

# Testing: Coverage and Structural Coverage

Testing, Quality Assurance, and Maintenance  
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based on slides by Prof. Marsha Chechik and Prof.  
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# How would you test this program?

`floor(x)` is the largest integer not greater than `x`.

```
def Foo (x, y):  
    """ requires: x and y are int  
        ensures: returns floor(max(x,y)/min(x, y)) """  
    if x > y:  
        return x / y  
    else  
        return y / x
```

# Testing

## Static Testing [at compile time]

- Static Analysis
- Review
  - Walk-through [informal]
  - Code inspection [formal]

## Dynamic Testing [at run time]

- Black-box testing
- White-box testing

Commonly, testing refers to dynamic testing.

# Complete Testing?

Poorly defined terms: “complete testing”, “exhaustive testing”, “full coverage”

The number of potential inputs are infinite.

Impossible to completely test a nontrivial system

- Practical limitations: Complete testing is prohibitive in time and cost [e.g., 30 branches, 50 branches, ...]
- Theoretical limitations: e.g. Halting problem

Need testing criteria

# CFG Exercise (1)

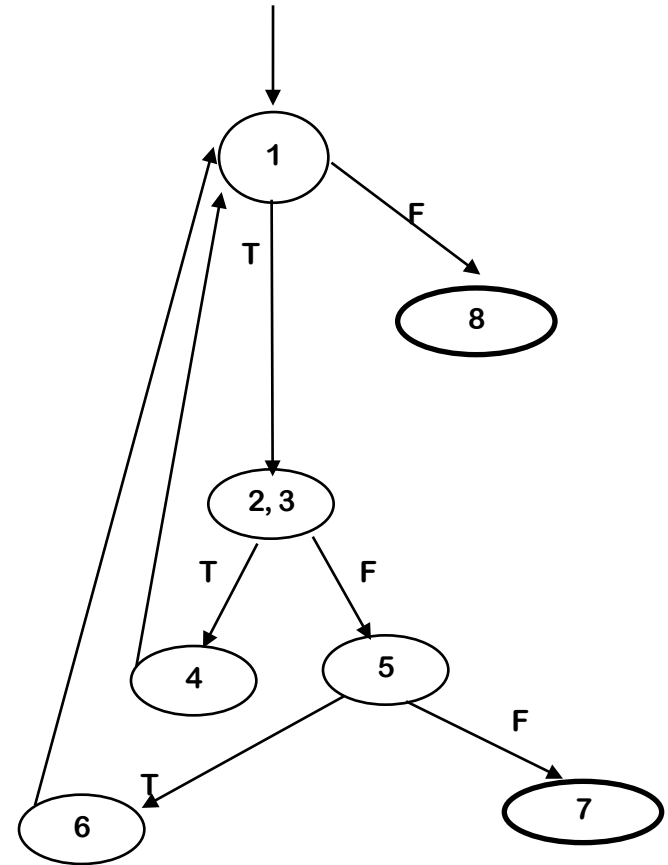
Draw a control flow graph with **7** nodes.

```
int binary_search(int a[], int low, int high,
int target) { /* binary search for target in
the sorted a[low, high] */
1   while (low <= high) {
2       int middle = low + (high - low)/2;
3       if (target < a[middle])
4           high = middle - 1;
5       else if (target > a[middle])
6           low = middle + 1;
       else
7           return middle;
    }
8   return -1; /* return -1 if target is not
found in a[low, high] */
}
```

# CFG Exercise (1) Solution

Draw a control flow graph with **7** nodes.

```
int binary_search(int a[], int low, int high,
int target) { /* binary search for target in
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2    int middle = low + (high - low)/2;
3    if (target < a[middle])
4      high = middle - 1;
5    else if (target > a[middle])
6      low = middle + 1;
  else
7    return middle;
  }
8  return -1; /* return -1 if target is not
found in a[low, high] */
}
```



# Test Case

## Test Case: [informally]

- What you feed to software; and
- What the software should output in response.

## Test Set: A set of test cases

**Test Case:** test case values, expected results, prefix values, and postfix values necessary to evaluate software under test

**Expected Results:** The result that will be produced when executing the test if and only if the program satisfies its intended behaviour

# Test Requirement & Coverage Criterion

**Test Requirement:** A test requirement is a specific element of a software artifact that a test case must satisfy or cover.

- Ice cream cone flavors: vanilla, chocolate, mint
- One test requirement: test one chocolate cone
- **TR** denotes a set of test requirements

A **coverage criterion** is a rule or collection of rules that impose test requirements on a test set.

- Coverage criterion is a recipe for generating TR in a systematic way.
- Flavor criterion [cover all flavors]
- TR = {flavor=chocolate, flavor=vanilla, flavor=mint}



# Adequacy criteria

Adequacy criterion = set of test requirements

A test suite satisfies an adequacy criterion if

- all the tests succeed (pass)
- every test requirement in the criterion is satisfied by at least one of the test cases in the test suite.

Example:

*the statement coverage adequacy criterion is satisfied by test suite  $S$  for program  $P$  if each executable statement in  $P$  is executed by at least one test case in  $S$ , and the outcome of each test execution was “pass”*

# Adequacy Criteria as Design Rules

Many design disciplines employ design rules

- e.g.: “traces (on a chip, on a circuit board) must be at least \_\_\_\_ wide and separated by at least \_\_\_\_”
- “Interstate highways must not have a grade greater than 6% without special review and approval”

Design rules do not guarantee good designs

- Good design depends on talented, creative, disciplined designers; design rules help them avoid or spot flaws

Test design is no different

# Where do test requirements come from?

Functional (black box, specification-based): from software specifications

- Example: If spec requires robust recovery from power failure, test requirements should include simulated power failure

Structural (white or glass box): from code

- Example: Traverse each program loop one or more times.

Model-based: from model of system

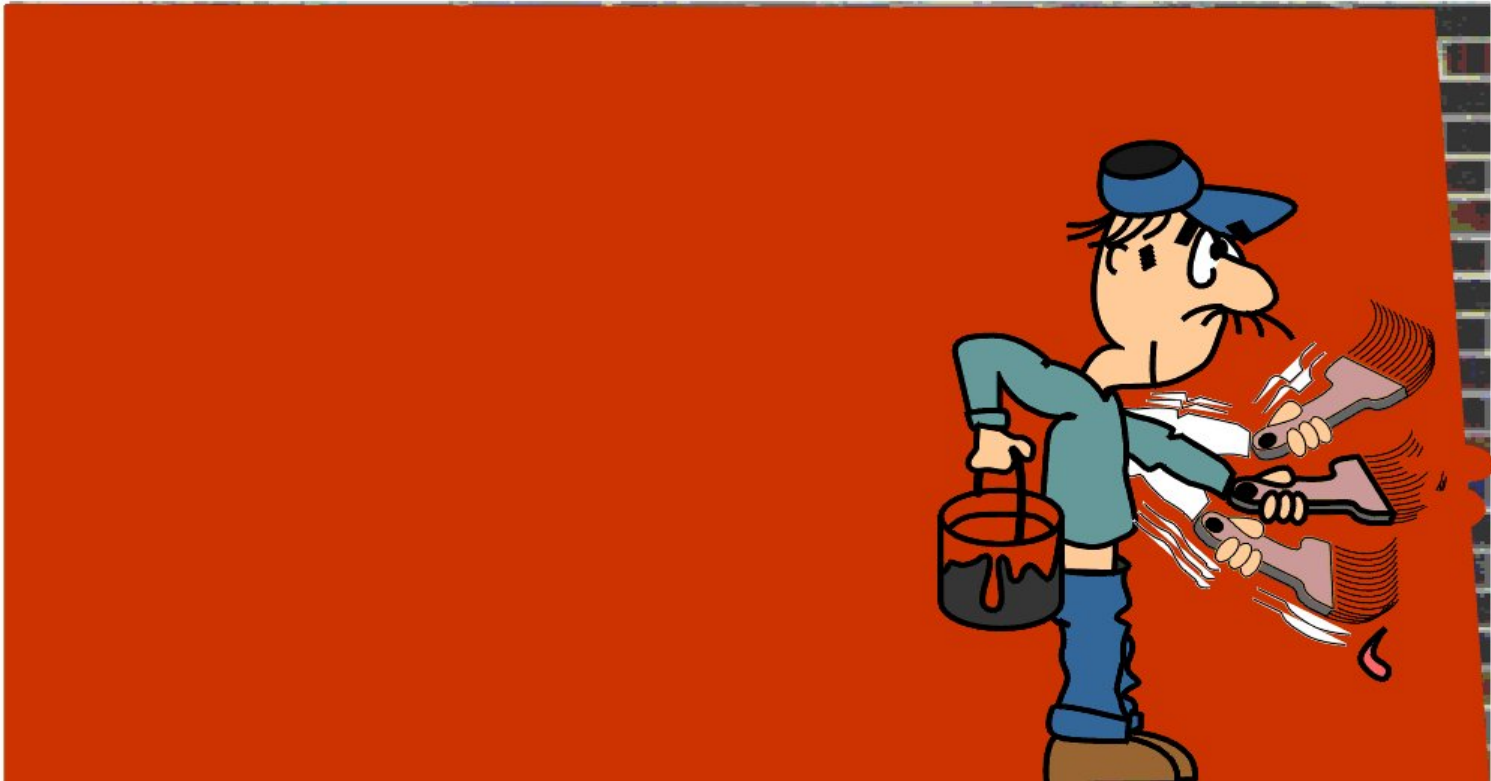
- Models used in specification or design, or derived from code
- Example: Exercise all transitions in communication protocol model

Fault-based: from hypothesized faults (common bugs)

- example: Check for buffer overflow handling (common vulnerability) by testing on very large inputs

# Code Coverage

Introduced by Miller and Maloney in 1963



# Coverage Criteria

Basic Coverage



- Line coverage
- Statement
- Function/Method coverage
- Branch coverage
- Decision coverage
- Condition coverage
- Condition/decision coverage
- Modified condition/decision coverage
- Path coverage
- Loop coverage
- Mutation adequacy
- ...

Advanced Coverage

# Line Coverage

Percentage of source code lines executed by test cases.

- For developer easiest to work with
- Precise percentage depends on layout?
  - `int x = 10; if (z++ < x) y = x+z;`
- Requires mapping back from binary?

In practice, coverage not based on lines, but on control flow graph

# Deriving a Control Flow Graph

```
public static String collapseNewlines(String argStr)
```

```
{  
    char last = argStr.charAt(0);  
    StringBuffer argBuf = new StringBuffer();
```

```
    for (int cldx = 0; cldx < argStr.length(); cldx++)
```

```
    {  
        char ch = argStr.charAt(cldx);  
        if (ch != '\n' || last != '\n')
```

```
        {  
            argBuf.append(ch);  
            last = ch;
```

```
        }  
    }  
    return argBuf.toString();  
}
```

```
public static String collapseNewlines(String argStr)
```

```
{  
    char last = argStr.charAt(0);  
    StringBuffer argBuf = new StringBuffer();  
    for (int cldx = 0 ;
```

```
        cldx < argStr.length();
```

```
        False True
```

```
{  
    char ch = argStr.charAt(cldx);  
    if (ch != '\n'
```

```
        False True  
        || last != '\n')
```

```
{  
    argBuf.append(ch);  
    last = ch;
```

```
        False
```

```
        }  
        cldx++;
```

```
    return argBuf.toString();  
}
```

Splitting multiple conditions depends on goal of analysis

# Statement coverage

Adequacy criterion: each statement (or node in the CFG) must be executed at least once

```
void foo (int z) {  
    int x = 10;  
    if (z++ < x) {  
        x+= z;  
    }  
}
```

Coverage:

$$\frac{\text{\# executed statements}}{\text{\# statements}}$$



# Statement coverage

Adequacy criterion: each statement (or node in the CFG) must be executed at least once

```
void foo (int z) {  
    int x = 10;  
    if (z++ < x) {  
        x+= z;  
    }  
}
```

```
@Test  
void testFoo() {  
    foo(10);  
}
```

Coverage:

$$\frac{\text{\# executed statements}}{\text{\# statements}}$$

# Statement coverage

Adequacy criterion: each statement (or node in the CFG) must be executed at least once

```
void foo (int z) {  
    int x = 10;  
    if (z++ < x) {  
        x+= z;  
    }  
}
```

```
@Test  
void testFoo() {  
    foo(10);  
}
```

Coverage:

$$\frac{\text{\# executed statements}}{\text{\# statements}}$$

# Statement coverage

Adequacy criterion: each statement (or node in the CFG) must be executed at least once

```
void foo (int z) {  
    int x = 10;  
    if (z++ < x) {  
        x+= z;  
    }  
}
```

```
@Test  
void testFoo() {  
    foo(5);  
}  
// 100% Statement coverage
```

Coverage Level:

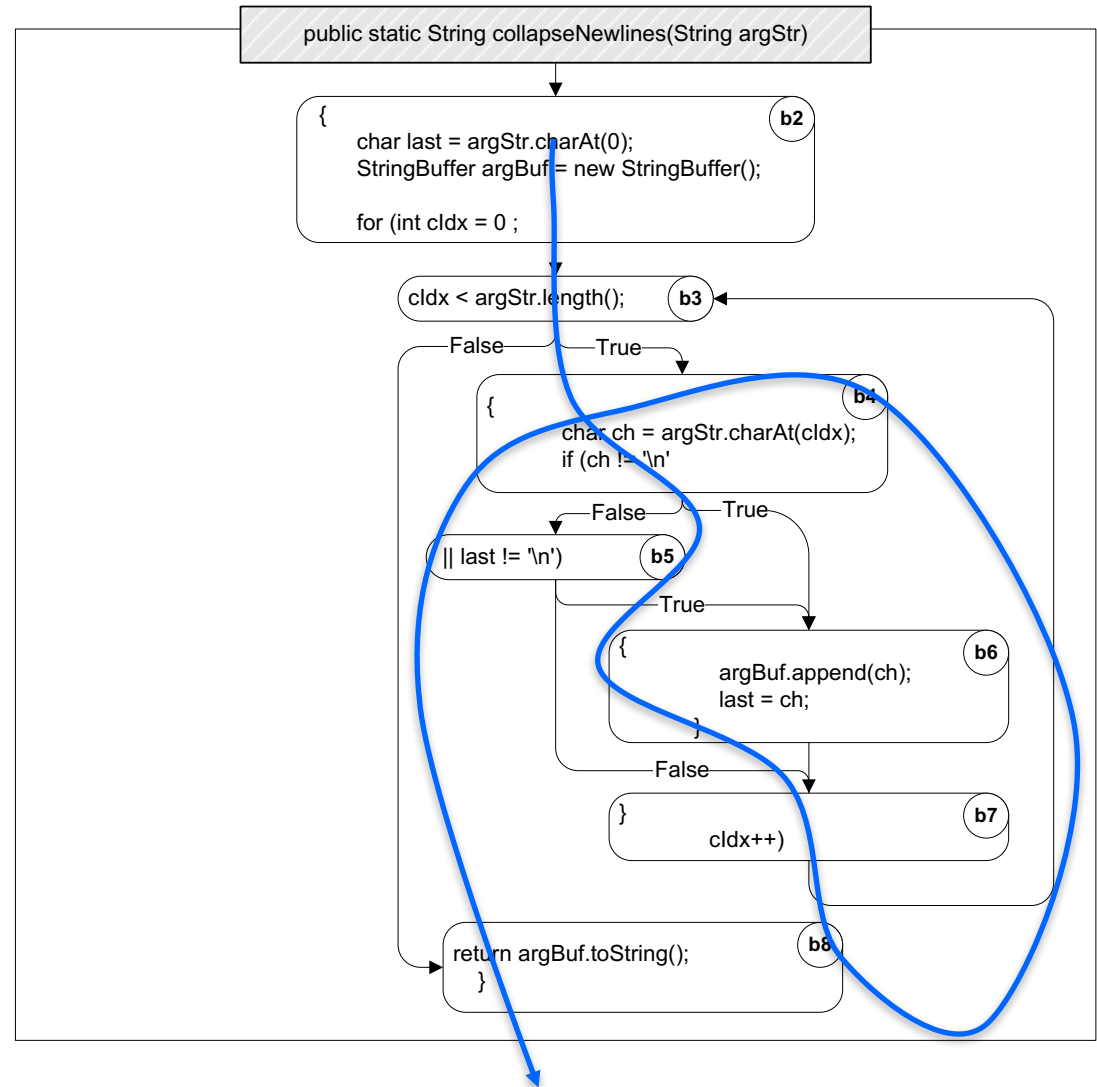
$$\frac{\text{\# executed statements}}{\text{\# statements}}$$

# Control Flow Based Adequacy Criteria

Every block / Statement?

Input: "a"

Trace: b2,b3,b4,b5,b6,b7,b3,b8



# Branch / Edge Coverage

Every branch going out of node executed at least once

- Decision-, all-edges-, coverage
- Coverage: percentage of edges hit.

Each branch predicate must be both true and false

# Branch Coverage

One longer input:

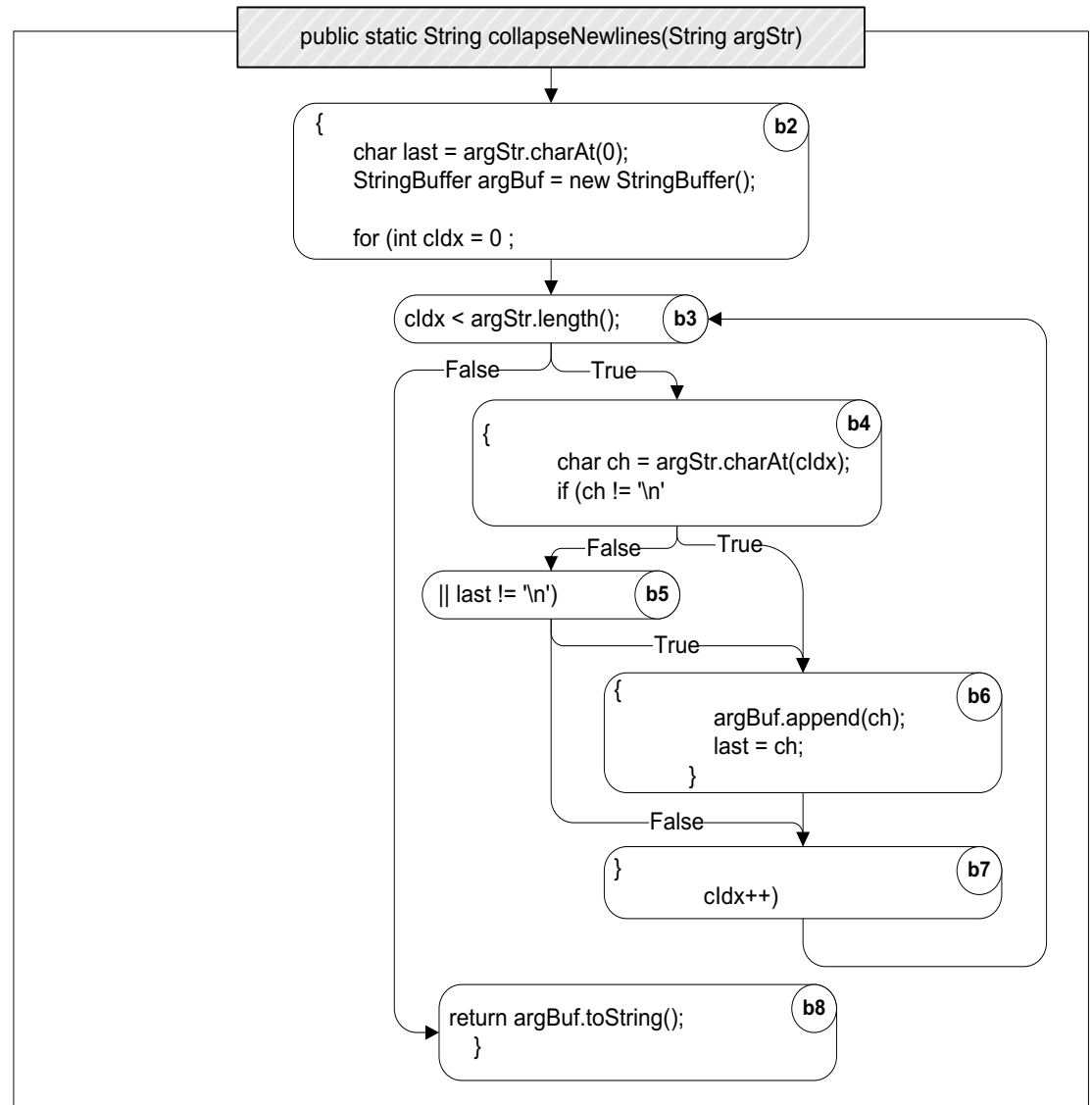
“a\n\n”

Alternatively:

Block (“a”) and

“\n” and

“\n\n”



# Infeasible Test Requirements

```
if (false)
    unreachableCall();
```

Real code from the Linux kernel:

```
while (0)
    {local_irq_disable();}
```

Statement coverage criterion cannot be satisfied for many programs.

# Coverage Level

Given a set of test requirements **TR** and a test set **T**, the *coverage level* is the ratio of the number of test requirements satisfied by **T** to the size of **TR**.

TR = {flavor=chocolate, flavor=vanilla, flavor=mint}

Test set 1 T1 = {3 chocolate cones, 1 vanilla cone}

Coverage Level =  $2/3 = 66.7\%$

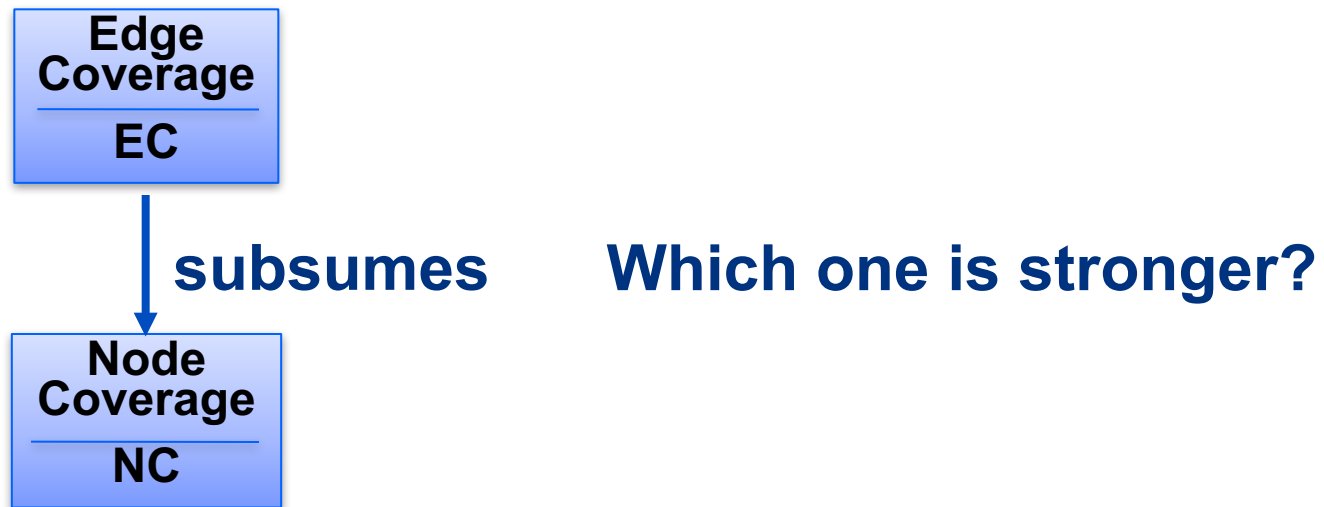
Coverage levels helps evaluate the goodness of a test set, especially in the presence of infeasible test requirements.



# Subsumption

**Criteria Subsumption:** A test criterion  $C1$  *subsumes*  $C2$  if and only if **every** set of test cases that satisfies criterion  $C1$  also satisfies  $C2$

Must be true for **every set** of test cases



Subsumption is a rough guide for comparing criteria, although it's hard to use in practice.

# More powerful coverage criterion helps find more bugs!

```
int d[2];
```

```
N1: if (x >= 0 && x < 2)
    { N2: print (x); }
```

```
N3: if (y > 0)
    { N4: print (d[x] + y); }
```

```
N5: exit (0);
```

Path [N1, N2, N3, N4, N5]:

satisfies node coverage but not edge coverage.

The corresponding test case passes. No bug found.

Path [N1, N3, N4, N5]: buffer overflow bug!

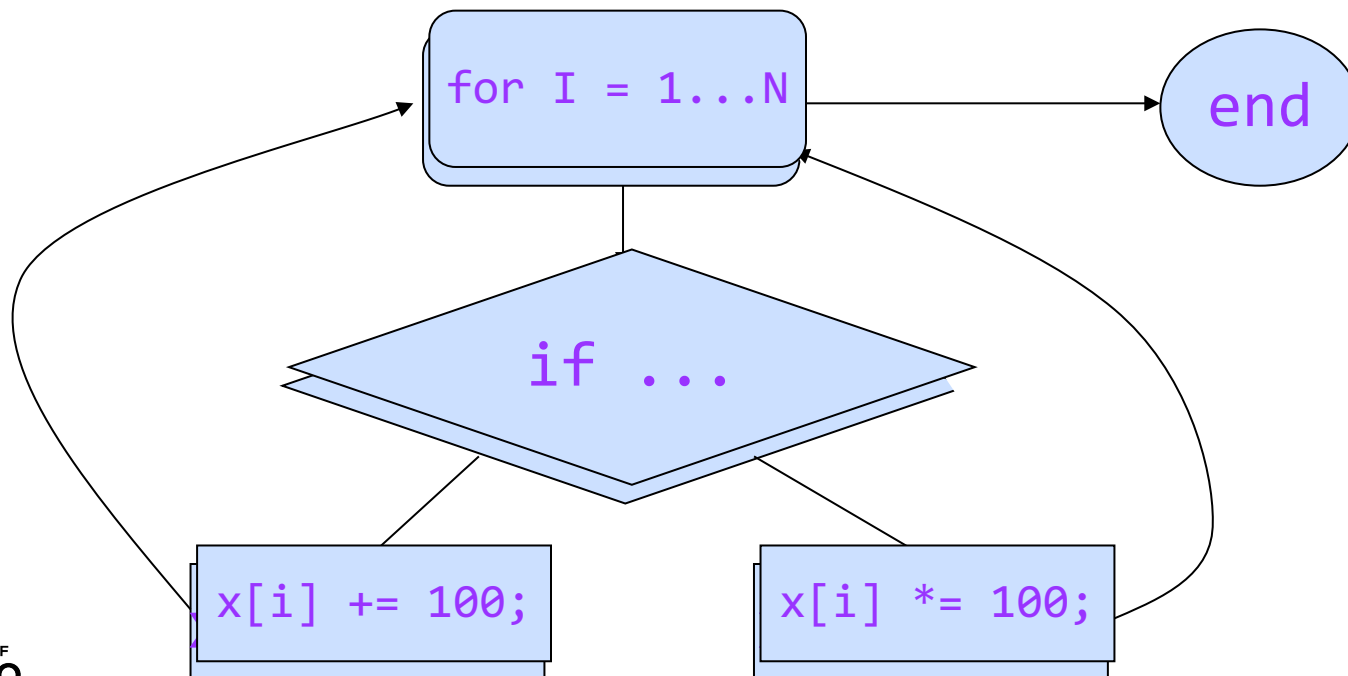
# Path Coverage

Adequacy criterion: each path must be executed at least once

Coverage:

# executed paths

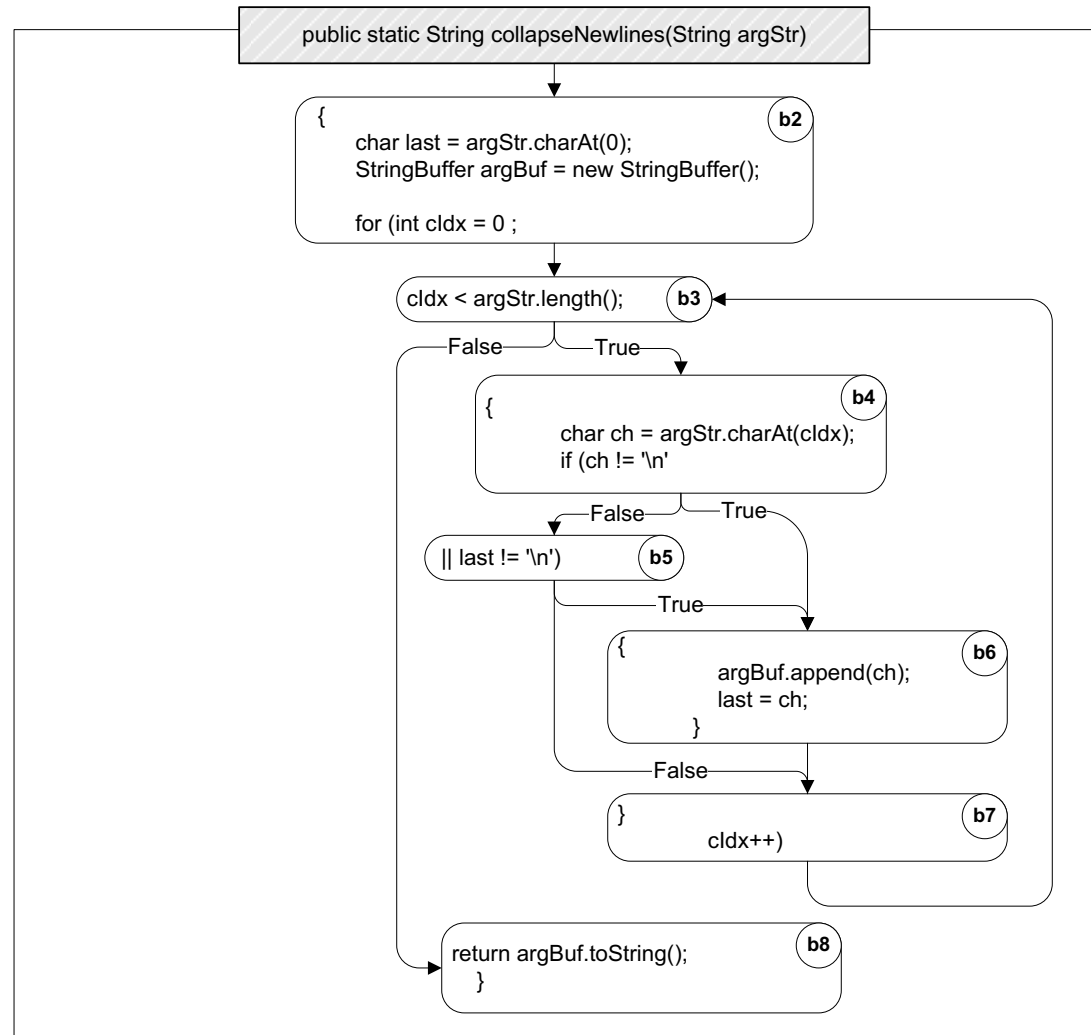
# paths



# Path-based criteria?

All paths?

Which paths?



# Branch vs Path Coverage

```
if( cond1 )  
    f1();  
else  
    f2();
```

How many test cases  
to achieve branch  
coverage?

```
if( cond2 )  
    f3();  
else  
    f4();
```

# Branch vs Path Coverage

```
if( cond1 )  
    f1();  
else  
    f2();
```

How many test cases to achieve branch coverage?

Two, for example:

```
if( cond2 )  
    f3();  
else  
    f4();
```

1. cond1: true, cond2: true
2. cond1: false, cond2: false

# Branch vs Path Coverage

```
if( cond1 )  
    f1();  
else  
    f2();
```

How about path coverage?

```
if( cond2 )  
    f3();  
else  
    f4();
```

# Branch vs Path Coverage

```
if( cond1 )  
    f1();  
else  
    f2();
```

```
if( cond2 )  
    f3();  
else  
    f4();
```

How about path coverage?

Four:

1. cond1: true, cond2: true
2. cond1: false, cond2: true
3. cond1: true, cond2: false
4. cond1: false, cond2: false



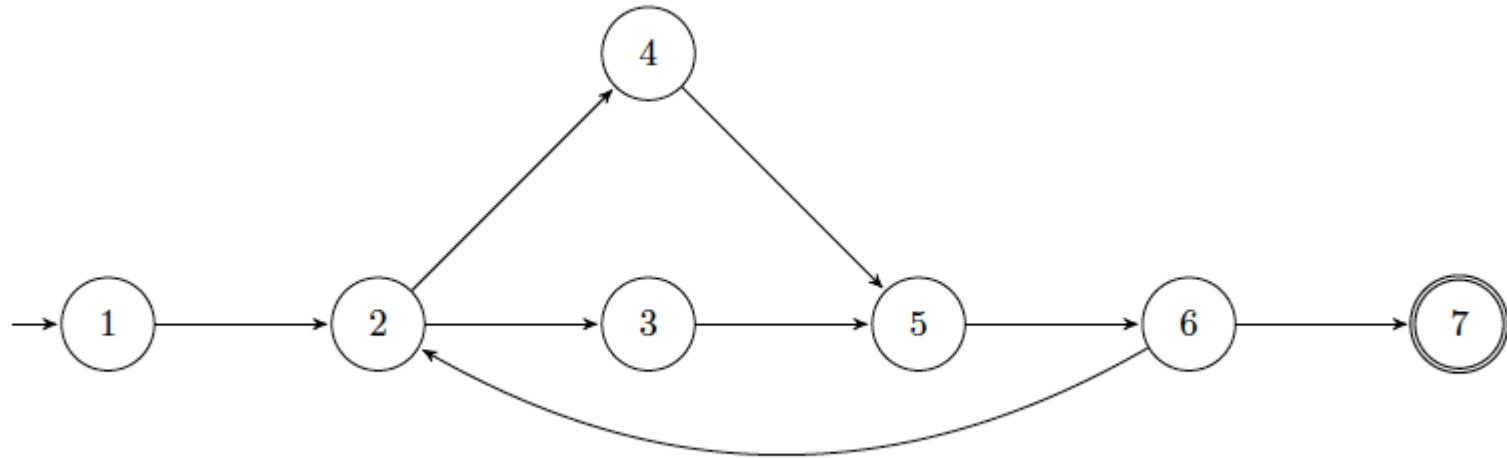
# Branch vs Path Coverage

```
if( cond1 )
    f1();
else
    f2();
if( cond2 )
    f3();
else
    f4();
if( cond3 )
    f5();
else
    f6();
if( cond4 )
    f7();
else
    f8();
if( cond5 )
    f9();
else
    f10();
if( cond6 )
    f11();
else
    f12();
if( cond7 )
    f13();
else
    f14();
```

**How many test cases for path coverage?**

**$2^n$  test cases, where n is the number of conditions**

# Test Path

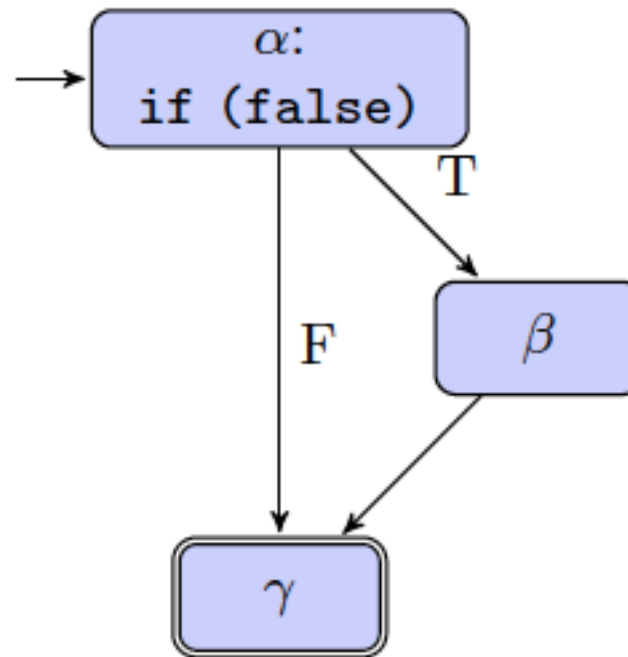


A **test path** is a path  $p$  [possibly of length 0] that starts at some node in  $N_0$  and ends at some node in  $N_f$ .

Test path examples:

- [1, 2, 3, 5, 6, 7]
- [1, 2, 3, 5, 6, 2, 3, 5, 6, 7]

# Paths and Semantics



**β is never  
executed!**

Some paths in a control flow graph may not correspond to program *semantics*.

In path coverage, we generally only talk about the *syntax* of a graph -- its nodes and edges -- and not its *semantics*.

# Syntactical and Semantic Reachability

A node  $n$  is *syntactically* reachable from  $m$  if there exists a path from  $m$  to  $n$ .

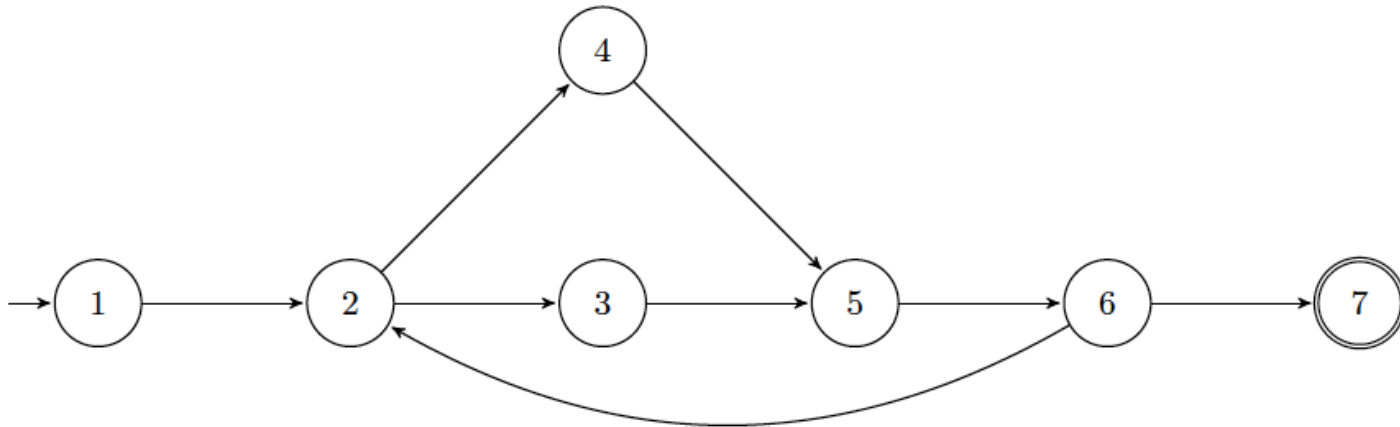
A node  $n$  is *semantically* reachable if one of the paths from  $m$  to  $n$  can be reached on some input.

Standard graph algorithms when applied to Control Flow Graph can only compute *syntactic reachability*.

*Semantic reachability* is undecidable.

# Reachability

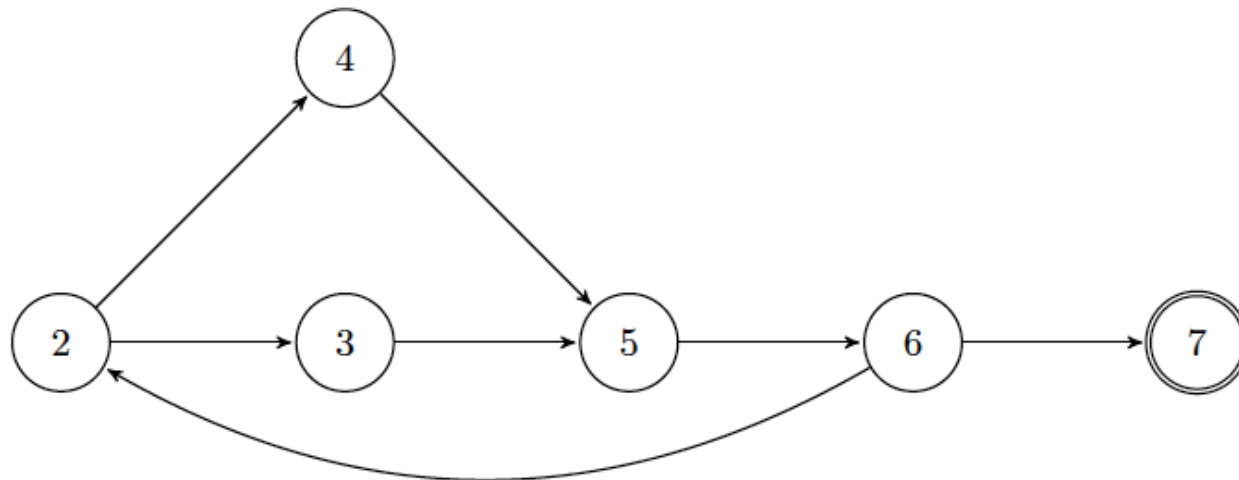
Let  $\text{reach}_G(X)$  denote the sub-graph of  $G$  that is (syntactically) reachable from  $X$ , where  $X$  is either a node, an edge, a set of nodes, or a set of edges.



In this example,  $\text{reach}_G(1)$  is the whole graph  $G$ .

# Syntactical Reachability

- $\text{reach}_{G\#}(2)$  is the subgraph that is syntactically reachable from node 2.



- $\text{reach}_{G\#}(7)$  is:



# Connect Test Cases and Test Paths

Connect test cases and test paths with a mapping  $path_G$  from test cases to test paths

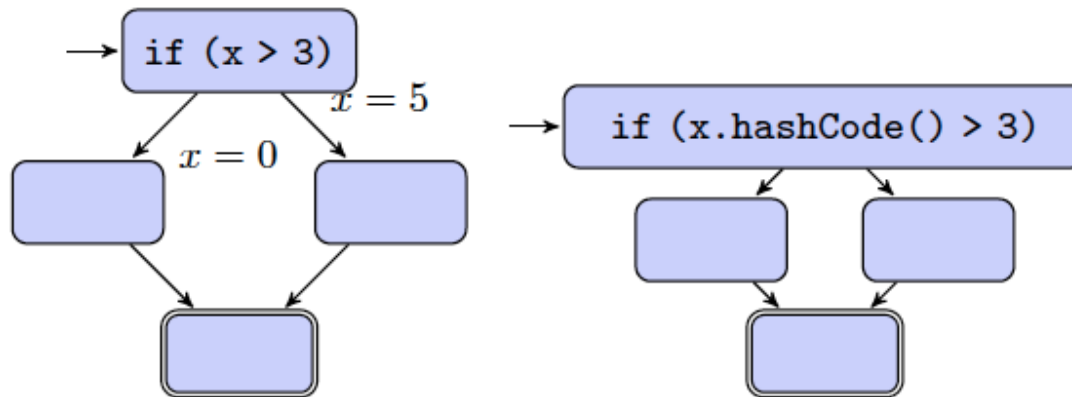
- e.g.,  $path_G[t]$  is the set of test paths corresponding to test case  $t$ .
- Usually just write  $path$ , as  $G$  is obvious from the context
- Lift the definition of path to test set  $T$  by defining  $path(T)$

$$path(T) = \{path(t) | t \in T\}.$$

- Each test case gives at least one test path. If the software is deterministic, then each test case gives exactly one test path; otherwise, multiple test cases may arise from one test path.

# Deterministic and Nondeterministic CFG

Here's an example of deterministic and nondeterministic control-flow graphs:



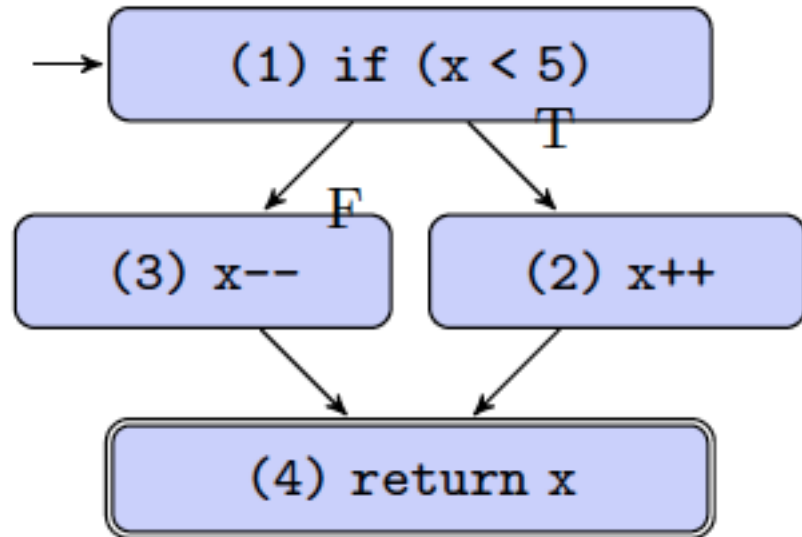
Causes of nondeterminism include dependence on inputs; on the thread scheduler; and on memory addresses, for instance as seen in calls to the default Java `hashCode()` implementation.

Nondeterminism makes it hard to check test case output, since more than one output might be a valid result of a single test input.



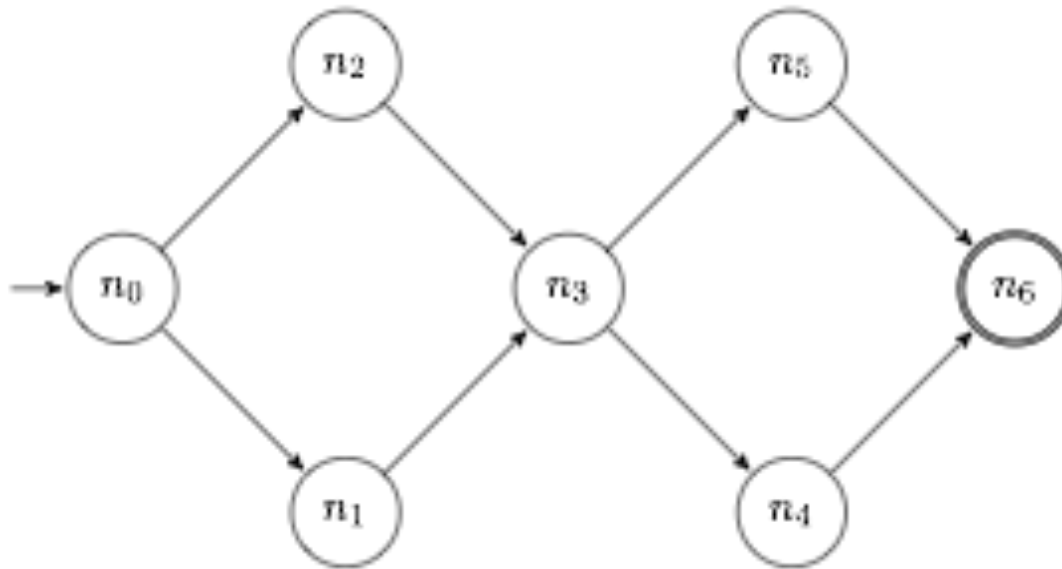
# Connecting Test Cases, Test Paths, and CFG

```
int foo(int x) {  
    if (x < 5) {  
        x ++;  
    } else {  
        x --;  
    }  
    return x;  
}
```



- Test case:  $x = 5$ ; test path: [(1), (3), (4)].
- Test case:  $x = 2$ ; test path: [(1), (2), (4)].

# Node Coverage



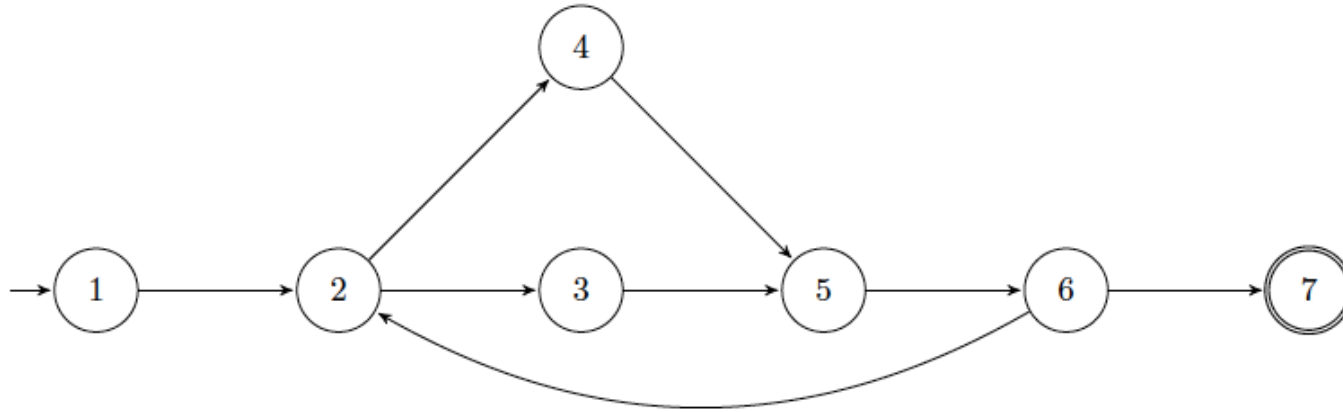
*Node coverage: For each node  $n \in reachG[N_0]$ , TR contains a requirement to visit node  $n$ .*

*Node Coverage [NC]: TR contains each **reachable** node in  $G$ .*

TR = {n0,n1,n2,n3,n4,n5,n6}

a.k.a. statement coverage

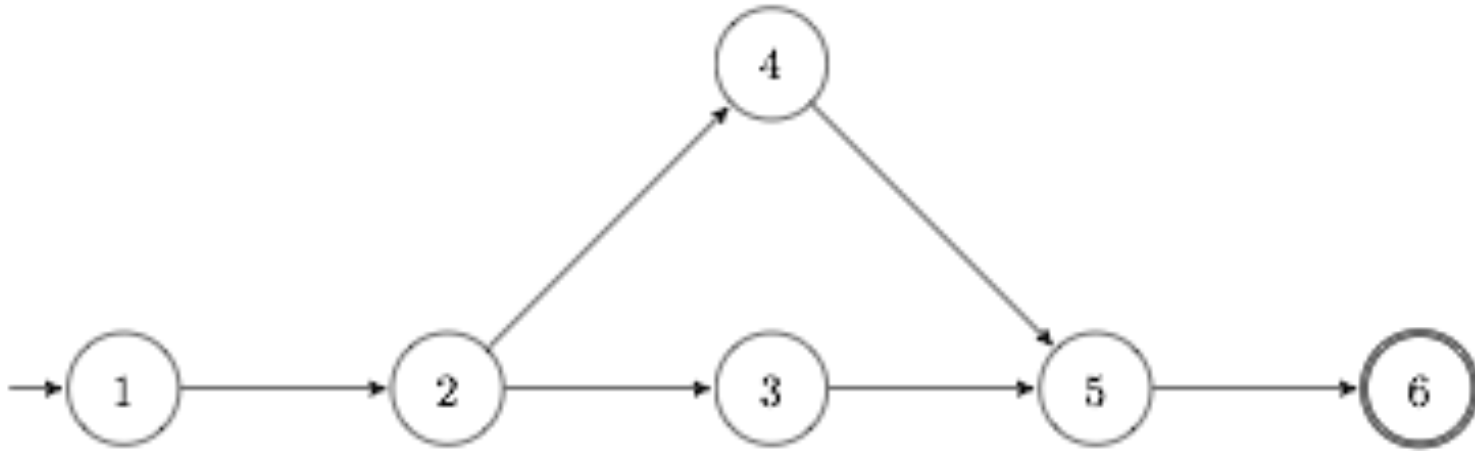
# Edge Coverage (a.k.a. Branch Coverage)



*Edge Coverage [EC]: TR contains each **reachable** path of length up to 1, inclusive, in G.*

$TR = \{[1,2], [2,4], [2,3], [3,5], [4,5], [5,6], [6,7], [6,2]\}$

# Edge Pair Coverage



*Edge-Pair Coverage [EPC]: TR contains each **reachable** path of length up to 2, inclusive, in G.*

$TR = \{[1,2,3], [1,2,4], [2,3,5], [2,4,5], [3,5,6], [4,5,6]\}$

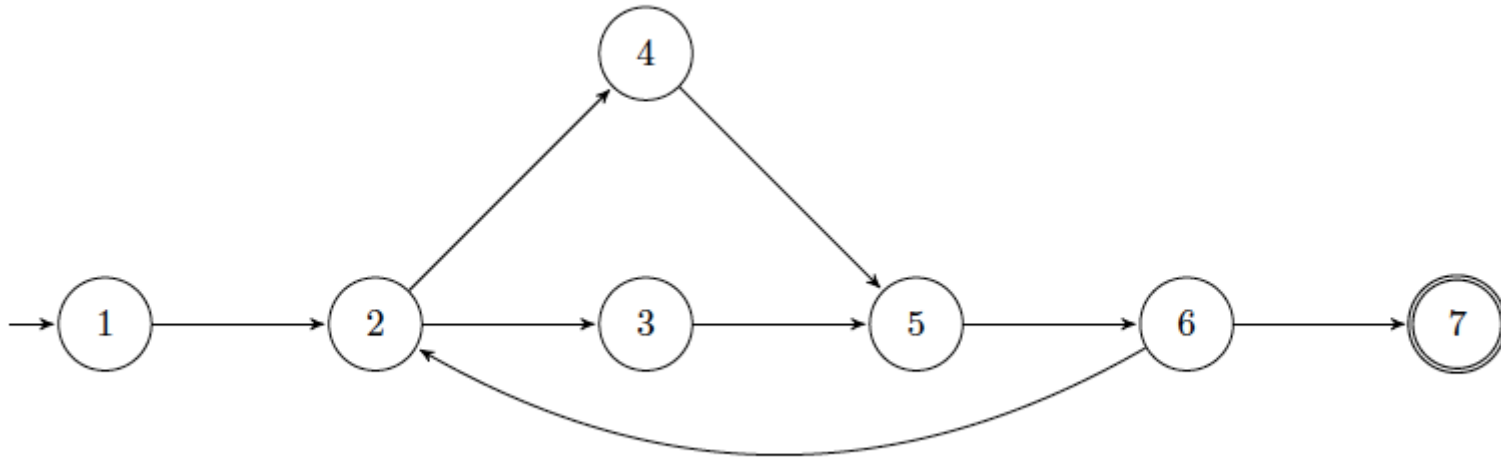
# Simple Path

A path is **simple** if no node appears more than once in the path, except that the first and last nodes may be the same.

Some properties of simple paths:

- no internal loops;
- can bound their length;
- can create any path by composing simple paths; and
- many simple paths exist [too many!]

# Simple Path Examples



Simple path examples:

- [1, 2, 3, 5, 6, 7]
- [1, 2, 4]
- [2,3,5,6,2]

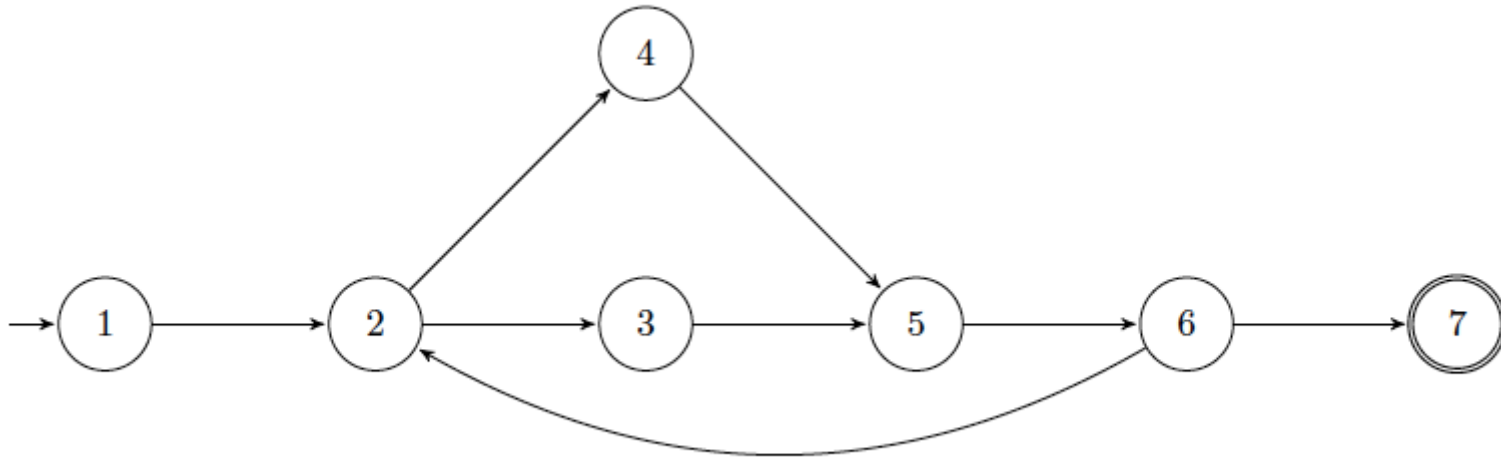
Not simple Path: [1,2,3,5,6,2,4]

# Prime Path

Because there are so many simple paths, let's instead consider **prime paths**, which are simple paths of maximal length.

A path is **prime** if it is simple and does not appear as a proper subpath of any other simple path.

# Prime Path Examples



Prime path examples:

- [1, 2, 3, 5, 6, 7]
- [1, 2, 4, 5, 6, 7]
- [6, 2, 4, 5, 6]

Not a prime path: [3, 5, 6, 7]



# Prime Path Coverage

Prime Path Coverage [PPC]: TR contains each prime path in  $G$ .

There is a problem with using PPC as a coverage criterion: a prime path may be infeasible but contains feasible simple paths.

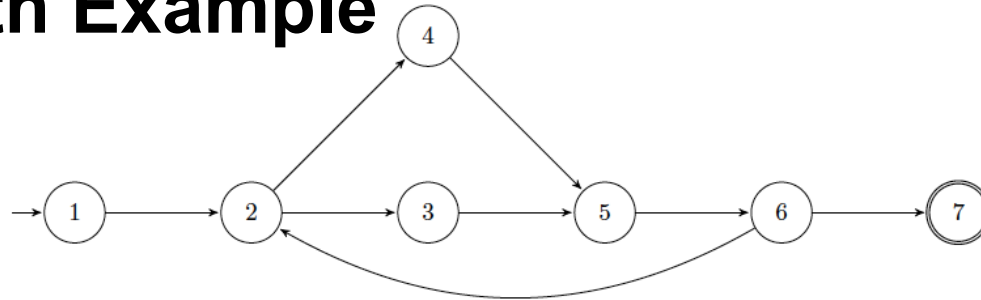
- How to address this issue?

# More Path Coverage Criteria

**Complete Path Coverage [CPC]:** TR contains all paths in  $G$ .

**Specified Path Coverage [SPC]:** TR contains a specified set  $S$  of paths.

# Prime Path Example



Simple paths

Len 0

[1]  
[2]  
[3]  
[4]  
[5]  
[6]  
[7]!

Len 1

[1,2]  
[2,4]  
[2,3]  
[3,5]  
[4,5]  
[5,6]  
[6,7]!  
[6,2]

Len 2

Len 3

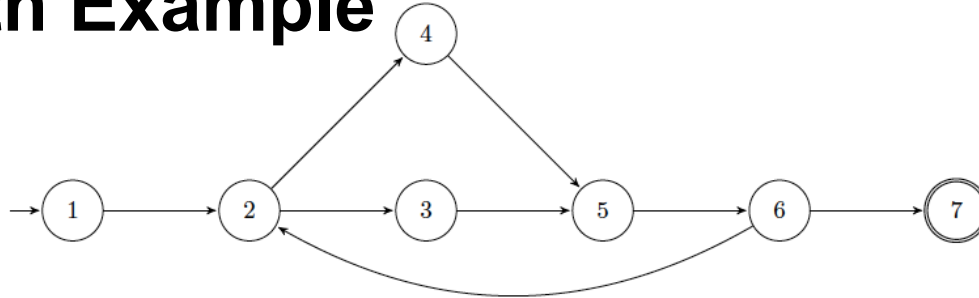
Len 4

Len 5

**53 Simple Paths**  
**12 Prime Paths**

! means path terminates

# Prime Path Example



Simple paths

Len 0

[1]x  
[2]x  
[3]x  
[4]x  
[5]x  
[6]x  
[7]!

Len 1

[1,2]x  
[2,4]x  
[2,3]x  
[3,5]x  
[4,5]x  
[5,6]x  
[6,7]!  
[6,2]x

Len 2

[1,2,4]x  
[1,2,3]x  
[2,4,5]x  
[2,3,5]x  
[3,5,6]x  
[4,5,6]x  
[5,6,7]!  
[5,6,2]x  
[6,2,4]x  
[6,2,3]x

Len 3

[1,2,4,5]x  
[1,2,3,5]x  
[2,4,5,6]x  
[2,3,5,6]x  
[3,5,6,7]!  
[3,5,6,2]x  
[4,5,6,7]!  
[4,5,6,2]x  
[5,6,2,4]x  
[5,6,2,3]x  
[6,2,4,5]x  
[6,2,3,5]x

Len 4

[1,2,4,5,6]x  
[1,2,3,5,6]x  
[2,4,5,6,7]!  
[2,4,5,6,2]\*  
[2,3,5,6,7]!  
[2,3,5,6,2]\*  
[3,5,6,2,4]  
[3,5,6,2,3]\*  
[4,5,6,2,4]\*  
[4,5,6,2,3]  
[5,6,2,4,5]\*  
[5,6,2,3,5]\*  
[6,2,4,5,6]\*  
[6,2,3,5,6]\*

Len 5

[1,2,4,5,6,7]!  
[1,2,3,5,6,7]!

Check paths without a x or \*:

12 Prime Paths

53 Simple Paths

! means path terminates.

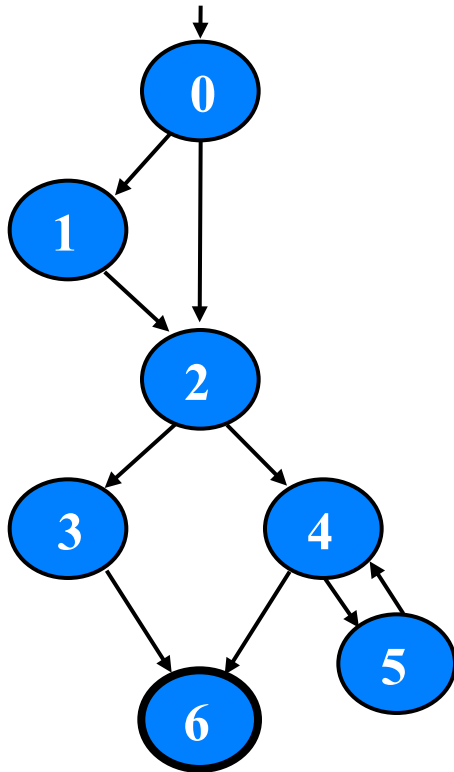
x means not prime paths.

\* denotes path cycles.

# Prime Path Example (2)

This graph has 38 **simple** paths

Only **9** *prime paths*



## Prime Paths

[ 0, 1, 2, 3, 6 ]

[ 0, 1, 2, 4, 5 ]

[ 0, 1, 2, 4, 6 ]

[ 0, 2, 3, 6 ]

[ 0, 2, 4, 5 ]

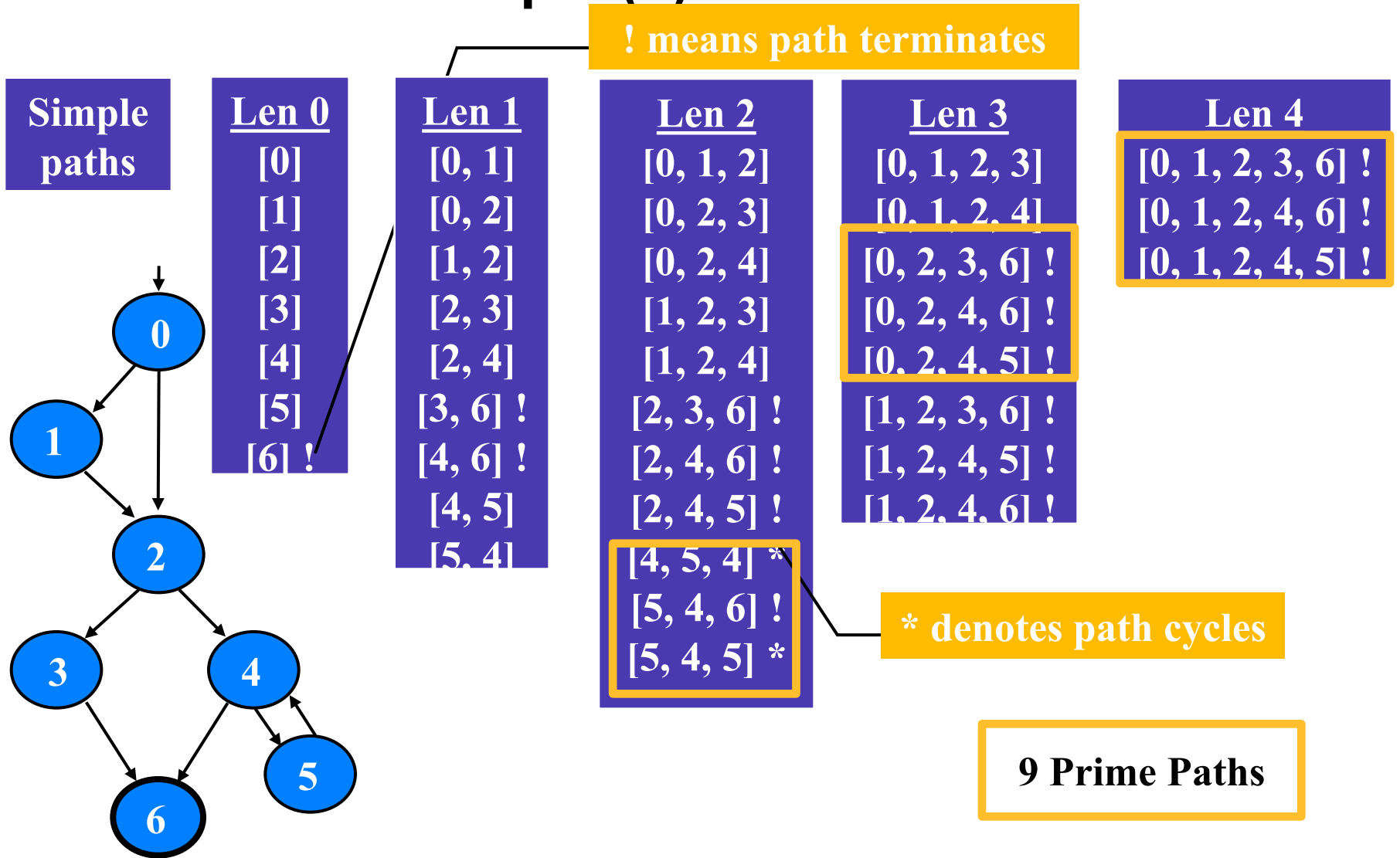
[ 0, 2, 4, 6 ]

[ 5, 4, 6 ]

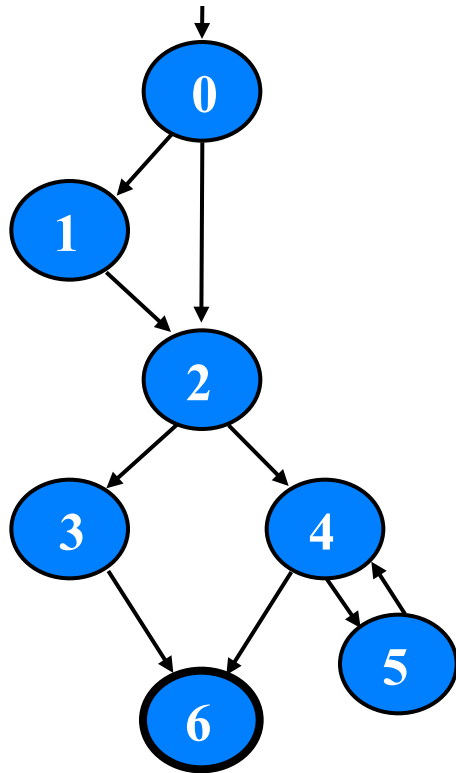
[ 4, 5, 4 ]

[ 5, 4, 5 ]

# Prime Path Example (2)



# Examples of NC, EC, EPC, CPC



## Node Coverage

TR = { 0, 1, 2, 3, 4, 5, 6 }

Test Paths: [ 0, 1, 2, 3, 6 ] [ 0, 1, 2, 4, 5, 4, 6 ]

## Edge Coverage

TR = { [0,1], [0,2], [1,2], [2,3], [2,4], [3,6], [4,5], [4,6], [5,4] }

Test Paths: [ 0, 1, 2, 3, 6 ] [ 0, 2, 4, 5, 4, 6 ]

## Edge-Pair Coverage

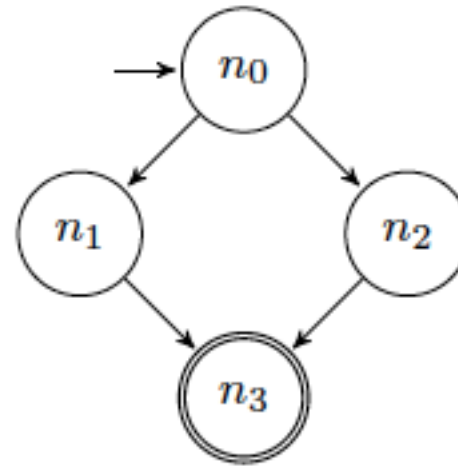
TR = { [0,1,2], [0,2,3], [0,2,4], [1,2,3], [1,2,4], [2,3,6],  
[2,4,5], [2,4,6], [4,5,4], [5,4,5], [5,4,6] }

Test Paths: [ 0, 1, 2, 3, 6 ] [ 0, 2, 3, 6 ] [ 0, 2, 4, 5, 4, 5, 4, 6 ]

## Complete Path Coverage

Test Paths: [ 0, 1, 2, 3, 6 ] [ 0, 1, 2, 4, 6 ] [ 0, 1, 2, 4, 5, 4, 6 ]  
[ 0, 1, 2, 4, 5, 4, 5, 4, 6 ] [ 0, 1, 2, 4, 5, 4, 5, 4, 5, 4, 6 ] ...

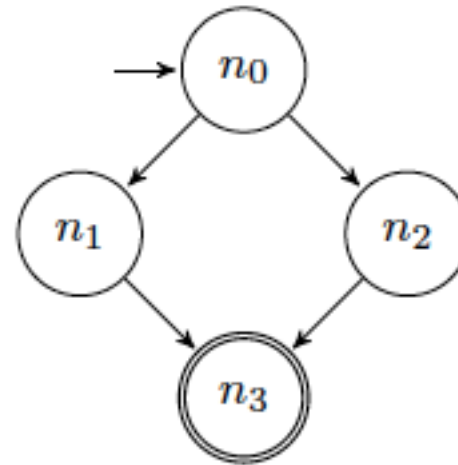
# Prime Path Coverage vs. Complete Path Coverage



- Prime paths:
- $\text{path}(t_1) =$
- $\text{path}(t_2) =$
- $T_1 = \{t_1, t_2\}$  satisfies both PPC and CPC.

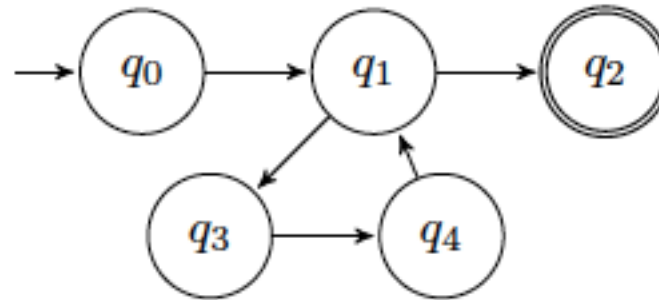


# Prime Path Coverage vs. Complete Path Coverage



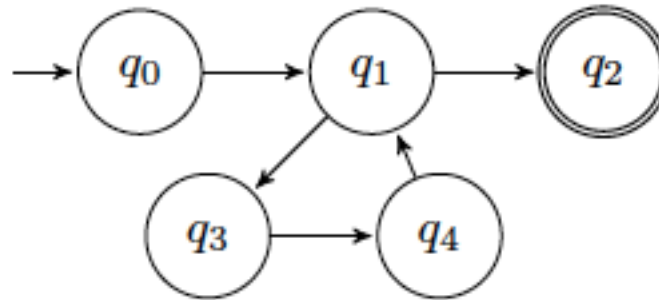
- Prime paths:  $[n_0, n_1, n_3], [n_0, n_2, n_3]$
- $\text{path}(t_1) = [n_0, n_1, n_3]$
- $\text{path}(t_2) = [n_0, n_2, n_3]$
- $T_1 = \{t_1, t_2\}$  satisfies both PPC and CPC.

# Prime Path Coverage vs. Complete Path Coverage (2)



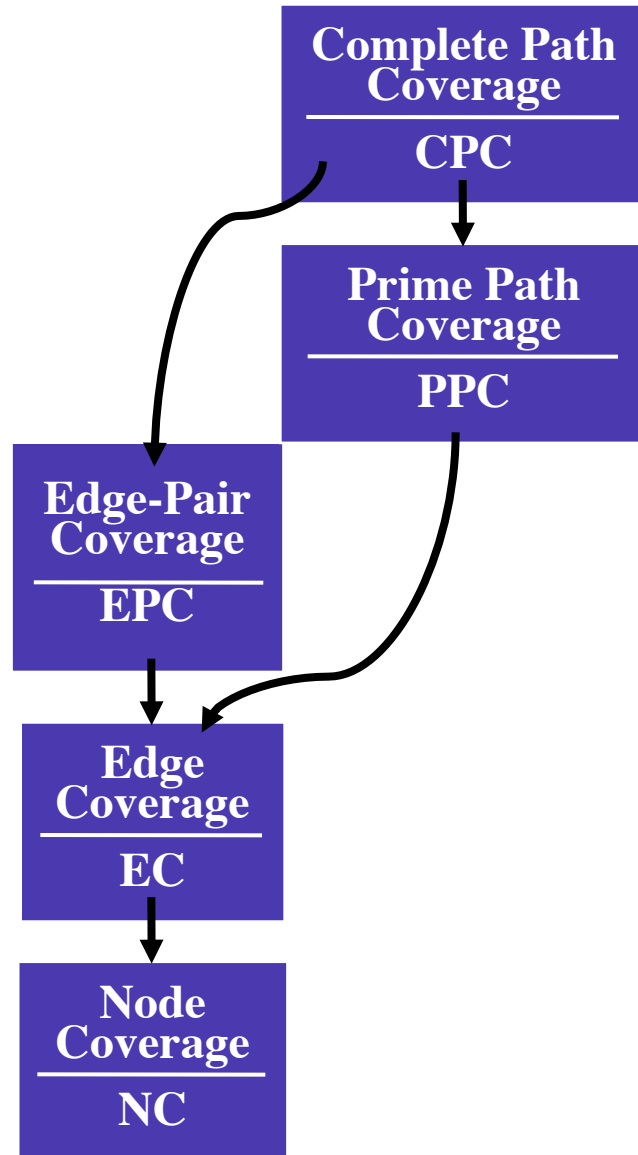
- Prime paths:
- $\text{path}(t_3) =$
- $\text{path}(t_4) =$
- $T_1 = \{t_3, t_4\}$  satisfies PPC but not CPC.

# Prime Path Coverage vs. Complete Path Coverage (2)



- Prime paths:  $[q_0, q_1, q_2]$ ,  $[q_0, q_1, q_3, q_4]$ ,  $[q_3, q_4, q_1, q_2]$ ,  
 $[q_1, q_3, q_4, q_1]$ ,  $[q_3, q_4, q_1, q_3]$ ,  $[q_4, q_1, q_3, q_4]$
- $\text{path}(t_3) = [q_0, q_1, q_2]$
- $\text{path}(t_4) = [q_0, q_1, q_3, q_4, q_1, q_3, q_4, q_1, q_2]$
- $T_1 = \{t_3, t_4\}$  satisfies PPC but not CPC.

# Graph Coverage Criteria Subsumption

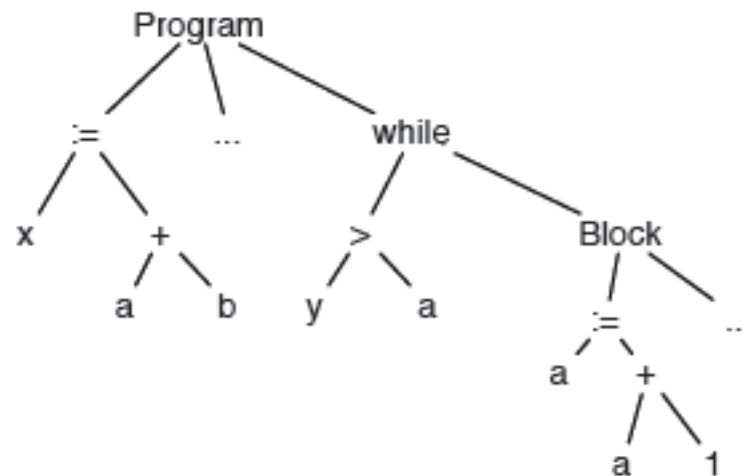


# How do we measure coverage?

*First:*

1. Parse the source code to build an Abstract Syntax Tree (AST)
2. Analyze the AST to build a Control Flow Graph (CFG)
3. Count points of interest
  - (total # of statements, branches, etc.)
4. Instrument the AST using the CFG
  - add tracing statements in the code

```
x := a + b;  
y := a * b;  
while (y > a) {  
    a := a + 1;  
    x := a + b  
}
```



# How do we measure coverage?

*Then:*

1. Transform AST back to instrumented code
2. Recompile and run the test suite on the recompiled code
3. Collect tracing data
  - (line 1 executed, line 3 executed, etc.)
4. Calculate coverage:
  - $\# \text{ traced points} / \text{total } \# \text{ points}$

# Coverage May Affect Test Outcomes

## *Heisenberg effect*

- *the act of observing a system inevitably alters its state.*

Coverage analysis changes the code by adding tracing statements

Instrumentation can change program behaviour

# Enabled In-code Assertions Mess Up Branch Coverage Reporting

**assert P**

Turned into:

```
if assertion-enabled then
    if P then skip()
    else abort()
else skip()
```

Thus 4 branches!

Reported as such

Assertions shouldn't fail

Resulting branch coverage reports:

- Not useful with assertion checking enabled
- Without it, they miss invariants



# Coverage: Useful or Harmful?

Measuring coverage (% of satisfied test obligations) can be a useful indicator ...

- Of progress toward a thorough test suite, of trouble spots requiring more attention

... or a dangerous seduction

- Coverage is only a proxy for thoroughness or adequacy
- It's easy to improve coverage without improving a test suite (much easier than designing good test cases)

The only measure that really matters is **effectiveness**

# EXERCISES

# Exercise 1: Bridge Coverage

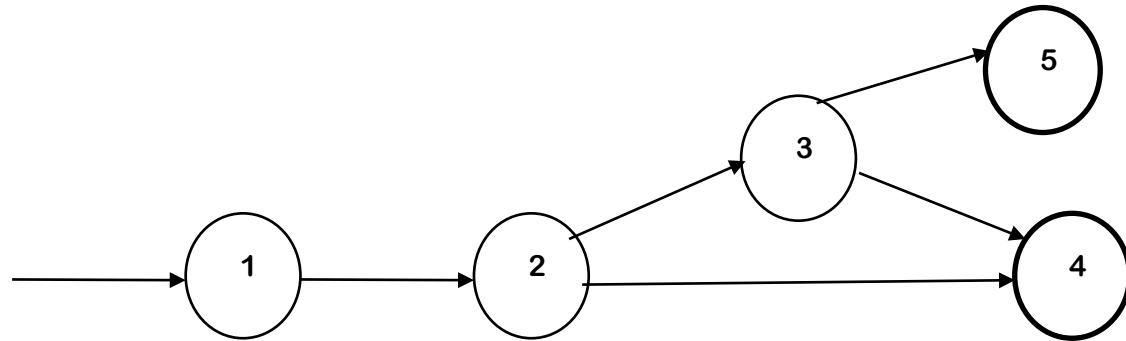
Bridge Coverage (BC): If removing an edge adds unreachable nodes to the graph, then this edge is a bridge. The set of test requirements for BC contains all bridges.

Assume that a graph contains at least two nodes, and all nodes in a graph are reachable from the initial nodes.

- (a) Does BC subsume Node Coverage (NC). If yes, justify your answer. If no, give a counterexample.
- (b) Does NC subsume BC? If yes, justify your answer. If no, give a counterexample

# Bridge Coverage: Part (a)

Bridge Coverage does not subsume Node Coverage.



TRBC = {[1,2], [2,3], [3,5]}

TRNC = {[1, 2, 3,4, 5]}

Test path [1,2,3,5] satisfies BC, but not NC because node 4 is not visited.

# Bridge Coverage: Part (b)

NC subsumes BC

Key points for the proof:

- For any bridge  $[a, b]$ , any test case that visits  $b$  must also visit the edge  $[a, b]$  (can be proved by contradiction).
- Any test set that satisfies NC must visit node  $b$  (TR of NC contains all nodes, including node  $b$ ). Therefore, for any bridge  $[a, b]$ , the test set will visit it. Therefore, NC subsumes BC.

## Exercise 2 (1/2)

Answer questions [a]-[g] for the graph defined by the following sets:

- $N = \{1, 2, 3, 4, 5, 6, 7\}$
- $N_0 = \{1\}$
- $N_f = \{7\}$
- $E = \{(1, 2), (1, 7), (2, 3), (2, 4), (3, 2), (4, 5), (4, 6), (5, 6), (6, 1)\}$

Also consider the following test paths:

- $t_0 = [1, 2, 4, 5, 6, 1, 7]$
- $t_1 = [1, 2, 3, 2, 4, 6, 1, 7]$

## Exercise 2 (2/2)

- [a] Draw the graph.
- [b] List the test requirements for EPC. [Hint: You should get 12 requirements of length 2].
- [c] Does the given set of test paths satisfy EPC? If not, identify what is missing.
- [d] List the test requirements for NC, EC and PPC on the graph.
- [e] List a test path that achieve NC but not EC on the graph.
- [f] List a test path that achieve EC but not PPC on the graph.

## Exercise 2: Partial Solutions (1/2)

[a] Draw the graph.

[b] List the test requirements for EPC. [Hint: You should get 12 requirements of length 2].

- The edge pairs are:  $\{[1, 2, 3], [1, 2, 4], [2, 3, 2], [2, 4, 5], [2, 4, 6], [3, 2, 3], [3, 2, 4], [4, 5, 6], [4, 6, 1], [5, 6, 1], [6, 1, 2], [6, 1, 7]\}$

[c] Does the given set of test paths satisfy EPC? If not, identify what is missing.

- No. Neither  $t_0$  nor  $t_1$  visits the following edge-pairs:  $\{[3, 2, 3], [6, 1, 2]\}$



## Exercise 2: Partial Solutions (2/2)

[d] TR for NC, EC, and PPC.

- $TR_{NC} =$
- $TR_{EC} =$
- $TR_{PPC} = \{[3, 2, 4, 6, 1, 7], [3, 2, 4, 5, 6, 1, 7], [4, 6, 1, 2, 3], [4, 5, 6, 1, 2, 3], [3, 2, 3], [2, 3, 2], [1, 2, 4, 5, 6, 1], [1, 2, 4, 6, 1], [2, 4, 6, 1, 2], [2, 4, 5, 6, 1, 2], [4, 6, 1, 2, 4], [4, 5, 6, 1, 2, 4], [5, 6, 1, 2, 4, 5], [6, 1, 2, 4, 6], [6, 1, 2, 4, 5, 6]\}$

[e] A test path that achieve NC but not EC.

- $[1, 2, 3, 2, 4, 5, 6, 1, 7]$  does not cover edge  $[4, 6]$ .

[f] A test path that achieve EC but not PPC.

- $[1, 2, 3, 2, 4, 5, 6, 1, 2, 4, 6, 1, 7]$  does not cover prime paths such as  $[3,2,3]$ .