Priority queues and Heaps



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http://xkcd.com/835/

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Priority queues and Heaps

Standard reminder to set phones to silent/vibrate mode, please!



- During today's lesson:
 - Introduce the notion of priority queues
 - Consider some "obvious" implementations (an array of queues; a balanced binary search tree)
 - Introduce the Heap data structure, which provides a more efficient implementation alternative for priority queues
 - Discuss the various operations on a heap and their run time.

- Priority queues are rather easy to define:
 - As the name suggests, they're queues where the elements have priorities associated to them.
 - We could look at it by analogy with real-life examples of FIFO structures: a line waiting to be served at a bank (or for the cash registers at a store, etc.)
 - It makes sense that they will serve first those who have been waiting the longest.

- Priority queues are rather easy to define:
 - As the name suggests, they're queues where the elements have priorities associated to them.
 - We could look at it by analogy with real-life examples of FIFO structures: a line waiting to be served at a bank (or for the cash registers at a store, etc.)
 - It makes sense that they will serve first those who have been waiting the longest.
 - Except if, for example, a senior or a disabled person arrives in the line — either by policy or by simple courtesy, the common practice is: even if they arrived after, they are served first.

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- In this example, we're all following the scheme of "first-arrive-first-served" — but seniors have higher priority than non-seniors.
 - So, as long as there are seniors in line, they will be served first, no matter how long we've been waiting, and regardless of whether a senior person arrived just two seconds ago.
- Disabled persons presumably have higher priority than seniors — same principle.

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 - Disabled persons have a designated line; seniors have a designated, separate, line; and the rest have a separate line.
 - The serve protocol is: check first the line for disabled persons — if there is someone, serve the first one in line there. If no-one in line, then check the line for seniors; and so on, until checking the line with lowest priority.

- This automatically suggests an obvious implementation strategy:
 - Use an array of queues.
 - Assign a non-negative integer number to represent the priority: 0 represents the highest priority; the larger the number, the lower the priority.
 - Use the priority as the subscript for the array (to get to the corresponding queue)

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 - Limited it is feasible (in a reasonable way) if we have a fixed number of priorities (good enough for many applications, but not good enough — mostly because we *can* do better than that)

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 - Not efficient
 - Can you see why?
 - If we have *m* priorities, then we have an array of *m* queues, and looking for the "next-in-line" takes Θ(*m*)

- We could turn this into a sorting scheme by thinking of the queue as a sorted list, where we sort by two criteria:
 - First, by priority
 - Then, for equal priorities, sort by arrival order
- This is a lexicographical order ... right? (why?)

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 If we keep a counter k and increase it every time we insert an element, then the pair (p,k), where p is the priority, provides the appropriate order:

$$(p_{1,}k_{1}) < (p_{2,}k_{2}) \Leftrightarrow p_{1} < p_{2} \text{ or}$$

$$p_{1} = p_{2} \text{ and } k_{1} < k_{2}$$

- With this, we could simply use a balanced binary search tree (e.g., an AVL tree) using that pair as the value being inserted.
- An AVL tree maintains the elements in order with insertions and removals taking logarithmic time.
- However, the implementation is more complicated than it could be, as we'll see next, when looking into Heaps.

- Heaps are a particular type of binary trees.
- We'll provide a recursive definition:
- A binary tree of height 0 is a heap.
- A non-empty binary tree is a heap if:
 - The root node is less than the values in either of the sub-trees (if present).
 - Both sub-trees are themselves heaps.

- An alternative way to phrase that is:
 - A non-empty binary tree is a heap if for every internal (non-leaf) node, every strict descendant is greater than the node.

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- Important "fine print" in that definition:
 - Sibling elements or in general elements in the two sub-trees have NO RELATIONSHIP WHATSOEVER!!



We know that b < a and that c < a; that says absolutely nothing about *b* as compared to, or related to, *c*.

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• This is an example of a heap:



- This is an example of a heap:
- We have to keep this notion completely apart from the notions of binary search trees. For example:
 - The smallest value (7) and the largest value (89) are both in the left sub-tree.



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• We can obviously find the lowest value in constant time: right? how?

- We can obviously find the lowest value in constant time: right? How?
 - Yes, this one is too obvious to bother writing the answer in the slides :-)

- Removing the lowest element (which is the operation corresponding to "serve the next in line") is rather simple, and presumably efficient:
 - Promote the node at the root of the sub-tree which has the least value.
 - Repeat the same for that sub-tree, all the way down until reaching a leaf node.

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 - As you may have noticed, removal takes O(h), and presumably, h is small (right? why? And again, why presumably?)

- Inserting an element can also be presumably efficient:
 - Create a leaf node with the inserted value, and then adjust.

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Let's look at an example — inserting 17 in the heap below:



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• 17 < 32, so we need to swap them:



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• It is also < 31, so we swap these as well:



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 < 19, so we swap, and we're done, since 17 > 12:



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 Notice that when swapping down a node, we don't need to check anything further for that node — for example, 19 was already less than anything in that sub-tree, so it can not need any further swaps:


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• BTW, this process is called *percolation* — the heavier (higher) elements "percolate" down:



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 - One rather neat way to do this is ensuring that we always have a *complete* binary tree!
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- However we want to do insertions in a way that maintains a balanced tree!
 - One rather neat way to do this is ensuring that we always have a *complete* binary tree!
 - (and BTW, when we say a complete binary tree, this carries a piece of good news with it ... right?)
 - So, we insert a leaf node, and adjust (you recall that with complete trees, you can only insert at the position following a "breadth-first" traversal — or rather, as if we were doing a breadth-first traversal)

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 BTW, the fact that we can get away with ensuring a complete binary tree is one of the advantages over a balanced binary search tree such as an AVL — maintaining a complete binary tree ensures balance with *much* lower overhead than that of a general balanced BST such as AVL trees.

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• Example: let's try inserting 25 into the following heap:



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• Example: let's try inserting 25 into the following heap:



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Since 25 < 36, we have to swap those. Now, 25 < 33, so we need to swap those at the second iteration — then we're done, since 25 > 17



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• And the resulting tree is a complete tree.



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So, as long as we maintain a complete binary tree, we know its height h = Θ(log n), and thus the two important operations (enqueue and dequeue) have a worst-case run time Θ(log n)

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 - Well... except that it gets better!!

Priority queues and Heaps

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- When we insert an element at the bottom (as a leaf node), do we need to do *h* swaps?
 - We certainly need to in the worst-case.... But what about the average case?
 - Would it stop half way on average?
 - That wouldn't be such great news it would still be
 Θ(log n) ... That is, it would be good, but not *that* good.

Priority queues and Heaps

 Given the exponential nature of the number of leaf nodes (there are as many leaf nodes as internal nodes in a perfect tree — so, at depth d+1, there are twice as many nodes at as depth d)

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- So, when a node is swapped to one level up, how does it compare against the rest of the elements at higher depth?

- Given the exponential nature of the number of leaf nodes (there are as many leaf nodes as internal nodes in a perfect tree — so, at depth d+1, there are twice as many nodes at as depth d)
- So, when a node is swapped to one level up, how does it compare against the rest of the elements at higher depth?
 - By definition, there is absolutely no relationship between the data in different branches But

Priority queues and Heaps

 Because of the constraint that sub-trees below one given node have all values greater than the node, we have that, on average, assuming random data, evenly distributed, then the behaviour is that nodes at depth d are less than nodes at depth d+1.

- Because of the constraint that sub-trees below one given node have all values greater than the node, we have that, *on average*, assuming random data, evenly distributed, then the behaviour is that nodes at depth *d* are less than nodes at depth *d*+1.
 - Thus, each time a node goes up one level, it is, on average, past half of the remaining elements!
 - So, after the first swap, on half of the cases it won't require any additional swaps; thus, average number of swaps is 1 !!

- The actual math goes more or less as follows:
 - After k swaps $(0 \le k \le h)$, we are at lower depth than $2^{(h-k)}$ elements, and we're interested in the probability of being above the parent node; this probability is given by the fraction $2^{(h-k)} / n$.

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 - We get the average case by computing the weighted average of the number of swaps (the weights being those probabilities):

Avg. swaps =
$$\sum_{k=0}^{h} k \cdot \frac{2^{(h-k)}}{n} = \frac{2^{h+1}-h-2}{n} = \Theta(1)$$

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- So, this is great news we have the following run times:
 - Insertion: $\Theta(\log n)$ worst-case $\Theta(1)$ average-case
 - Removal: Θ(log *n*) worst-case and average-case
- This is definitely much better than with balanced binary search trees.

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 Food for thought: why did this happen? Why, if we have a binary search tree structure in both cases, and we're in a sense putting data in order, why did we get something so radically faster with binary heaps?

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• I'm actually leaving that one for you guys to think about it

- There's one additional detail, though:
 - When removing (the root element), how do we guarantee that the resulting tree will be a complete binary tree? (in the tree below, we won't end up promoting 88 — which is the only way in which we would end up with a complete binary tree)



- There's one additional detail, though:
 - We'd end up promoting 39 and leaving a hole there (in this case, we could move 88 to that position; but in general, we have no guarantee that we'll be able to ... right? why?).



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 - We'd end up promoting 39 and leaving a hole there (in this case, we could move 88 to that position; but in general, we have no guarantee that we'll be able to ... right? why?). So, any ideas ?



- There are actually two possibilities:
 - Either move the 88 to the hole left by the removal and then adjust (as if we were doing an insertion; percolate it to its corresponding position).
 - Or move the last entry to the root, and then percolate it down.



- Coming back to the issue of ordering by comparing pairs (p, k) priority + order of arrival...
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- Coming back to the issue of ordering by comparing pairs (p, k) priority + order of arrival...
- Let's look at how this works with heaps:
 - Let's say that we insert 7 elements, all with priority
 2. The counter *k* would then go from 0 to 6, and the heap could end up as follows:

- Now removing them:
 - We extract the element at the root:



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• Now removing them:

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• We extract the element at the root: (2,6) goes up, then swapped with (2,1), then (2,3)



- Now removing them:
 - Then we'd go in the following order:


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- One last detail perhaps the "cool upon cool" of all features of this binary heap:
 - Because we always maintain a complete binary tree, then we can implement it as an array !!
 - Leaving the first cell (subscript 0) unused:
 - Children of node k (i.e., value at subscript k of the array) are 2k and 2k+1.
 - Parent of node k is $k \div 2$ (as in, integer division)

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 - Because we always maintain a complete binary tree, then we can implement it as an array !!
 - Leaving the first cell (subscript 0) unused:
 - Children of node k (i.e., value at subscript k of the array) are 2k and 2k+1.
 - Parent of node k is $k \div 2$ (as in, integer division)
 - So here's a radical idea: maybe we will be able to use heaps to sort data! Since it is all in an array, sounds like we're in business...

- Sorting using heaps ...
 - One important obstacle we'd have to clear:
 - Can it be done in-place? Sounds like we'd need to take the data from the array (arbitrary and unconstrained data) and insert the elements into a heap.

- Sorting using heaps ...
 - One important obstacle we'd have to clear:
 - Can it be done in-place? Sounds like we'd need to take the data from the array (arbitrary and unconstrained data) and insert the elements into a heap.
- That will actually be our next topic the truly remarkable *Heap Sort* algorithm!

Summary

• During today's lesson:

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- Introduced the notion of priority queues
- Discussed some "obvious", but not too efficient, implementations (array of queues; balanced binary search tree)
- Looked into the Heap data structure, for a more efficient implementation alternative for priority queues.
 - Discussed operations on a heap and their run time.