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Standard reminder to set phones to silent/vibrate mode, please!



- Today's class:
 - We'll look at one of the issues with linear probing, namely clustering
 - Discuss double hashing:
 - Use one hash function to determine the bin
 - A second hash function determines the jump size for the probing sequence.
 - Look at some practical issues and approaches to deal with these issues.

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- One important problem with linear probing is clustering — as collisions start to occur, then blocks of contiguous occupied bins (clusters) appear.
- And a quite unfortunate aspect is that the longer these clusters, the longer our searches or insertions (or deletions) will take (and remember that we wanted them to be constant time and fast!)

- An even more unfortunate aspect is the fact that the longer these clusters, the more likely it will be that they will grow with each insertion!
 - This is because a new value inserted will make the cluster grow if the hash falls anywhere in the interval [C_S-1, C_E+1], where C_S, C_E are the beginning and the end of the cluster, respectively.
 - Any hash that falls in the cluster will end up taking the position C_F +1, as a result of the linear probing.

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- The bad news: It turns out that if the jump size is fixed, this does not make the slightest difference with respect to our "standard" linear probing (i.e., with jump size p = 1)

- This is a direct consequence of the jump size being fixed.
 - Jump size different from one just makes it a bit more difficult to visualize, but the problem is exactly the same

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- So... What if we could choose a different jump size for each insertion?
- For example, the first insertion uses jump size
 1, second insertion jump size 2, and so on...
 - Would this work, and avoid the issue of clustering?
 - Clearly, not at all how could we do lookups, if the probing sequence depends on the order in which the elements were inserted, which we don't (can't) keep track of!

 However, if the jump size was a function of the value being inserted, things would work, right?

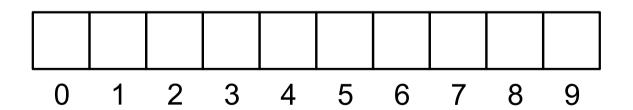
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- A function of the value being inserted ... sounds familiar, doesn't it?
- It would be a bad idea to re-use the same hash function that we used to obtain the bin
 - However, we could use a second (different) hash function

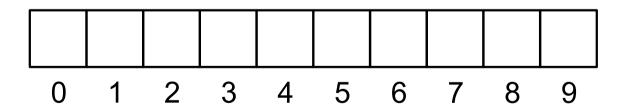
- We recall from two classes ago that we wanted to scramble the bits of the data and then select a subset of those bits (e.g., the m bits from the middle)
- What about taking advantage of the computation already done, and choose a different block of bits for the second hash function?

- Let's look at an example, not with bits, but with something more human-brain-friendly:
 - The hash table uses size 10
 - For the hash function, multiply the value times 117 and keep the right-most digit
 - For the second hash function (jump size), just use the same result, and take the second digit

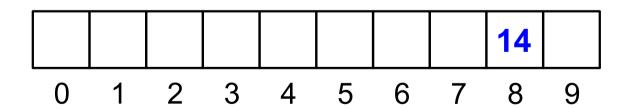
 We'll insert values 14, 29, 43, 19, and 5 into the initially empty hash table:



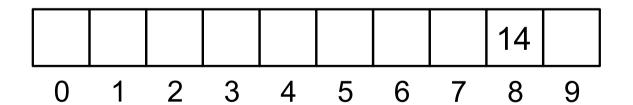
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 - 14×117 = 1638 ⇒ bin 8 (and jump size 3 not relevant now, since this insertion causes no collision)



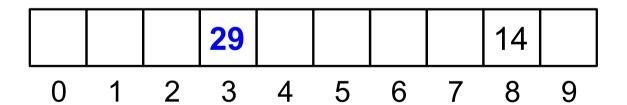
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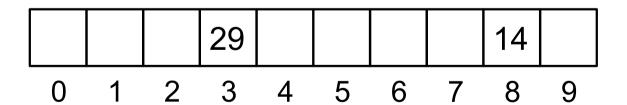
- We'll insert values 14, 29, 43, 19, and 5 into the initially empty hash table:
 - $29 \times 117 = 3393 \Rightarrow bin 3$ (jump size not relevant)



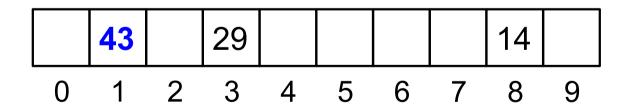
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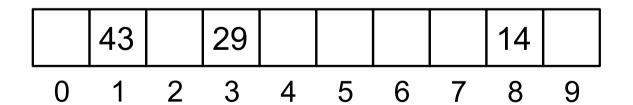
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 - $43 \times 117 = 5031 \Rightarrow bin 1 (jump size not relevant)$



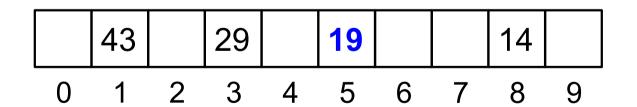
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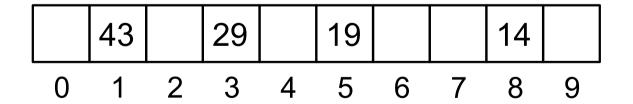
- We'll insert values 14, 29, 43, 19, and 5 into the initially empty hash table:
 - 19×117 = 2223 ⇒ bin 3, causing a collision (jump size given by the second digit, 2)
 - Probe bin 3 + 2 available, so we're done:



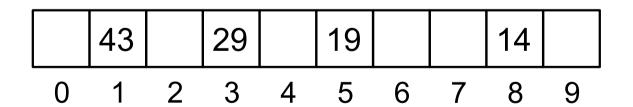
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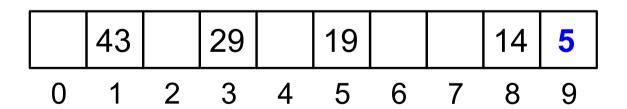
- We'll insert values 14, 29, 43, 19, and 5 into the initially empty hash table:
 - 5×117 = 585 ⇒ bin 5, causing a collision (jump size given by the second digit, 8)
 - Where would this one end up?



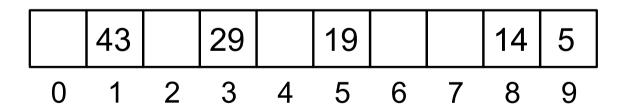
- We'll insert values 14, 29, 43, 19, and 5 into the initially empty hash table:
 - 5×117 = 585 ⇒ bin 5, causing a collision (jump size given by the second digit, 8)
 - 5 + 8 (modulo 10, of course) is 3, which is already taken, so we check 3 + 8, which is 1, also taken, then bin 9!



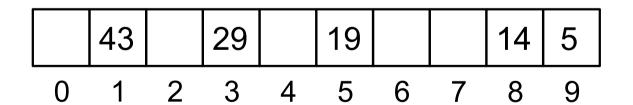
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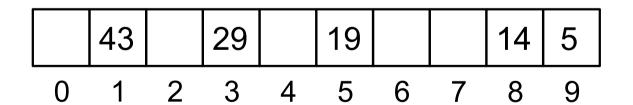
There's a big (read: BIG!) problem with this.
 Let's try inserting 59:



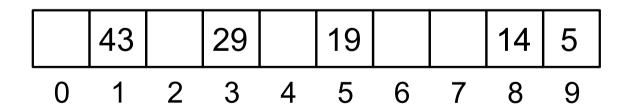
- There's a big (read: BIG!) problem with this.
 Let's try inserting 59:
 - 59×117 = 6903 ⇒ bin 3, causing a collision, so we choose jump size ... Oops!



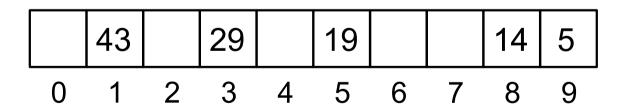
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 Let's try inserting 59:
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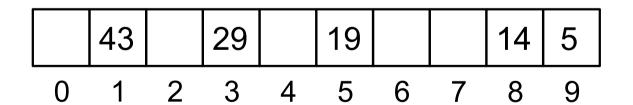
- There's a big (read: BIG!) problem with this.
 Let's try inserting 59:
 - Ok, so we could fix this by not allowing the second hash function to take value 0 (could we do that with just an if? If the value is 0, just make it 1 — why not?)



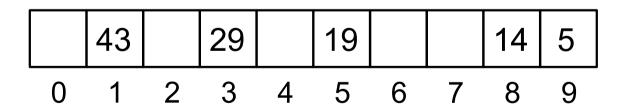
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 - But that's not all let's try inserting 74:
 - 74×117 = 8658 ⇒ bin 8, causing a collision, so we get jump size = 5, so we probe and... oops!



- Why does this happens?
- How do we fix it?



- The problem is that the cycle is given by the least-common-multiple of the two values.
- We'd like it to be the product of the two numbers, but if the numbers are not relatively prime (i.e., share common factors), then the LCM is lower.

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 - This guarantees that every bin will be visited before cycling and start repeating bins.
 - And this is easy if one of the numbers (e.g., the table size) is prime (every number is relatively prime to a prime number, of course!)

- But a prime table size has several problems:
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 - Modulo operations become expensive (can't take advantage of bit shifts and bit and operations)
 - Also, dynamically growing the size gets complicated and expensive (have to find prime numbers for the new size).

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- In addition to all the good things about powers of 2 that we already saw.... Another great thing about powers of two is that their only factor is 2 ...
- So it's easy to find numbers relatively prime to them — any odd number is relatively prime to any power of 2 !!!

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- If b_0 is 1, the number has the form 1 + 2n; otherwise, it has the form 2n.

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 - It's quite straightforward, actually; if we want, say, 8 bits total, we take seven bits from the partial result with the "scrambled" bits, shift them to the second least-significant bit, and set bit 0 to 1.
 - The last step is done with bitwise OR (vertical bar operator in C++):

```
hash = ((result & mask) >> shift) | 1;
```

Next, we'll look at removing elements.

 Can we use the same (efficient) trick as we did with linear probing?

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- How do we determine the sequence of elements to scan, if they're not consecutive?
- How do we check in constant time if a given element is going to be in trouble due to the hole left by the deletion?

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 - Hint: we already saw the approach that we need here!
 - Yes we pretty much have no choice but to mark the deleted bins with a value designated to denote a bin from which an element was removed.
 - Like we mentioned, when searching, this special mark is interpreted as "bin is occupied". But when inserting, the mark is interpreted as "available", and it can be of course overwritten by the value being inserted.

 We may want to keep a counter of how many of these special marks we have, and if it exceeds some threshold, we just reallocate and copy the elements, re-hashing everything.

- We may want to keep a counter of how many of these special marks we have, and if it exceeds some threshold, we just reallocate and copy the elements, re-hashing everything.
 - This (a linear time operation) should not affect the fact that on average, things happen in Θ(1).

We also want to keep track of the load factor, λ
 (the ratio of elements in the table to the size of
 the table), so that we double the size if λ
 exceeds a threshold (typically 2/3 or so)

Summary

- During today's class, we discussed:
 - Clustering with linear probing
 - Double hashing:
 - Use one hash function to determine the bin
 - A second hash function determines the jump size for the probing sequence.
 - How to make the second hash suitable (typically, table size 2^m and jump size always odd)