

# In a nutshell: Least-squares best-fitting polynomial

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## Least-squares best-fitting linear polynomials

Given  $n + 1$  points  $(x_0, y_0), \dots, (x_n, y_n)$  with at least two different  $x$  values, we can find a least-squares best-fitting linear polynomial that passes as closely as possible to the  $n + 1$  points as follows:

1. Create the Vandermonde matrix  $V = \begin{pmatrix} x_0 & 1 \\ x_1 & 1 \\ x_2 & 1 \\ \vdots & \vdots \\ x_{n-1} & 1 \\ x_n & 1 \end{pmatrix}$  and the vector  $\mathbf{y} = \begin{pmatrix} y_0 \\ y_1 \\ y_2 \\ \vdots \\ y_{n-1} \\ y_n \end{pmatrix}$ .
2. Solve the system  $V^T V \mathbf{a} = V^T \mathbf{y}$ . This can be simplified to solving  $\begin{pmatrix} \sum_{k=0}^n x_k^2 & \sum_{k=0}^n x_k \\ \sum_{k=0}^n x_k & n+1 \end{pmatrix} \begin{pmatrix} a_1 \\ a_0 \end{pmatrix} = \begin{pmatrix} \sum_{k=0}^n x_k y_k \\ \sum_{k=0}^n y_k \end{pmatrix}$ .
3. The first entry is the coefficient of  $x$  and the second is the constant coefficient.

If these  $n + 1$   $x$ -values are equally spaced, we can shift and scale them so that the  $x$ -values line up with the points  $-n, 1 - n, 2 - n, \dots, -2, -1, 0$ , in which case, the system of two linear equations in two unknowns simplifies to:

$$\begin{pmatrix} \frac{n(n+1)(2n+1)}{6} & -\frac{n(n+1)}{2} \\ -\frac{n(n+1)}{2} & n+1 \end{pmatrix} \begin{pmatrix} a_1 \\ a_0 \end{pmatrix} = \begin{pmatrix} -\sum_{k=0}^n k y_k \\ \sum_{k=0}^n y_k \end{pmatrix}$$

## Least-squares best-fitting quadratic polynomials

Assuming there are at least three different  $x$  values, we can find a least-squares best-fitting quadratic polynomial that passes as closely as possible to the  $n + 1$  points as follows:

1. Create the Vandermonde matrix  $V = \begin{pmatrix} x_0^2 & x_0 & 1 \\ x_1^2 & x_1 & 1 \\ x_2^2 & x_2 & 1 \\ \vdots & \vdots & \vdots \\ x_{n-1}^2 & x_{n-1} & 1 \\ x_n^2 & x_n & 1 \end{pmatrix}$  and the vector  $\mathbf{y} = \begin{pmatrix} y_0 \\ y_1 \\ y_2 \\ \vdots \\ y_{n-1} \\ y_n \end{pmatrix}$ .

2. Solve the system  $V^T V \mathbf{a} = V^T \mathbf{y}$ . This can be simplified to solving

$$\begin{pmatrix} \sum_{k=0}^n x_k^4 & \sum_{k=0}^n x_k^3 & \sum_{k=0}^n x_k^2 \\ \sum_{k=0}^n x_k^3 & \sum_{k=0}^n x_k^2 & \sum_{k=0}^n x_k \\ \sum_{k=0}^n x_k^2 & \sum_{k=0}^n x_k & n+1 \end{pmatrix} \begin{pmatrix} a_2 \\ a_1 \\ a_0 \end{pmatrix} = \begin{pmatrix} \sum_{k=0}^n x_k^2 y_k \\ \sum_{k=0}^n x_k y_k \\ \sum_{k=0}^n y_k \end{pmatrix}.$$

3. The first entry is the coefficient of  $x^2$ , the second the coefficient of  $x$ , and the last is the constant coefficient.

If these  $n + 1$   $x$ -values are equally spaced, we can shift and scale them so that the  $x$ -values line up with the points  $-n, 1 - n, 2 - n, \dots, -2, -1, 0$ , in which case, the system of three linear equations in three unknowns simplifies to:

$$\begin{pmatrix} \frac{n(n+1)(2n+1)(3n^2+3n-1)}{30} & -\frac{n^2(n+1)^2}{2} & \frac{n(n+1)(2n+1)}{6} \\ -\frac{n^2(n+1)^2}{2} & \frac{n(n+1)(2n+1)}{6} & -\frac{n(n+1)}{2} \\ \frac{n(n+1)(2n+1)}{6} & -\frac{n(n+1)}{2} & n+1 \end{pmatrix} \begin{pmatrix} a_2 \\ a_1 \\ a_0 \end{pmatrix} = \begin{pmatrix} \sum_{k=0}^n k^2 y_k \\ -\sum_{k=0}^n k y_k \\ \sum_{k=0}^n y_k \end{pmatrix}$$