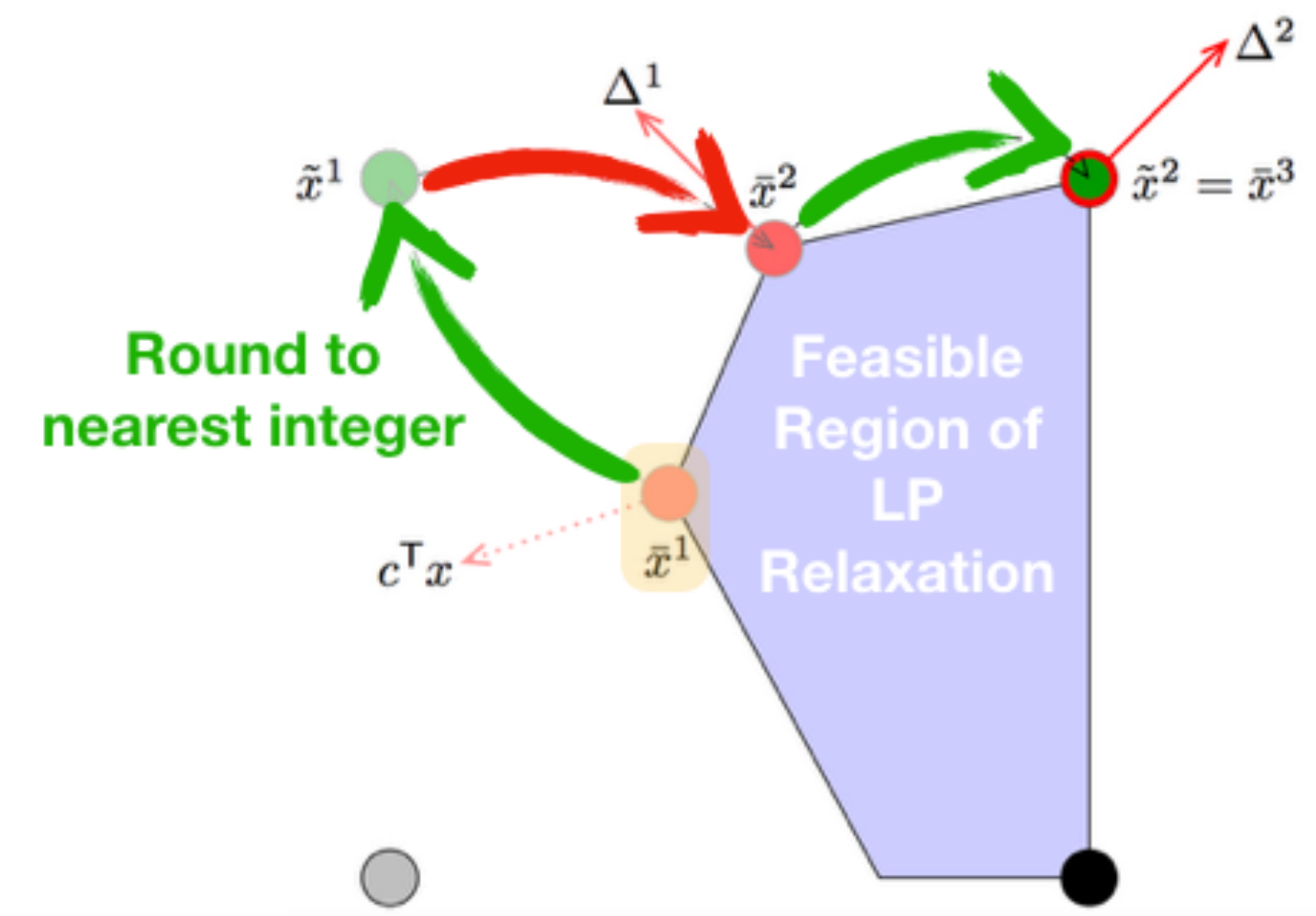
2 What is the *role of ML* in the algorithm?

- 0 Start with LP-feasible (fractional) solution
 - 1 **Round** to nearest integer, **return** if LP-feasible
 - 2 **Project** integer point to **nearest** LP-feasible point
 - 3 Go back to step 1
- iterate

$$\begin{matrix} \bar{x}^1 \\ \bar{x}^2 \end{matrix} \begin{bmatrix} \bar{x}^1 \\ \bar{x}^1 \end{bmatrix}$$

Key Step:

$$\begin{aligned} \min_x \quad & \Delta(x, [\bar{x}^t]) \\ \text{s.t.} \quad & Ax \leq b, \\ & x \in [0, 1]^n \end{aligned}$$



2 What is the role of *ML* in the algorithm?

- iterate
- 0 Start with LP-feasible (fractional) solution \bar{x}^1
 - 1 **Round** to nearest integer, **return** if LP-feasible $[\bar{x}^1]$
 - 2 **Project** integer point to **nearest** LP-feasible point \bar{x}^2
 - 3 Go back to step 1

$$\begin{aligned} \min_x \quad & \Delta(x, [\bar{x}^t]) \\ \text{s.t.} \quad & Ax \leq b, \\ & x \in [0, 1]^n \end{aligned}$$

2 What is the role of ML in the algorithm?

- iterate
- 0 Start with LP-feasible (fractional) solution \bar{x}^1
 - 1 **Round** to nearest integer, **return** if LP-feasible $[\bar{x}^1]$
 - 2 **Project** integer point to **nearest** LP-feasible point \bar{x}^2
 - 3 Go back to step 1

L1-distance

$$\begin{aligned} \min_x \quad & \Delta(x, [\bar{x}^t]) \\ \text{s.t.} \quad & Ax \leq b, \\ & x \in [0, 1]^n \end{aligned}$$

2 What is the role of ML in the algorithm?

- iterate
- 0 Start with LP-feasible (fractional) solution \bar{x}^1
 - 1 **Round** to nearest integer, **return** if LP-feasible $[\bar{x}^1]$
 - 2 **Project** integer point to **nearest** LP-feasible point \bar{x}^2
 - 3 Go back to step 1

L1-distance

$$\min_x \Delta(x, [\bar{x}^t])$$

$$\text{s.t. } Ax \leq b,$$

$$x \in [0, 1]^n$$

$$\begin{aligned} & \sum_j |x_j - [\bar{x}^t]_j| \\ &= \sum_{j: [\bar{x}^t]=0} x_j + \sum_{j: [\bar{x}^t]=1} (1 - x_j) \end{aligned}$$

2 What is the role of ML in the algorithm?

iterate

- 0 Start with LP-feasible (fractional) solution
- 1 **Round** to nearest integer, **return** if LP-feasible
- 2 **Project** integer point to **nearest** LP-feasible point
- 3 Go back to step 1

$$\bar{x}^1 \quad \bar{x}^2 \quad \left[\bar{x}^1 \right]$$

L1-distance

$$\sum_{j: [\bar{x}^t]=0} x_j + \sum_{j: [\bar{x}^t]=1} (1 - x_j)$$

$$\begin{aligned} \min_x \quad & \Delta(x, [\bar{x}^t]) \\ \text{s.t.} \quad & Ax \leq b, \\ & x \in [0, 1]^n \end{aligned}$$

2 What is the role of ML in the algorithm?

iterate

0 Start with LP-feasible (fractional) solution

1 **Round** to nearest integer, **return** if LP-feasible

2 **Project** integer point to **nearest** LP-feasible point

3 Go back to step 1

$$\begin{matrix} \bar{x}^1 \\ \bar{x}^2 \end{matrix} \begin{bmatrix} \bar{x}^1 \\ \bar{x}^1 \end{bmatrix}$$

~~L1 distance~~

~~$$\sum_{j: [\bar{x}^t]=0} x_j + \sum_{j: [\bar{x}^t]=1} (1 - x_j)$$~~

$$\begin{aligned} \min_x \quad & \Delta(x, [\bar{x}^t]) \\ \text{s.t.} \quad & Ax \leq b, \\ & x \in [0, 1]^n \end{aligned}$$

2 What is the role of ML in the algorithm?

- iterate
- 0 Start with LP-feasible (fractional) solution
 - 1 **Round** to nearest integer, **return** if LP-feasible
 - 2 **Project** integer point to **nearest** LP-feasible point
 - 3 Go back to step 1

$$\bar{x}^1 \quad \bar{x}^2 \quad \left[\bar{x}^1 \right]$$

~~L1 distance~~ $\sum_{j: [\bar{x}^t]=0} x_j + \sum_{j: [\bar{x}^t]=1} (1 - x_j)$

$$\begin{aligned} \min_x \quad & \Delta(x, [\bar{x}^t]) \\ \text{s.t.} \quad & Ax \leq b, \\ & x \in [0, 1]^n \end{aligned}$$

Learn the
projection
coefficients!!

2 *What is the role of ML in the algorithm?*

$$\begin{aligned} \min_x \quad & \ell_1(x, [\bar{x}^t]) \\ \text{s.t.} \quad & Ax \leq b, \\ & x \in [0, 1]^n \end{aligned}$$

2 *What is the role of ML in the algorithm?*

$$\begin{aligned} \min_x \quad & \ell_1(x, [\bar{x}^t]) \\ \text{s.t.} \quad & Ax \leq b, \\ & x \in [0, 1]^n \end{aligned}$$

2 *What is the role of ML in the algorithm?*

$$\min_x \cancel{l_1(x, [\bar{x}^t])}$$

$$\text{s.t. } Ax \leq b,$$

$$x \in [0, 1]^n$$

2 *What is the role of ML in the algorithm?*

$$\mathbf{p}^\top x$$

$$\min_x \cancel{l_1(x, [\bar{x}^t])}$$

$$\text{s.t. } Ax \leq b,$$

$$x \in [0, 1]^n$$

2 What is the role of ML in the algorithm?

$$\begin{aligned} & \mathbf{p}^\top x \\ \min_x & \quad \cancel{l_1(x, [\bar{x}^t])} \\ \text{s.t.} & \quad Ax \leq b, \\ & \quad x \in [0, 1]^n \end{aligned}$$

$$\mathbf{p}_i = \text{model} \left(\bar{x}_i^t, [\bar{x}_i^t]; \Theta \right)$$

2 What is the role of ML in the algorithm?

$$\begin{aligned} & \mathbf{p}^\top x \\ \min_x & \quad \cancel{l_1(x, [\bar{x}^t])} \\ \text{s.t.} & \quad Ax \leq b, \\ & \quad x \in [0, 1]^n \end{aligned}$$

$$\mathbf{p}_i = \text{model}\left(\bar{x}_i^t, [\bar{x}_i^t]; \Theta\right)$$

Properties of model

2 What is the role of ML in the algorithm?

$$\begin{aligned} & \mathbf{p}^\top x \\ \min_x & \cancel{\ell_1(x, [\bar{x}^t])} \\ \text{s.t.} & Ax \leq b, \\ & x \in [0, 1]^n \end{aligned}$$

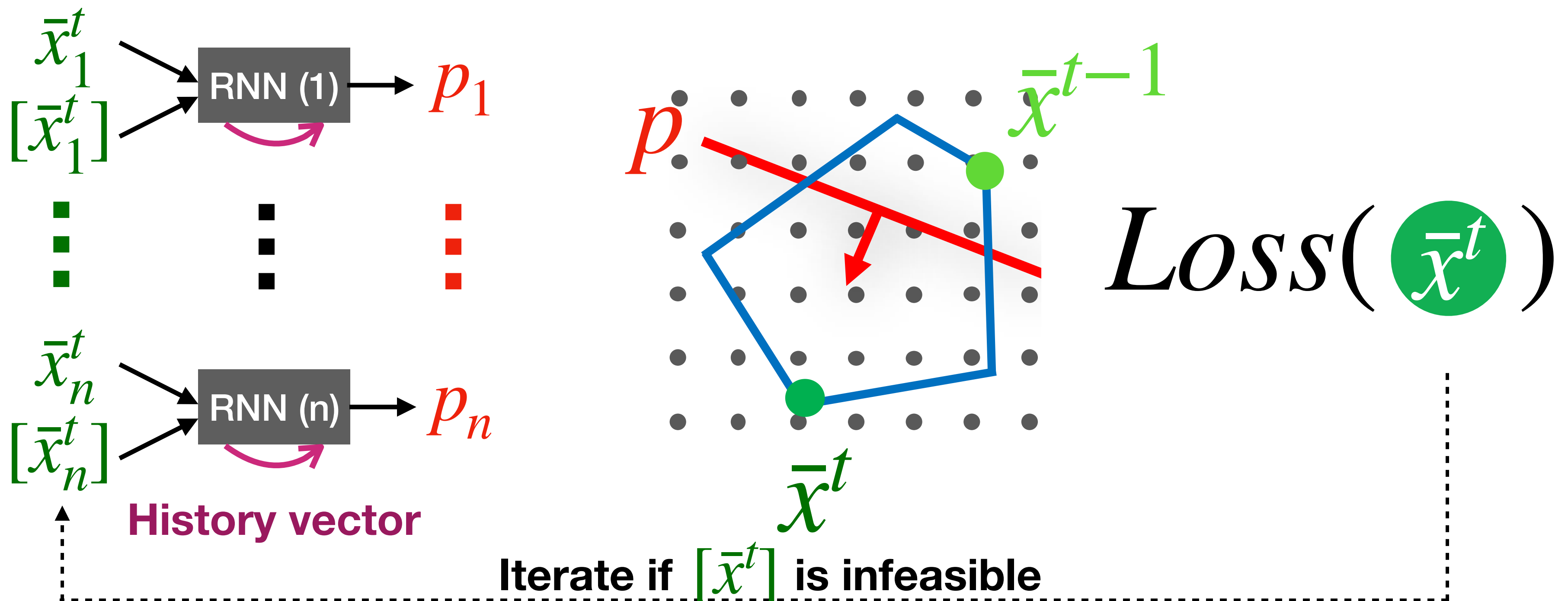
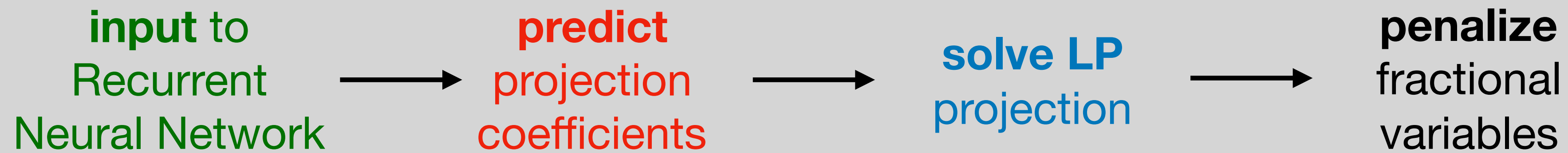
$$\mathbf{p}_i = \text{model}\left(\bar{x}_i^t, [\bar{x}_i^t]; \Theta\right)$$

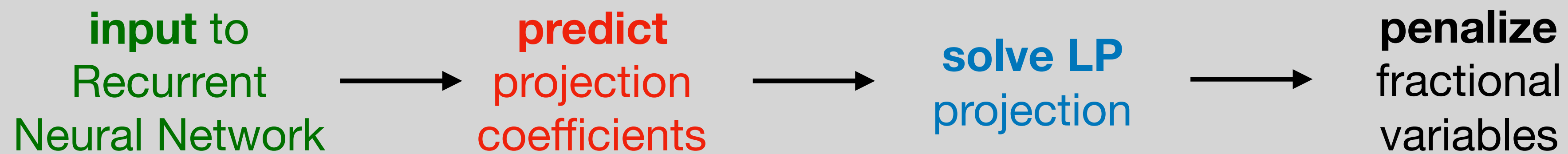
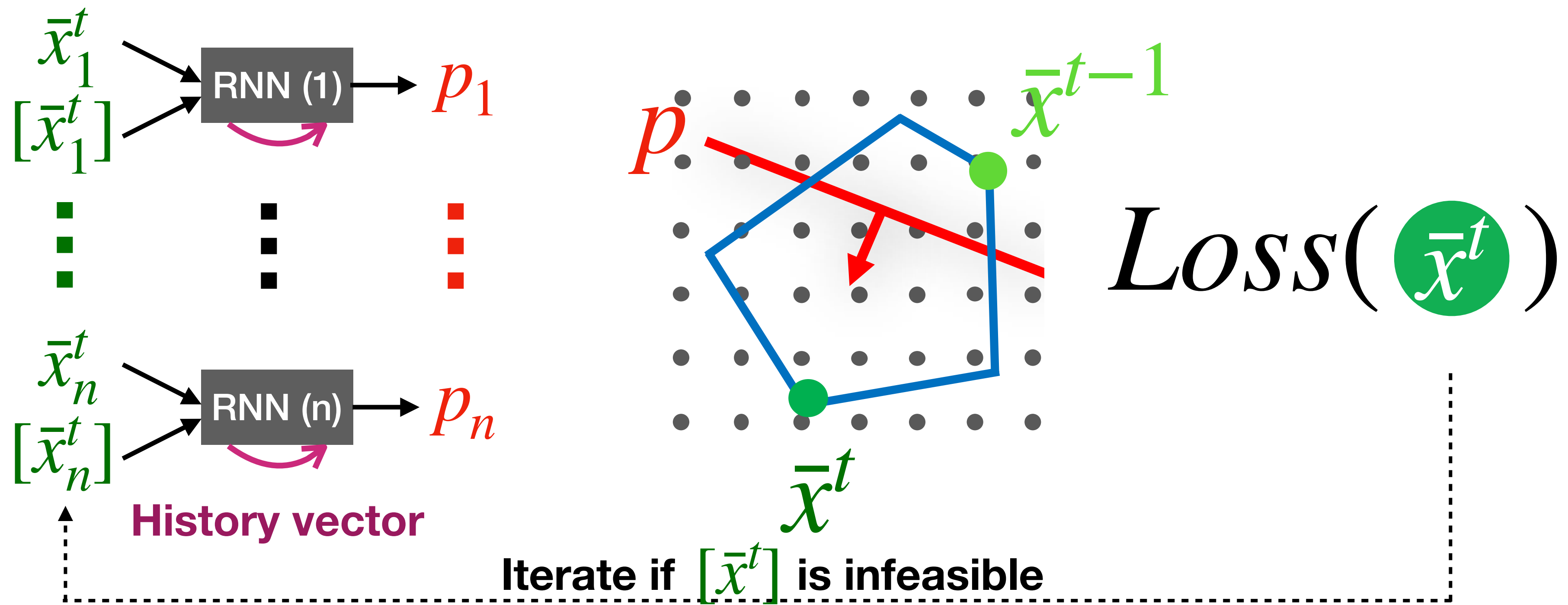
Properties of `model`

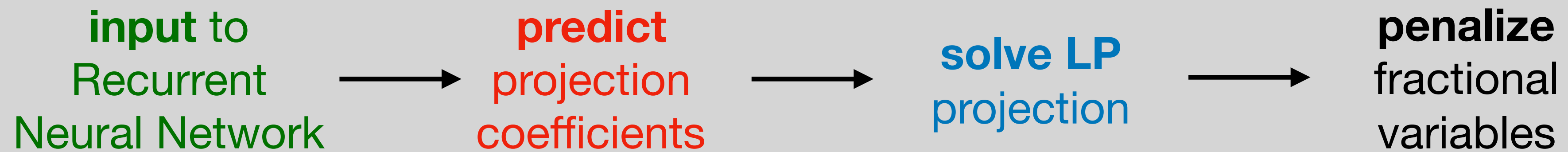
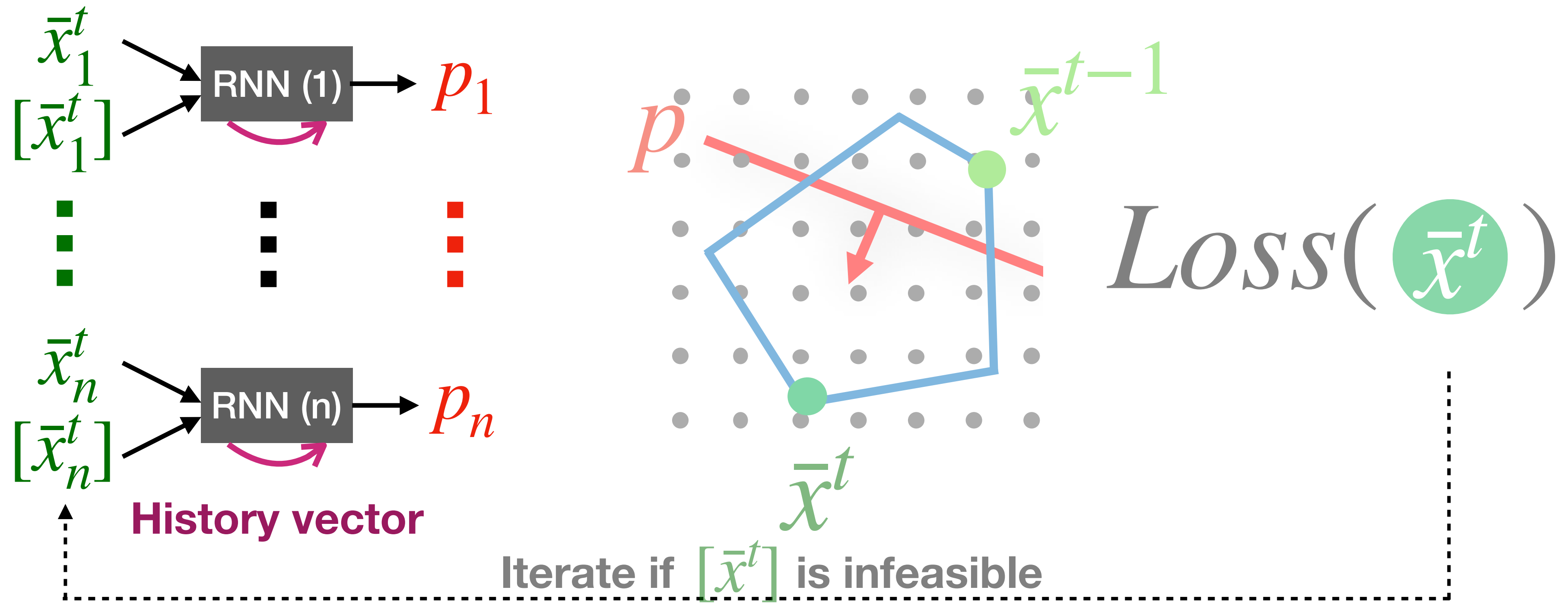
- **Parameters shared** across variables
- **Recurrent** across iterations

3 How can we train the algorithm?

$$\min_x c^T x \text{ s.t. } Ax \leq b, x \in \{0,1\}^n$$

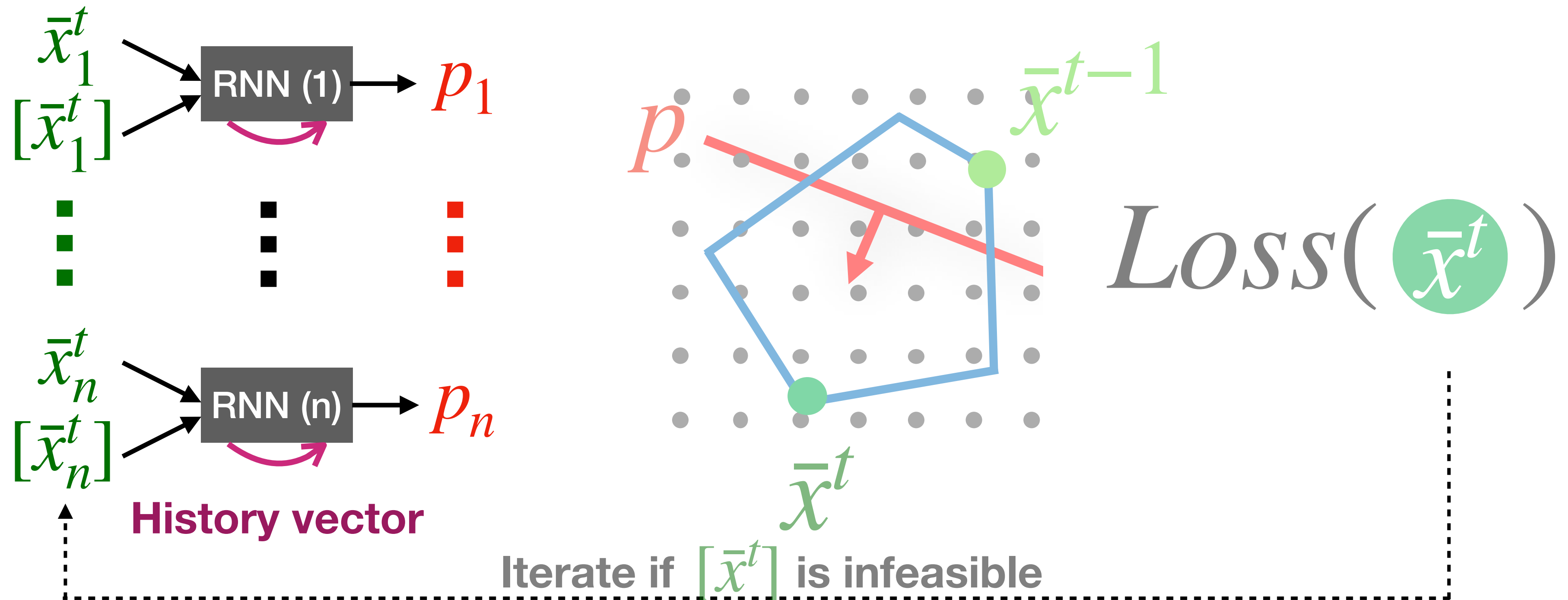






RNN

A neural network with parameters Θ
Same network used for all fractional variables
History vector is variable-specific



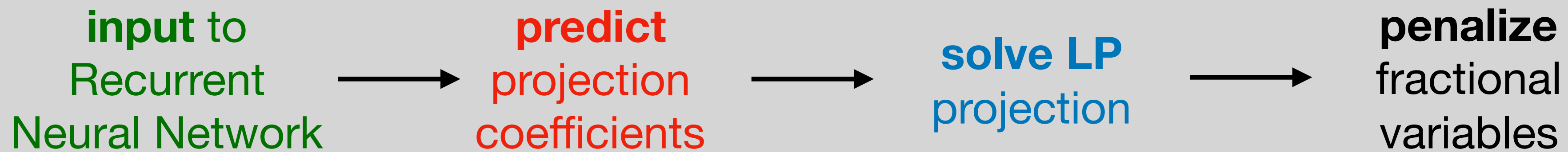
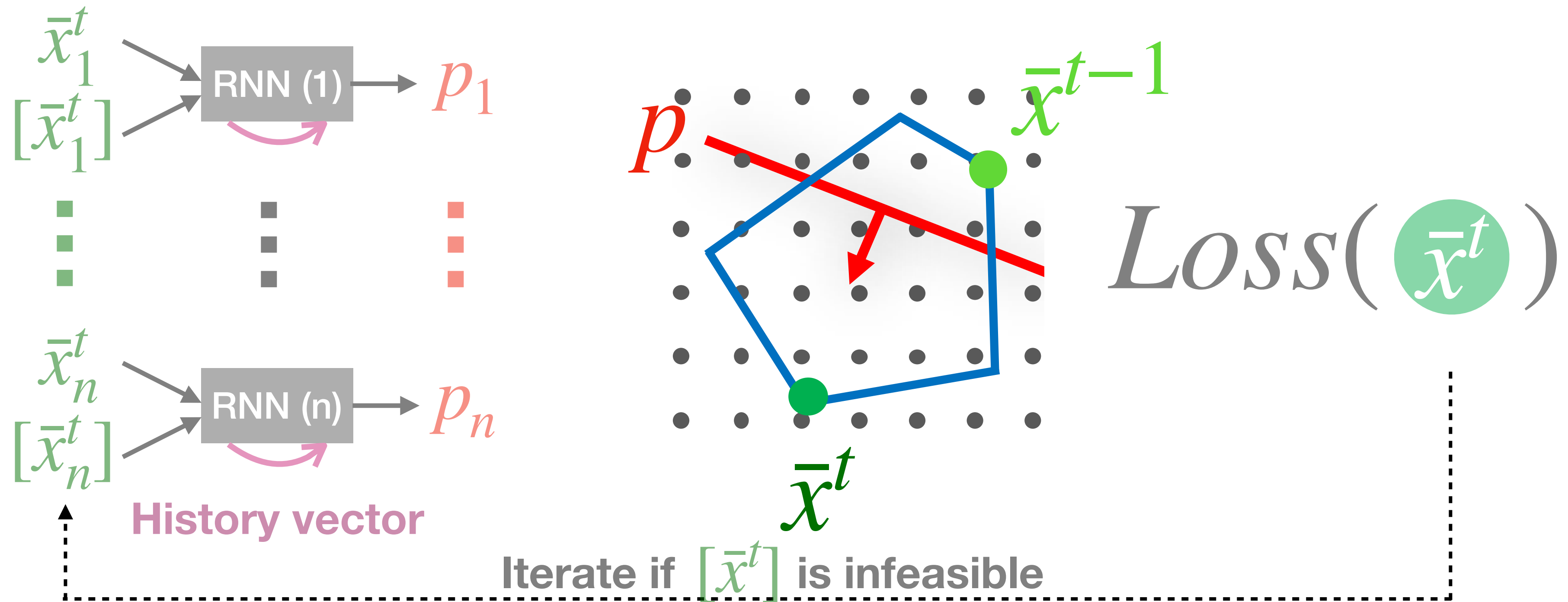
input to
Recurrent
Neural Network

predict
projection
coefficients

solve LP
projection

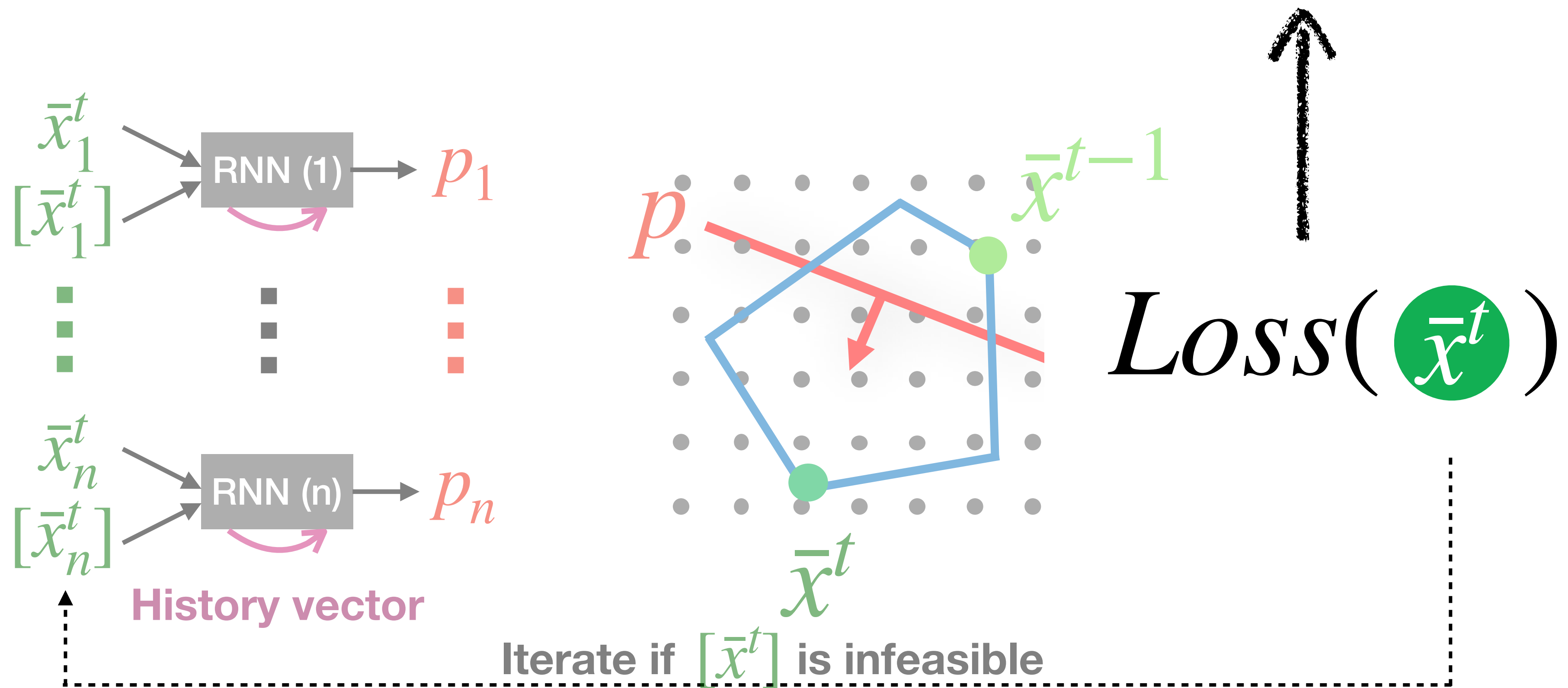
penalize
fractional
variables

To make LP solution differentiable,
 add small constant quadratic term
 See OptNet by Amos & Kolter, 2017



Binary Cross-Entropy Loss

$$- [\bar{x}_j^t] \cdot \log \bar{x}_j^t + (1 - [\bar{x}_j^t]) \cdot \log (1 - \bar{x}_j^t)$$



input to
Recurrent
Neural Network



predict
projection
coefficients



solve LP
projection



penalize
fractional
variables

Experimental Setup

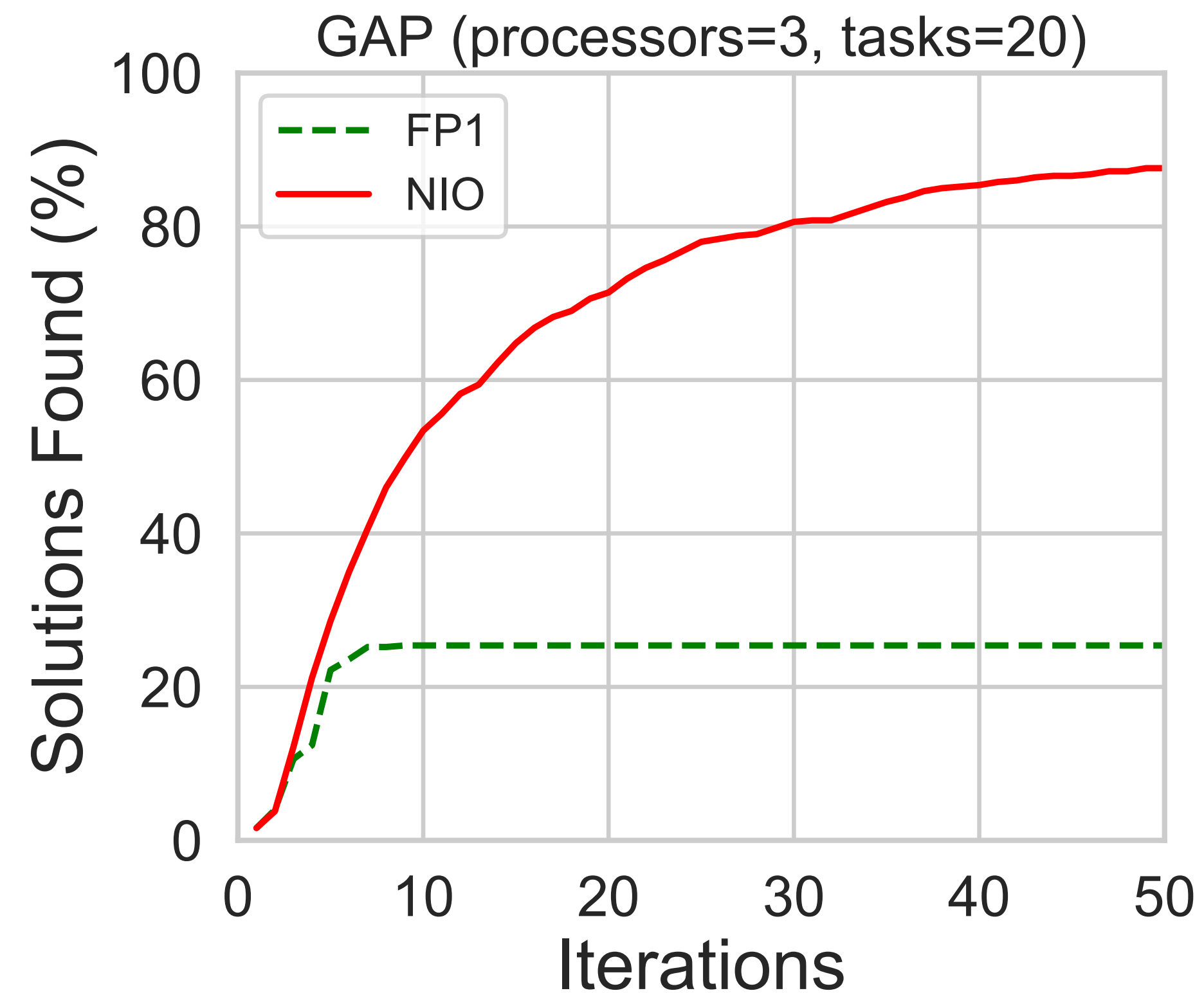
- ▶ Generate Training / Validation / Testing instances
 - ▶ **No need to solve Training instances!**
- ▶ NIO is **fully differentiable**
 - ▶ Train with gradient descent

$$\begin{aligned} & \underset{x}{\text{maximize}} && \sum_{i=1}^m \sum_{j=1}^n p_{ij} x_{ij} \\ & \text{subject to} && \sum_{j=1}^n w_{ij} x_{ij} \leq c_i, \quad i = 1, \dots, m, \\ & && \sum_{i=1}^m x_{ij} = 1, \quad j = 1, \dots, n, \\ & && x_{ij} \in \{0, 1\}, \quad i = 1, \dots, m, j = 1, \dots, n. \end{aligned}$$

Learning IP Heuristics in Practice

Generalized Assignment Problem (GAP)

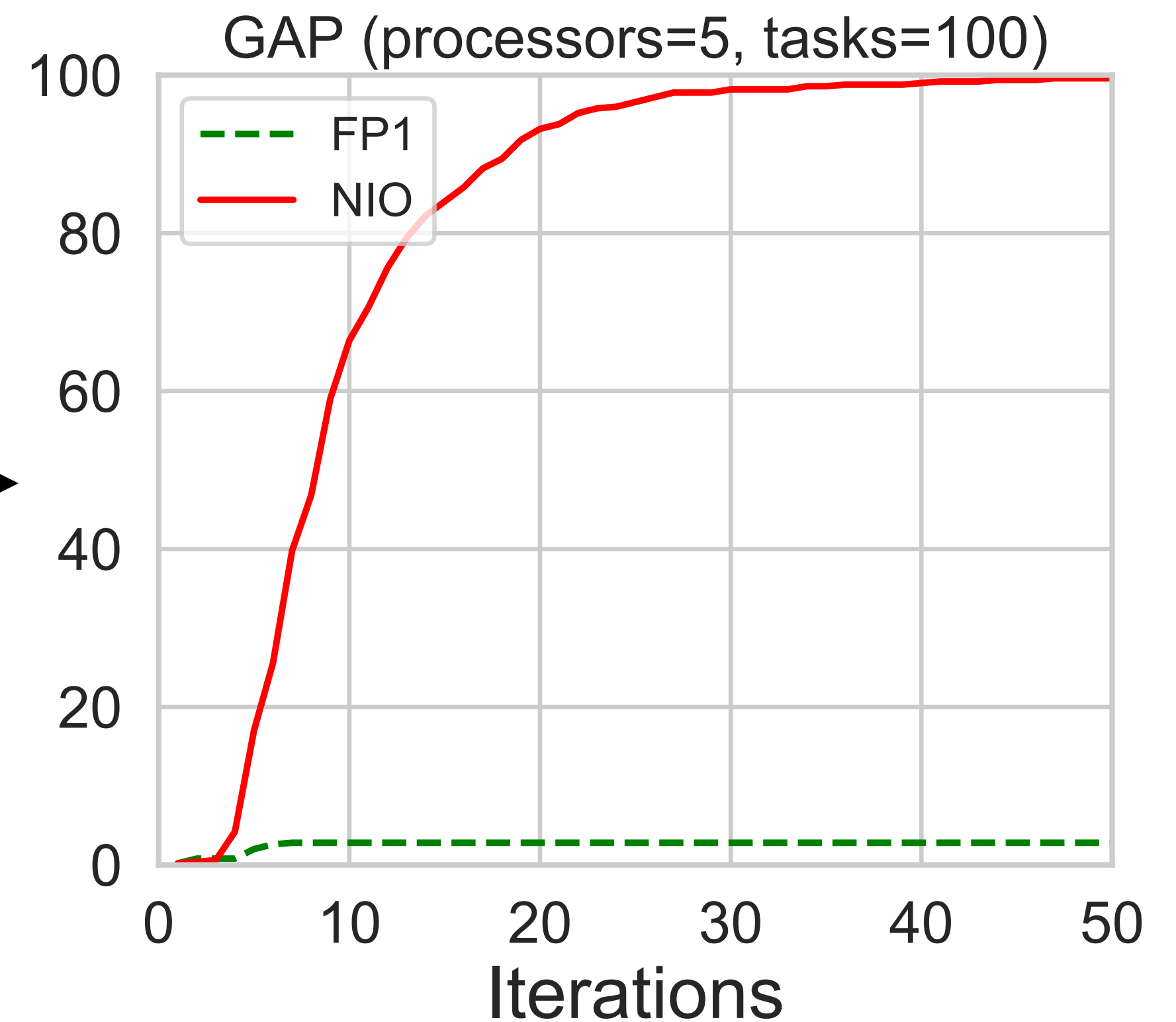
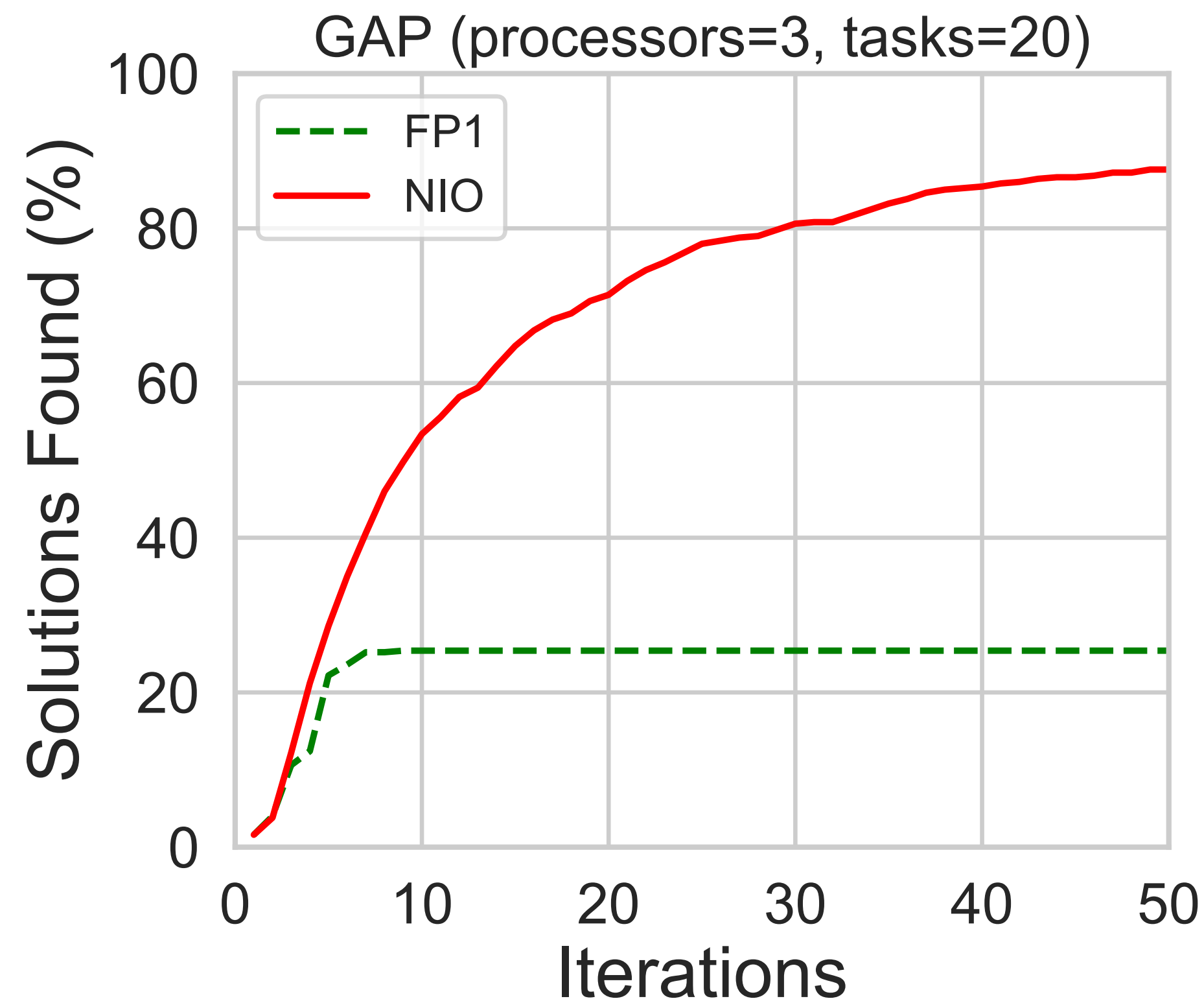
Train on 500 small instances, Test on 500 larger instances



Learning IP Heuristics in Practice

Generalized Assignment Problem (GAP)

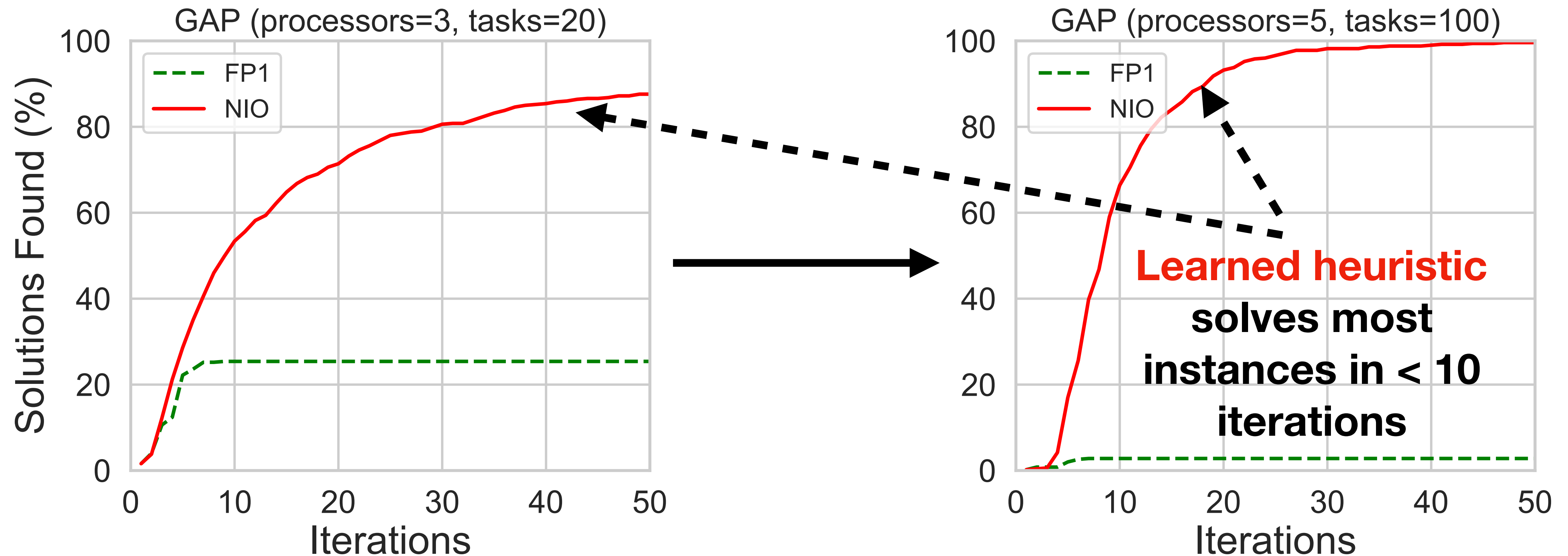
Train on 500 small instances, Test on 500 larger instances



Learning IP Heuristics in Practice

Generalized Assignment Problem (GAP)

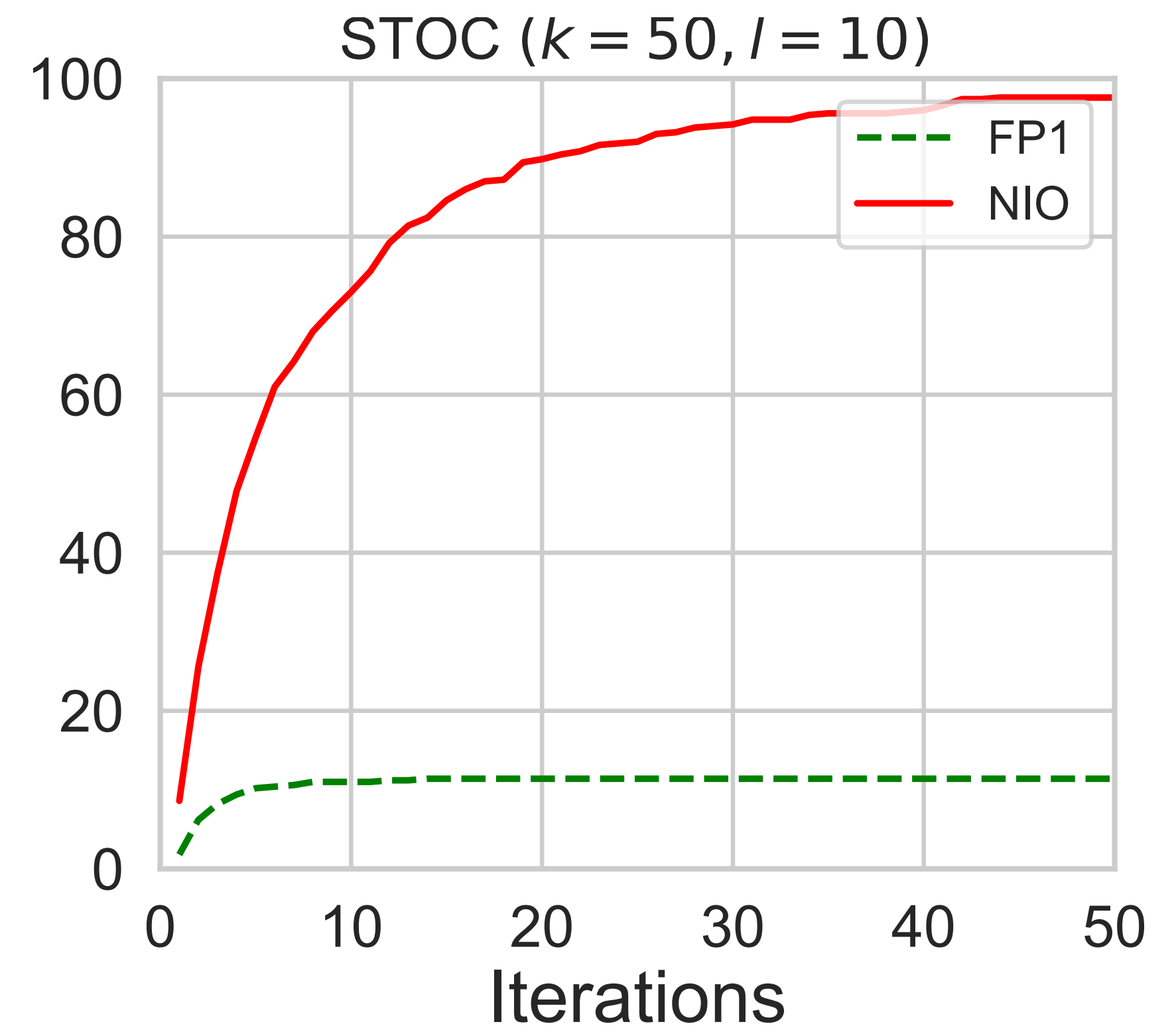
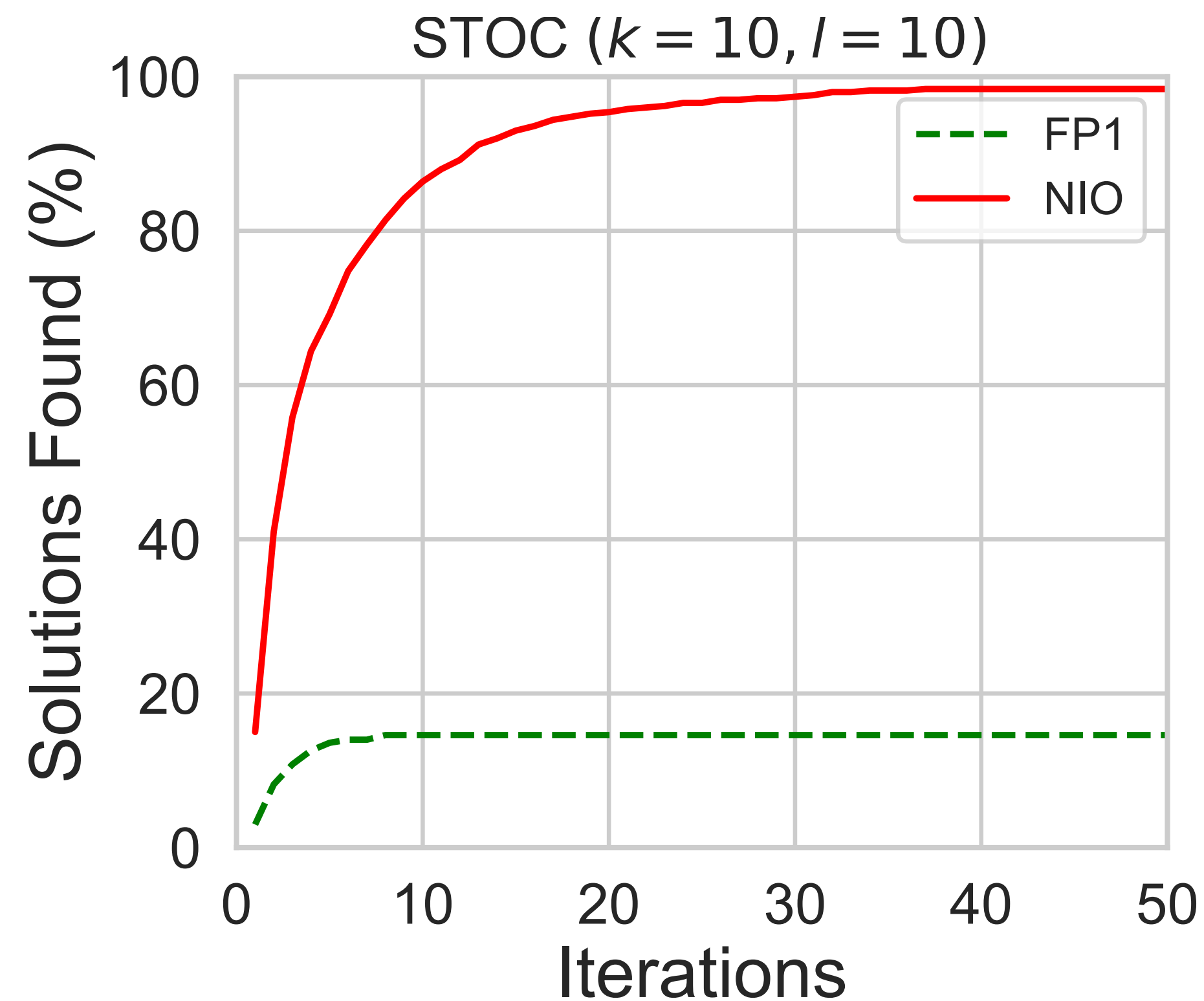
Train on 500 small instances, Test on 500 larger instances



Learning IP Heuristics in Practice

Two-Stage Stochastic Integer Programs (STOC)

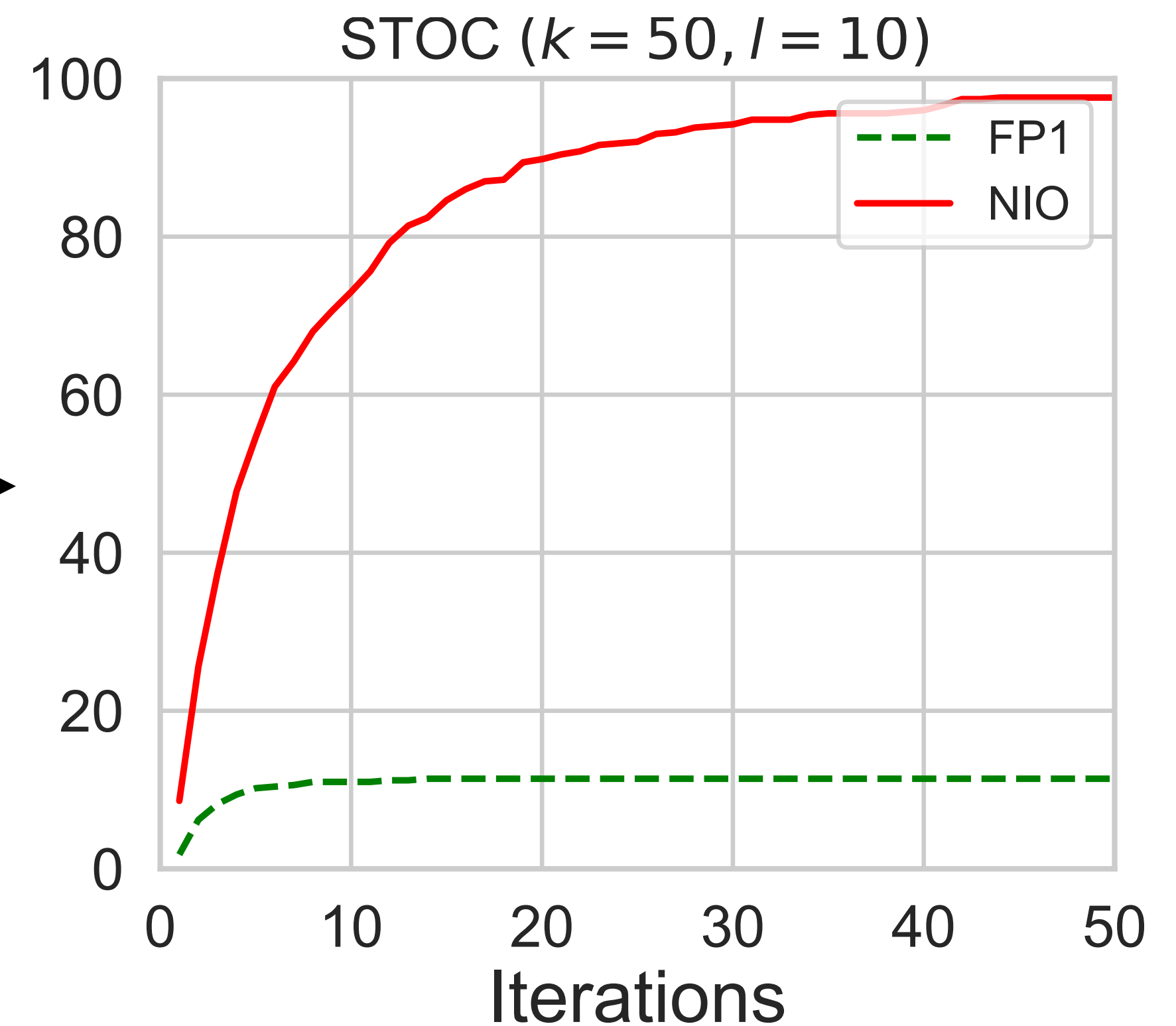
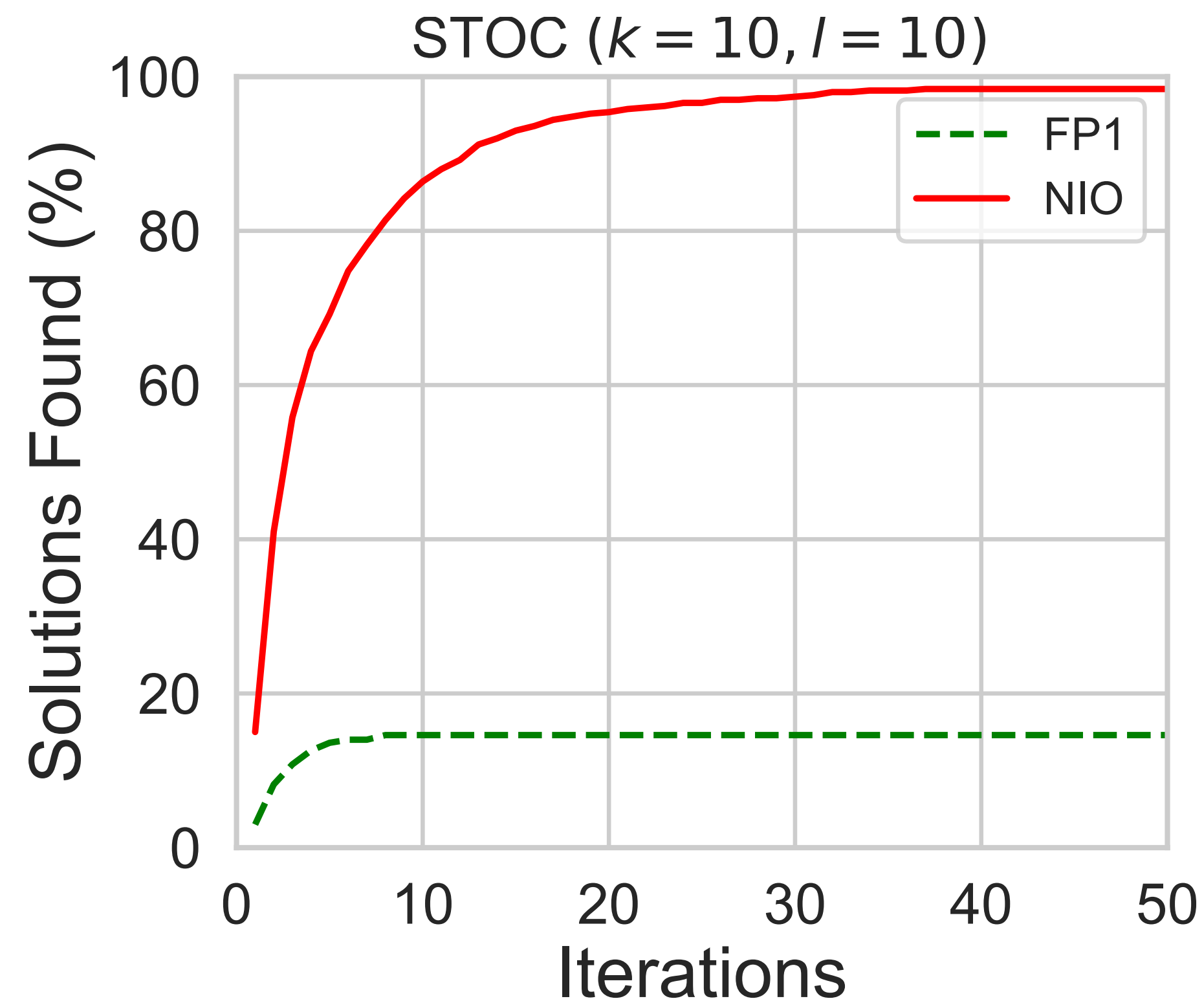
Train on 500 small instances, Test on 500 larger instances



Learning IP Heuristics in Practice

Two-Stage Stochastic Integer Programs (STOC)

Train on 500 small instances, Test on 500 larger instances



What about advanced codes?

Two-Stage Stochastic Integer Programs (STOC)

FP1 + presolve + propagation



	NIO	FP2	FP1
STOC (10,10)	99.2	95.4	14.6
STOC (20,20)	22.6	0.6	0
STOC (30,20)	7.6	0	0

Solutions Found (%) in 100 iterations

Compared to Pure Neural Net

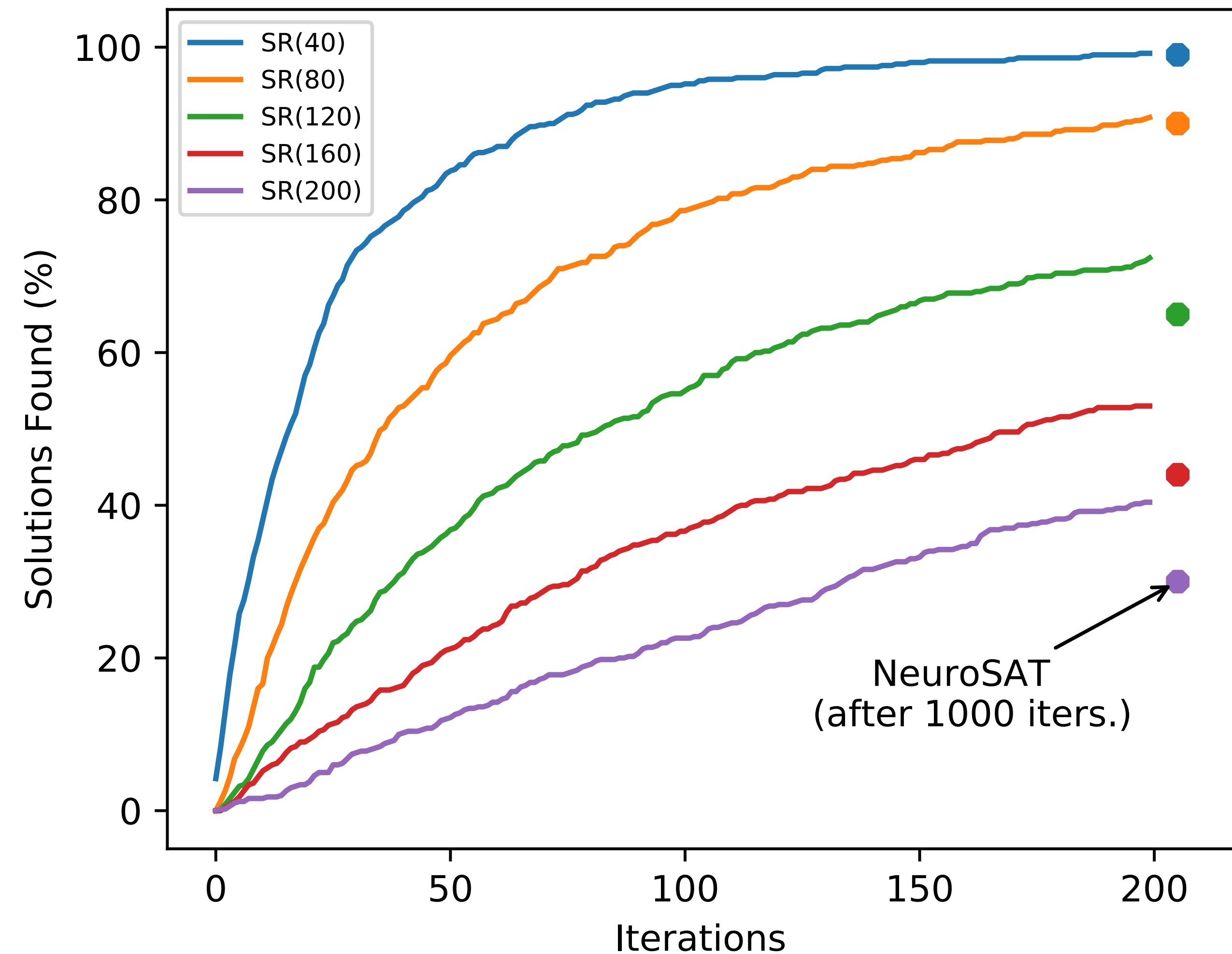


Easy for
SAT solvers

- ▶ **SAT**isfiability problem
- ▶ **NIO**: use model from GAP on SAT
- ▶ **NeuroSAT***: Deep Learning model for SAT solving
 - ▶ Trained with **supervised** learning
 - ▶ **Millions of training instances**

* Learning a SAT Solver from Single-Bit Supervision. ICLR 2019

Higher is Better



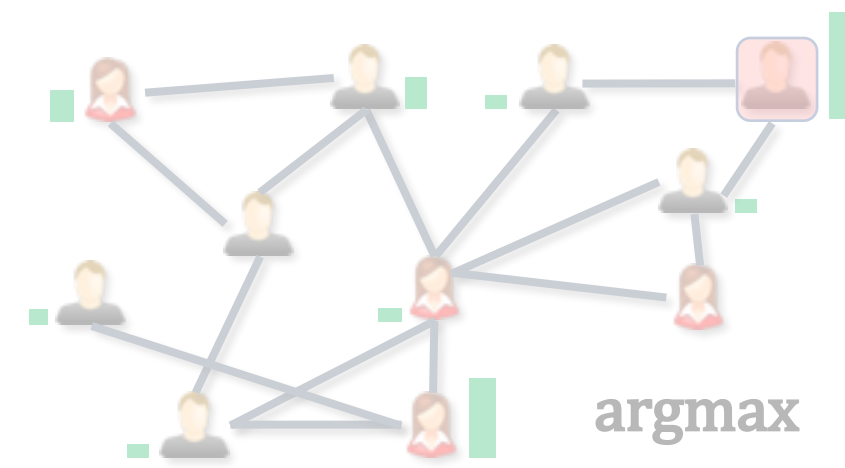
ML Paradigm

Self-Supervised Learning ■

Reinforcement Learning ■

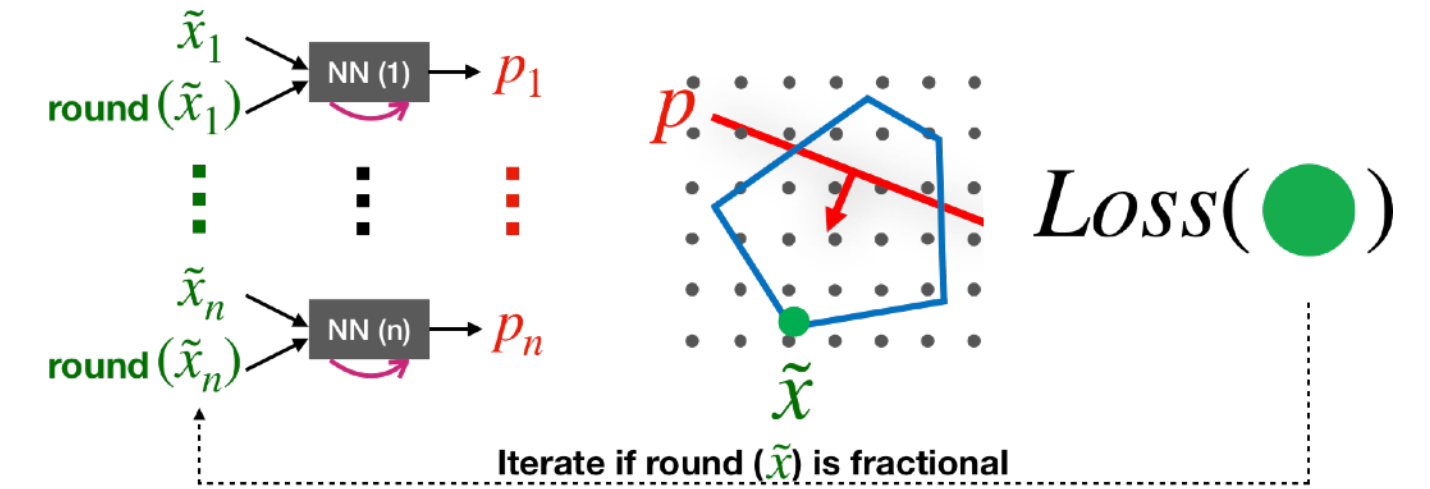
Supervised Learning ■

Greedy Heuristic



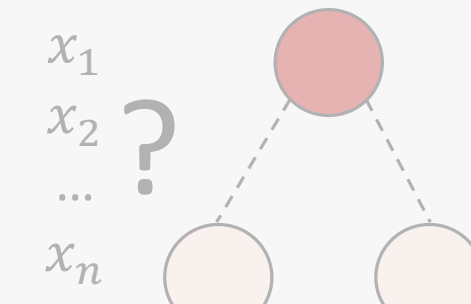
Graph Optimization

General IP Heuristic

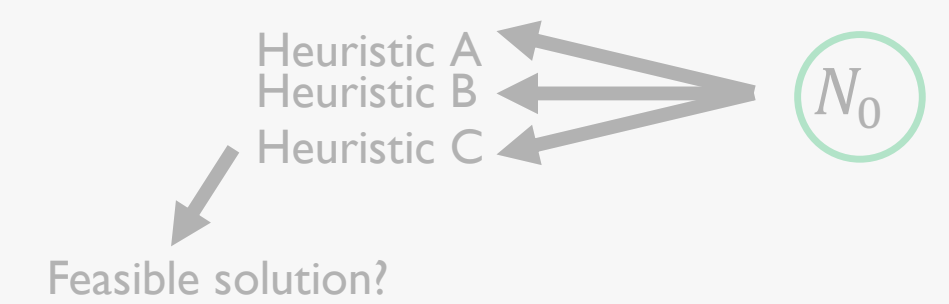


Exact Solving

Branching



Heuristic Selection



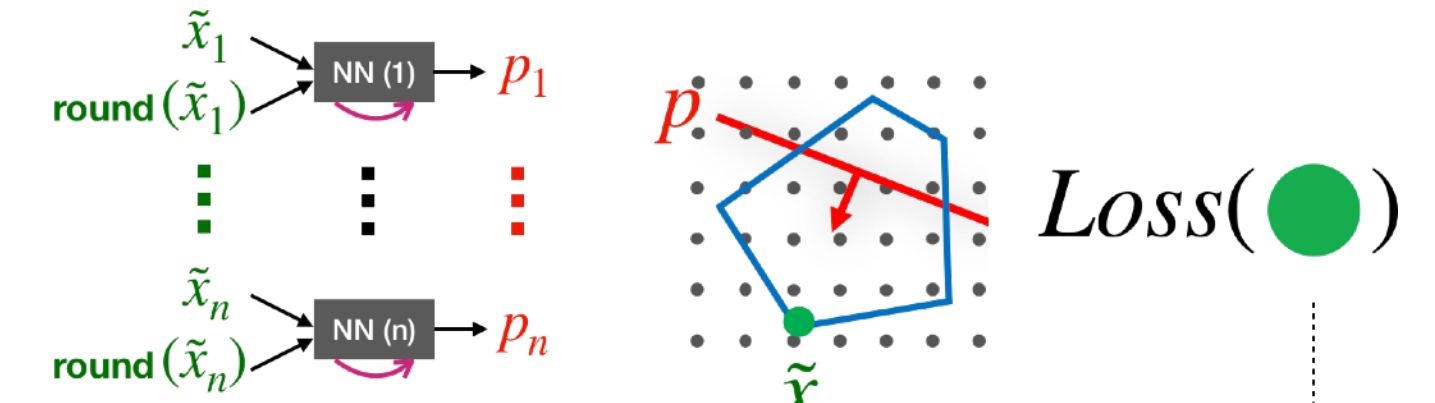
Integer Programming

Problem Type

ML Paradigm

Self-Supervised Learning ■

General IP Heuristic



Greedy Heuristic

Rein

Takeaways

- ▶ Incorporate **LP-projections** into **neural network** model
- ▶ Can **learn** heuristics for **arbitrary Integer Programs**
- ▶ **No supervised or reinforcement learning required!**
- ▶ **Outperforms** the **Feasibility Pump** on various problems

Graph Optimization Integer Programming

Problem Type

Humans learn to **design algorithms**.

Can **algorithms** “learn” to
design algorithms?

The diagram features a central question: "Can algorithms 'learn' to design algorithms?". The word "algorithms" is highlighted in yellow. A white arrow points from the first "algorithms" to the text "Machine Learning" above it. A yellow arrow points from the second "algorithms" to the text "Discrete Optimization" below it.

Machine Learning

Discrete Optimization

Machine Learning

Can **algorithms** “learn” to
design algorithms?

Discrete Optimization

Machine Learning

Can algorithms “learn” to

~~design~~ **algorithms?**
tailor

Discrete Optimization

Machine Learning

Can algorithms “learn” to
~~design~~ **algorithms**?
tailor

Discrete Optimization

Yes!

Machine Learning

Can algorithms “learn” to
~~design~~ **tailor** algorithms?

Discrete Optimization

Yes!

ML complements human algorithms

ML fills in algorithm **details using data**

Data-Driven Algorithm Design

Impact in ML and OPT

ML models for DiscOpt

- ◆ Attention for TSP [Kool+, 2019]
- ◆ Graph Convolutions [Li+, 2018]
- ◆ Imitation learning [Song+, 2018]

Combinatorial problems

- ◆ SAT [Selsam+, 2019]
- ◆ SMT [Balunovic+, 2018]
- ◆ k-Coverage [Li+, 2019]
- ◆ Scheduling [Mao+, 2019]
- ◆ Assignment [Emami+, 2018]
- ◆ VRP [Nazari+, 2018]
- ◆ Multiple-TSP [Kaempfer+, 2018]
- ◆ Stochastic Opt. [Nair+, 2018]

Branch-and-Bound

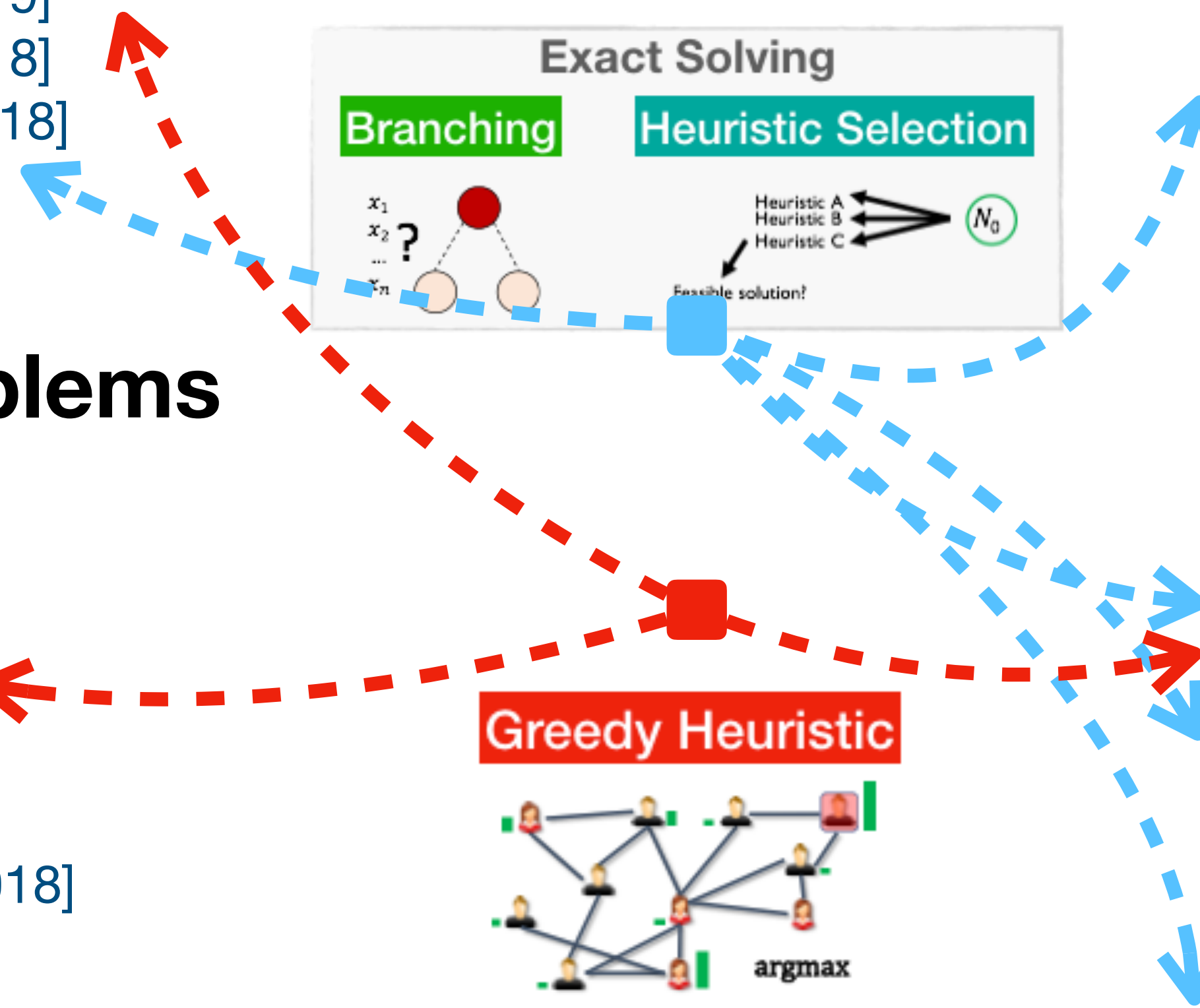
- ◆ Multi-objective IP [Sierra-Altamiranda+, 2019]
- ◆ Outcome prediction [Fischetti+, 2019]
- ◆ Cut selection [Baltean-Lugojan+, 2018]
- ◆ Formulation selection [Bonami+, 2018]
- ◆ Solution prediction [Larsen+, 2018]
- ◆ Decompositions [Kruber+, 2017]

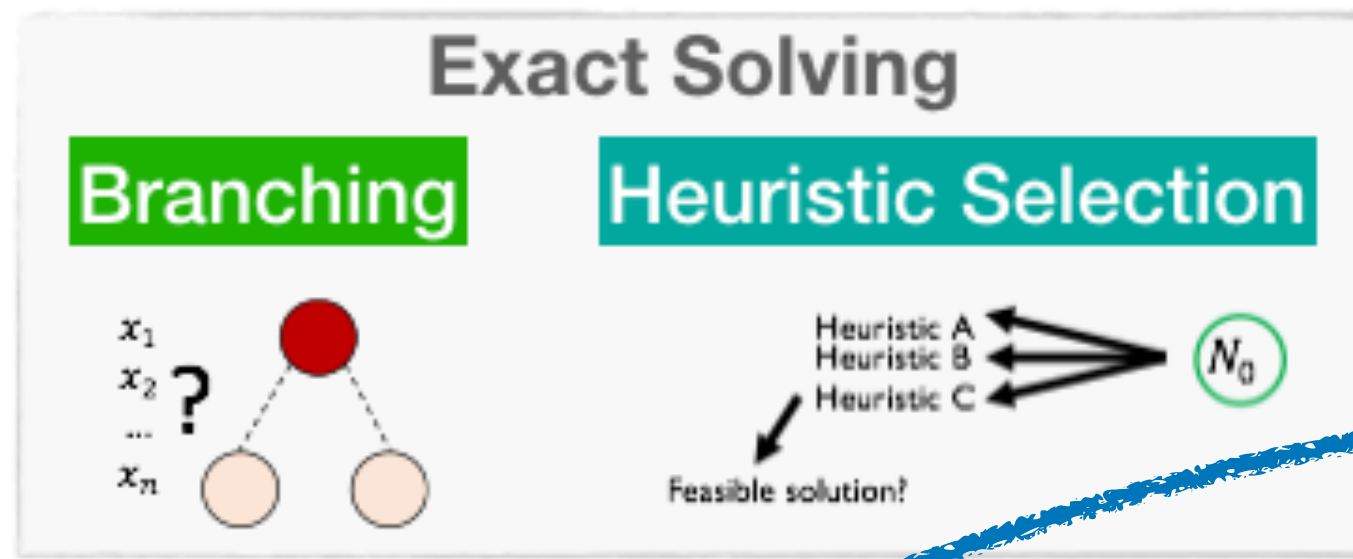
Applications

- ◆ Unit commitment [Xavier+, 2019]
- ◆ Sensor placement [Shen+, 2019]
- ◆ Recommender systems [Fu+, 2017]

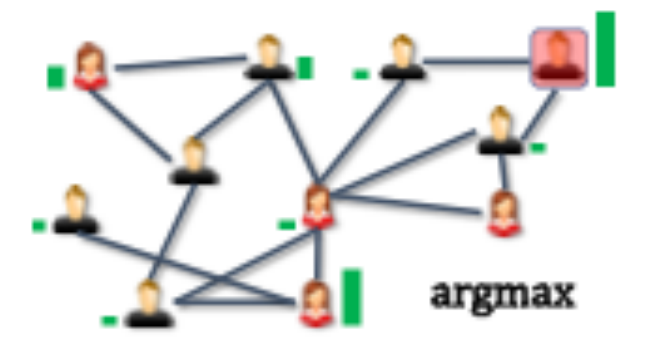
Theory

- ◆ Learning to Branch [Balcan+, 2018]

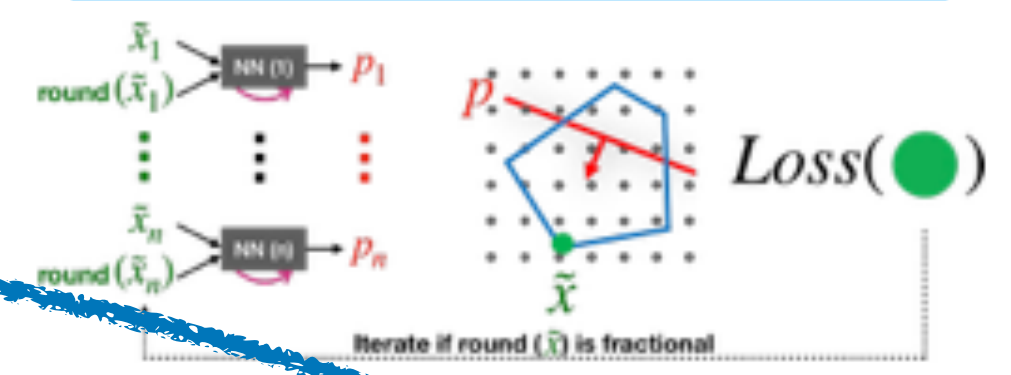




Greedy Heuristic



General Integer Programming Heuristic

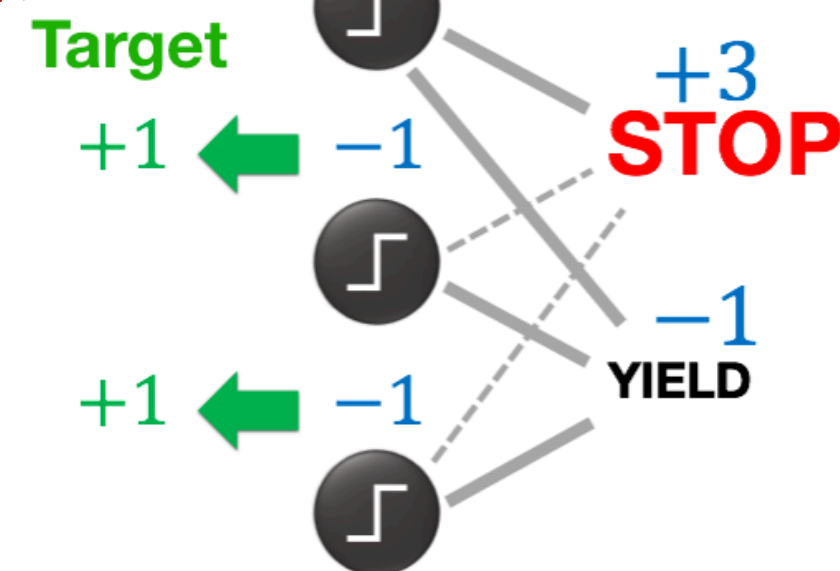


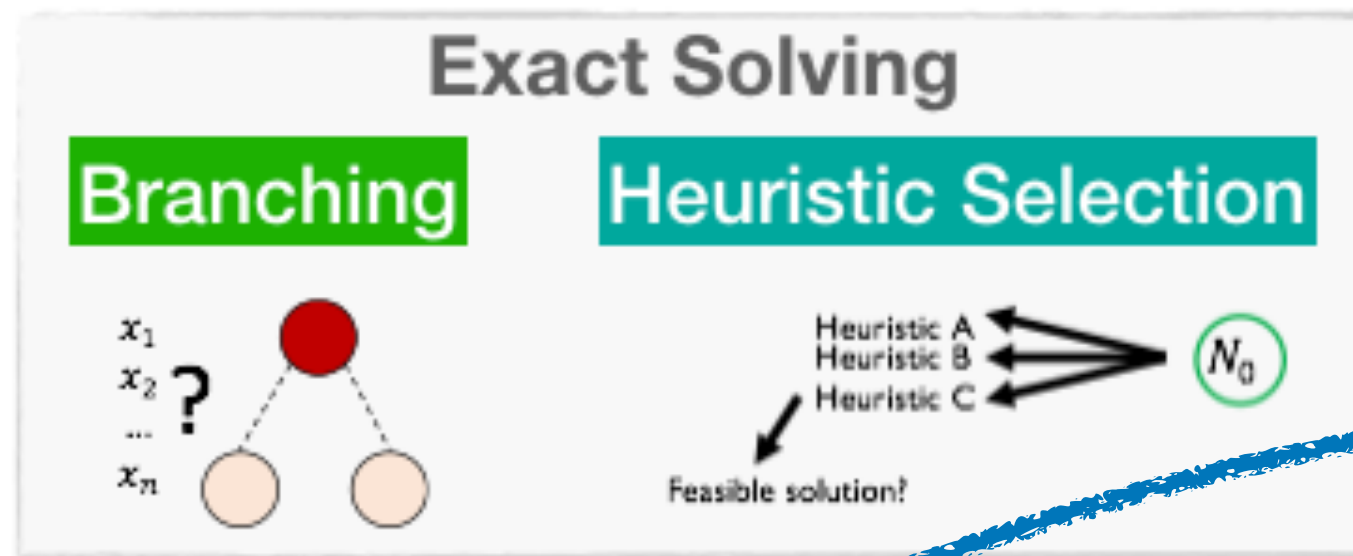
Machine Learning

Discrete Optimization

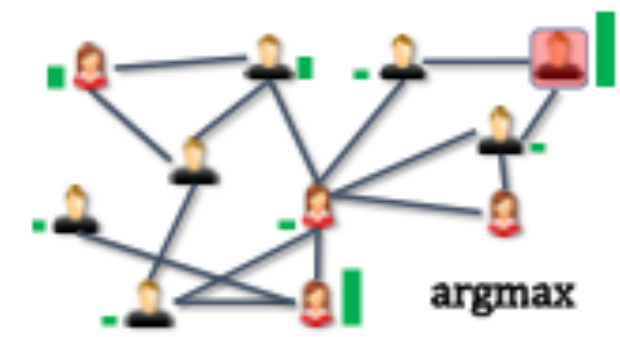


Attack

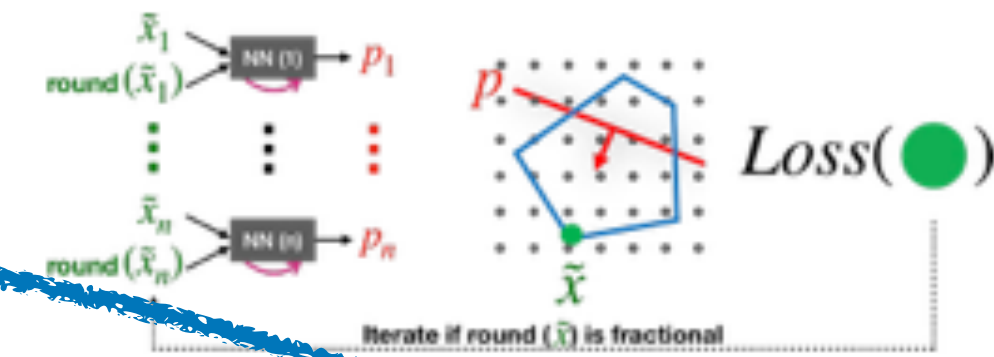




Greedy Heuristic



General Integer Programming Heuristic



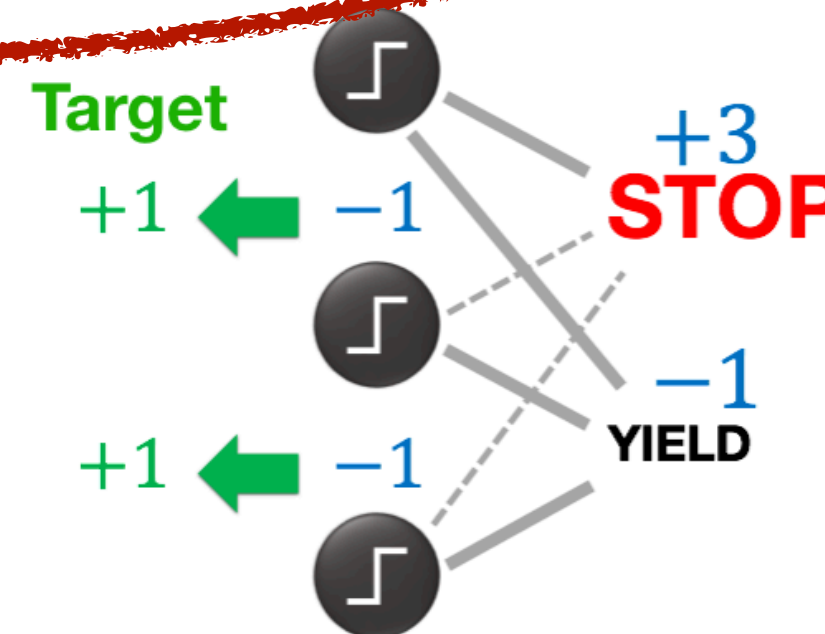
Machine Learning

ML x OPT
Exciting synergies and challenges in both directions

Discrete Optimization



Attack



Questions?

www.ekhalil.com

Relevant papers

Neural Integer Optimization: Learning to Satisfy Generic Constraints.
w/ R. Trivedi, B. Dilkina. **Submitted to NeurIPS 2019.**

Learning Combinatorial Optimization Algorithms over Graphs.
w/ H. Dai (co first auth.), Y. Zhang, B. Dilkina, L. Song. **NeurIPS 2017.**

Learning To Run Heuristics in Tree Search.
w/ B. Dilkina, G. Nemhauser, S. Ahmed, Y. Shao. **IJCAI 2017.**

Learning to Branch in Mixed Integer Programming.
w/ P. Le Bodic, L. Song, G. Nemhauser, B. Dilkina. **AAAI 2016.**

Combinatorial Attacks on Binarized Neural Networks.
w/ A. Gupta, B. Dilkina. **ICLR 2019.**

